

SYMBOLIC-NUMERIC FACTORIZATION OF LINEAR DIFFERENTIAL OPERATORS

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I. INTRODUCTION

II. DIFFERENTIAL GALOIS GROUP

III. COMPUTING AN INVARIANT SUBSPACE

IV. VAN DER HOEVEN'S ALGORITHM

V. IMPLEMENTATION

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Object of study. Let $a_i \in \overline{\mathbb{Q}}(z)$.

$$(E) : a_n(z)f^{(n)}(z) + \cdots + a_1(z)f'(z) + a_0(z)f(z) = 0$$

Formalism. f solution of $(E) \Leftrightarrow L \cdot f = 0$ where

$$L = a_n \partial^n + \cdots + a_1 \partial + a_0 \in \overline{\mathbb{Q}}(z) \langle \partial \rangle$$

is a so-called *linear differential operator*.

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Leibniz rule: $(zf)' = zf' + f \quad \rightarrow \quad \partial z = z\partial + 1$

Example. $L = z\partial^2 + (-4z^3 + 5z)\partial + 4z^2 - 5$

and an example of factorization:

$$z\partial^2 + (-4z^3 + 5z)\partial + 4z^2 - 5 = (\partial - 4z^2 + 5)(z\partial - 1)$$

Factoring a linear differential operator

- ▶ **1894**: Beke (right-hand factor of order 1)
- ▶ **1996**: Singer (adaptation of Berlekamp's algorithm)
- ▶ **1997**: van Hoeij (algorithm of the type "local \rightarrow global")
- ▶ **2004**: Cluzeau, van Hoeij (modular algorithm)
- ▶ **2007**: van der Hoeven (symbolic-numeric algorithm)

Improvements of Beke's algorithm

- **1989**: Schwarz
- **1990**: Grigor'ev
- **1994**: Bronstein
- **1996**: Tsarev

Complexity analysis (bounds on coefficients):

- ▶ **1990**: Grigor'ev
- ▶ **2020**: Bostan, Rivoal, Salvy

Let \mathcal{F} denote $\overline{\mathbb{Q}}(z)$ and consider a differential operator $L \in \mathcal{F}\langle \partial \rangle$. Write $L = q(a_n \partial^n + \cdots + a_1 \partial + a_0)$ with $q \in \overline{\mathbb{Q}}(z)$ such that the $a_i \in \overline{\mathbb{Q}}[z]$ are coprime.

Definition. A point $z_0 \in \mathbb{C}$ is an ordinary point of L if $a_n(z_0) \neq 0$. Otherwise, it is a singular point (or a singularity) of L .

Fix an ordinary point z_0 of L .

Proposition. For each $1 \leq i \leq n$, there is a unique power series $h_i = \sum_{j=0}^{+\infty} h_{i,j}(z - z_0)^j$ such that:

- h_i est solution of L in a neighborhood of z_0 ,
- $h_i^{(j)}(z_0) = \delta_{i,j+1}$ for $0 \leq j < n$.

Remark. The basis (h_1, \dots, h_n) gives an canonical identification of the solution space $\text{Sol}(L) := \text{Span}_{\overline{\mathbb{Q}}}(h_1, \dots, h_n)$ with $\overline{\mathbb{Q}}^n$.

approximation \rightarrow guessing \rightarrow post-certification

Factorization of a reducible polynomial $P \in \mathbb{Q}[X]$ [Lenstra, 1984]

- 1: compute an approximation \tilde{x} of a solution $x \in \mathbb{C}$ (Newton's method)
- 2: guess the minimal polynomial $m_x \in \mathbb{Q}[X]$ from \tilde{x} (LLL algorithm)
- 3: check that m_x divides P (Euclidean division)

Factorization of a reducible operator $L \in \mathcal{F}\langle\partial\rangle$ where $\mathcal{F} = \overline{\mathbb{Q}}(z)$

- 1: compute an approximation \tilde{y} of a solution $y \in \overline{\mathbb{Q}}[[z - z_0]]$
(differential equation \leftrightarrow recurrence relation on coefficients)
- 2: guess the minimal operator $m_y \in \overline{\mathbb{Q}}[z]\langle\partial\rangle$ from \tilde{y}
(Hermite-Padé approximants)
- 3: check that m_y divides L in $\overline{\mathbb{Q}}(z)\langle\partial\rangle$ (right-Euclidean division)

approximation \rightarrow guessing \rightarrow post-certification

Factorization of a reducible **polynomial** $P \in \mathbb{Q}[X]$

[Lenstra, 1984]

