# Refined enumeration of planar Eulerian orientations 

Andrew Elvey Price<br>Joint work with Mireille Bousquet-Mélou

CNRS, Université de Tours, France
10/06/2024

## PLANAR MAPS



## PLANAR MAPS



## Rooted planar maps



SmALL PLANAR MAPS





## A CHRONOLOGY OF PLANAR MAPS

## Random maps

## Bijections (enumeration)

## Matrix integrals (enumeration)

|  | Recursive approach (enumeration) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| 1960 | 1978 | 1981 | 1995 | 2000 |

- Recursive approach: Tutte, Brown, Bender, Canfield, Richmond, Goulden, Jackson, Wormald, Walsh, Lehman, Gao, Wanless, Bonzom...
- Matrix integrals: Brézin, Itzykson, Parisi, Zuber, Bessis, Ginsparg, Kostov, Zinn-Justin, Boulatov, Kazakov, Mehta, Bouttier, Di Francesco, Guitter, Eynard...
- Bijections: Cori \& Vauquelin, Schaeffer, Bouttier, Di Francesco \& Guitter (BDG), Bernardi, Fusy, Poulalhon, Bousquet-Mélou, Chapuy...
- Geometric properties of random maps: Chassaing \& Schaeffer, BDG, Marckert \& Mokkadem, Jean-François Le Gall, Miermont, Curien, Albenque, Bettinelli, Ménard, Angel, Sheffield, Miller, Gwynne, Holden, Budzinski, Louf, Carrance


## MAPS EQUIPPED WITH AN ADDITIONAL STRUCTURE

How many maps equipped with...

- a spanning tree [Mullin 67, Bernardi]
- a spanning forest? [Bouttier et al., Sportiello et al., Bousquet-Mélou \& Courtiel]
- a self-avoiding walk? [Duplantier \& Kostov; Gwynne \& Miller]
- a proper $q$-colouring? [Tutte 74-83, Bouttier et al.]
- a bipolar orientation? [Kenyon, Miller, Sheffield, Wilson, Fusy, Bousquet-Mélou...]


## MAPS EQUIPPED WITH AN ADDITIONAL STRUCTURE

How many maps equipped with...

- a spanning tree [Mullin 67, Bernardi]
- a spanning forest? [Bouttier et al., Sportiello et al., Bousquet-Mélou \& Courtiel]
- a self-avoiding walk? [Duplantier \& Kostov; Gwynne \& Miller]
- a proper $q$-colouring? [Tutte 74-83, Bouttier et al.]
- a bipolar orientation? [Kenyon, Miller, Sheffield, Wilson, Fusy, Bousquet-Mélou...]


## Additional structures in this talk:

- Maps equipped with an height function (H-maps)
- Maps equipped with an Eulerian orientation (EO-maps)
- Quadrangulations equipped with a height function (H-quads)
- Quartic maps equipped with an Eulerian orientation (EO-quarts)


## BACKGROUND

- 2000: EO-quarts problem non-rigorously "solved" with weight $\omega$ [Kostov]
- 2013: Bijective link between H-quads and H-maps [Ambjørn and Budd]
- 2017: EO-maps enumeration problem posed [Bousquet-Mélou, Bonichon, Dorbec, Pennarun]
- 2018: Bijective link H-maps to EO-maps and H-quads to EO-quarts [E.P., Guttmann], conjectured Asymptotics
- 2020: Exact solution for $\omega=0,1$ [E.P., Bousquet-Mélou] (using guess and check of functional equations)
- 2023: Exact solution for all $\omega$ [E.P., Zinn-Justin] (using complex analysis, following Kostov)


## BACKGROUND

- 2000: EO-quarts problem non-rigorously "solved" with weight $\omega$ [Kostov]
- 2013: Bijective link between H-quads and H-maps [Ambjørn and Budd]
- 2017: EO-maps enumeration problem posed [Bousquet-Mélou, Bonichon, Dorbec, Pennarun]
- 2018: Bijective link H-maps to EO-maps and H-quads to EO-quarts [E.P., Guttmann], conjectured Asymptotics
- 2020: Exact solution for $\omega=0,1$ [E.P., Bousquet-Mélou] (using guess and check of functional equations)
- 2023: Exact solution for all $\omega$ [