- 1: compute an approximation \tilde{x} of a solution $x \in \mathbb{C}$ (Newton's method)
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Factorization of a reducible **operator** $L \in \mathcal{F}\langle\partial\rangle$ where $\mathcal{F} = \overline{\mathbb{Q}}(z)$

- 1: compute an approximation \tilde{y} of a solution $y \in \overline{\mathbb{Q}}[[z - z_0]]$
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if y is not
well-chosen
then $m_y = L$



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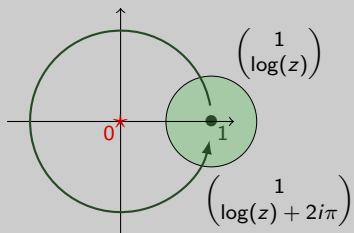
V. IMPLEMENTATION

polynomial $P \in \mathbb{Q}[X]$ operator $L \in \mathcal{F}\langle \partial \rangle$ degree d order n d roots $x_1, \dots, x_d \in \overline{\mathbb{Q}}$
counted with multiplicity n linearly independent
solutions $y_1, \dots, y_n \in \mathbb{Q}[[z - z_0]]$ splitting field $\mathbb{L} = \mathbb{Q}(x_i)$ Picard–Vessiot extension $\mathcal{E} = \mathcal{F}(y_i)$ $\text{Gal}(P) := \text{Aut}(\mathbb{L}/\mathbb{Q})$ $\text{Gal}_{\text{diff}}(L) := \left\{ \begin{array}{l} \sigma \in \text{Aut}(\mathcal{E}/\mathcal{F}) \\ \text{s.t. } \sigma \circ \partial = \partial \circ \sigma \end{array} \right\}$ linear left action of $\text{Gal}_{\text{diff}}(L)$
on $\text{Sol}(L) = \{f \in \mathcal{E} \mid L \cdot f = 0\}$ **Proposition.** There is a one-to-one correspondance:

$$L = L_1 L_2 \quad \longleftrightarrow \quad \begin{array}{l} \text{subspace } V \text{ invariant} \\ \text{under the action of the} \\ \text{differential Galois group} \end{array}$$

$V = \text{Ker}(L_2)$

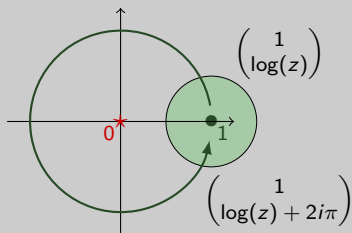
Example: $L = z\partial^2 + \partial$



$$\underbrace{\begin{pmatrix} 1 & 0 \\ 2i\pi & 1 \end{pmatrix}}_{\text{monodromy of } L \text{ around the singularity } 0} \begin{pmatrix} 1 \\ \log(z) \end{pmatrix} = \begin{pmatrix} 1 \\ \log(z) + 2i\pi \end{pmatrix}$$

monodromy of L around the singularity 0

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monodromy of L around the singularity 0

Theorem. [Schlesinger, 1885]

Let $L \in \mathcal{F}\langle \partial \rangle$ be an operator.

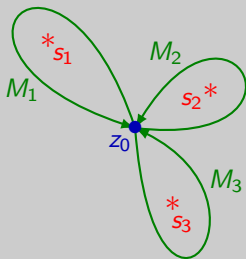
If L is *Fuchsian* then $\text{Gal}_{\text{diff}}(L)$ is the Zariski-closure of the group generated by the monodromy matrices of L (with a fixed base-point).

► How to check the Fuchsianity of L ?
→ Fuchs' Criterion [Fuchs, 1866]

► What if L is not Fuchsian?
→ add exponential matrices and Stokes's matrices
[Ramis, 1985]

If L is Fuchsian:

$L = L_1 L_2 \iff$ subspace V invariant under the action of the the **monodromy matrices**



no non-trivial subspace of $\text{Sol}(L)$ is invariant under the action of the M_i 's

L is irreducible

$L \in \overline{\mathbb{Q}}(z)\langle\partial\rangle$ with singularities s_1, \dots, s_r

monodromy matrices $M_1, \dots, M_r \in \text{Mat}_n(\mathbb{C})$

a non-trivial subspace $V \subset \text{Sol}(L)$ invariant under the action of the M_i 's

$L_2 \in \overline{\mathbb{Q}}(z)\langle\partial\rangle$ a minimal annihilator of a non-zero $f \in V$

$L = L_1 L_2$

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Let $\mathcal{M} = \{M_1, \dots, M_r\} \subset \text{Mat}_n(\mathbb{C})$ be a finite list of matrices.

- $\mathcal{A} := \mathbb{C}[\mathcal{M}]$, the algebra of non-commutative polynomials in the M_i 's
- $\text{Orb}_{\mathcal{M}}(v) := \{Mv; M \in \mathcal{A}\}$, the orbit of v under the action of \mathcal{M}

Algorithm Orbit(\mathcal{M}, v)

INPUT: a list $\mathcal{M} = \{M_1, \dots, M_r\} \subset \text{Mat}_n(\mathbb{C})$ and $v \in \mathbb{C}^n$

OUTPUT: the orbit of v under the action of the M_i 's

Proposition. There is a non-trivial \mathcal{M} -invariant subspace $V \subset \mathbb{C}^n$ iff there is a non-zero vector $v \in \mathbb{C}^n$ such that $\text{Orb}_{\mathcal{M}}(v) \subsetneq \mathbb{C}^n$.

Proposition [van der Hoeven, 2007]. Let (v_1, \dots, v_n) be a basis of \mathbb{C}^n such that the projection maps onto the $\mathbb{C}v_i$'s belong to \mathcal{A} . Then there is a non-trivial \mathcal{M} -invariant subspace $V \subset \mathbb{C}^n$ iff there is an index i such that $\text{Orb}_{\mathcal{M}}(v_i) \subsetneq \mathbb{C}^n$.

Remark. Let $M \in \mathcal{A}$. Denote by $\lambda_1, \dots, \lambda_k$ the eigenvalues, with multiplicities m_1, \dots, m_k , of M . For each j , the projection map onto the generalized eigenspace $E_j := \text{Ker}((M - \lambda_j I_n)^{m_j})$ is polynomial in M (therefore it belongs to \mathcal{A}).

Lemma 1. Assume that there is no non-trivial \mathcal{M} -invariant subspace. Then there is an $M \in \mathcal{A}$ with exactly n eigenvalues.

Lemma 2. Consider $N_1, \dots, N_s \in \text{Mat}_n(\mathbb{C})$ and take a random linear combination $N \in \text{Span}_{\mathbb{C}}(N_1, \dots, N_s)$.

With probability 1, the number of eigenvalues of N is maximal.

Algorithm `Invariant_Subspace(\mathcal{M})`**INPUT:** a list $\mathcal{M} = \{M_1, \dots, M_r\} \subset \text{Mat}_n(\mathbb{C})$ **OUTPUT:** a non-trivial \mathcal{M} -invariant subspace or `None`

- 1: take a random $M \in \mathcal{A} := \mathbb{C}[\mathcal{M}]$
- 2: *for* each 1-dimensional generalized eigenspace E of M *do*
- 3: *if* $\text{Orbit}(\mathcal{M}, E) \neq \mathbb{C}^n$ *then*
- 4: return $\text{Orbit}(\mathcal{M}, E)$
- 5: *if* all the generalized eigenspaces of M are 1-dimensional *then*
- 6: return `None`
- 7: *else*
- 8: take a generalized eigenspace E of M of dimension > 1
- 9: select $v \in E$ such that $\text{Orbit}(\mathcal{M}, v) \neq \mathbb{C}^n$ /* (details hidden) */
- 10: return $\text{Orbit}(\mathcal{M}, v)$

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Implementation of operations $+$, $-$, \times , \div , $\sqrt{\cdot}$, \dots on intervals in such a way that the following invariant is respected.

Motto

The interval contains the exact value.

Example: Let $\pi := [3.1415, 3.1416]$ be an interval representing π . We require that $\sqrt{\pi} \supset \{x \in \mathbb{R} \text{ such that } 3.1415 \leq x^2 \leq 3.1416\}$.

Difficulties

- Overestimation
- Testing nullity

Extensions

- Complex numbers
- Vectors, matrices

INTERVAL VERSION OF THE ALGORITHM FOR COMPUTING AN INVARIANT SUBSPACE

rigorous output

Algorithm `Invariant_Subspace`(\mathcal{M})

INPUT: a list $\mathcal{M} = \{M_1, \dots, M_r\} \subset \text{Mat}_n(\mathbf{C})$

OUTPUT: a non-trivial \mathcal{M} -invariant subspace or `None` or `Fail`

- 1: take a random $M \in \mathcal{A} := \mathbf{C}[\mathcal{M}]$
- 2: *for* each 1-dimensional generalized eigenspace E of M *do* /* can Fail */
- 3: *if* $\text{Orbit}(\mathcal{M}, E) \neq \mathbf{C}^n$ *then*
- 4: return $\text{Orbit}(\mathcal{M}, E)$
- 5: *if* all the generalized eigenspaces of M are 1-dimensional *then*
- 6: return `None`
- 7: *else*
- 8: take a generalized eigenspace E of M of dimension > 1
- 9: select $v \in E$ such that $\text{Orbit}(\mathcal{M}, v) \neq \mathbf{C}^n$ /* can Fail (details hidden) */
- 10: return $\text{Orbit}(\mathcal{M}, v)$

Algorithm `Right_∂Factor(L)`**INPUT:** a Fuchsian operator $L \in \overline{\mathbb{Q}}(z)\langle\partial\rangle$ **OUTPUT:** a non-trivial right factor $\in \overline{\mathbb{Q}}(z)\langle\partial\rangle$ of L or **Irreducible**

- 1: *loop*
- 2: compute $\mathcal{M} = \{\mathbf{M}_1, \dots, \mathbf{M}_r\}$ the monodromy matrices by approximations with rigorous error bounds
- 3: $\mathbf{V} = \text{Invariant_Subspace}(\mathcal{M})$
- 4: *if* \mathbf{V} is **Fail** *then*
- 5: increase precision
- 6: *else-if* \mathbf{V} is **None** *then*
- 7: return **Irreducible**
- 8: *else*
- 9: guess a candidate operator L_2 from \mathbf{V}
- 10: *if* L_2 divides L *then*
- 11: return L_2
- 12: *else*
- 13: increase precision and order of truncation

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In SageMath system, source available at

https://github.com/a-goyer/diffop_factorization.

Main functions

- `InvSub` (interval version, with rigorous `None`)
- `right_dfactor`, `dfactor`
- and the structure `ComplexOptimisticField`

The code takes advantage of:

- `ore_algebra` package, in particular the subpackage `analytic` for arbitrary-precision monodromy computation (https://github.com/mkauers/ore_algebra)
- Arb library (<https://arblib.org/>)
- some Sage functions (the method `.minimal_approximant_basis` of polynomial matrices for Hermite–Padé approximation, ...)

COMPARISON OF RUNNING TIMES

operator	order	DEtools (*)	diffop_factorization
fcc3 (**)	3	0.182s	0.148s
fcc4 (**)	4	0.630s	1.32s
fcc5 (**)	6	61.9s	12.9s
fcc6 (**)	8	>10h	432s
lclm(fcc3, fcc4)	7	66.6s	98.0s
fcc4 × fcc3	7	1.88s	31.5s
fcc3 × fcc4	7	4.59s	24.8s
fcc4 ²	8	122.s	108.s
random4 × fcc3	7	2.04s	169.s
random4 × random3	7	2.40s	404.s
$(z^2\partial + 3)((z - 3)\partial + 4z^5)$	2	>10h	1.96s

(*) command DFactor of the Maple package DEtools (author: van Hoeij)

(**) <http://koutschan.de/data/fcc1/> (probabilistic walks)

Thank you for listening!

Summary

- an implementation of van der Hoeven's algorithm for factorization of operators is now available! 😊
- confirmation that symbolic-numeric approach can compete with purely symbolic approach!
- detailed proofs of correction of the irreducible case

Remaining work and outlook

- study the theoretical complexity
- non-Fuchsian case
- algebraic/exponential/liouvillian solutions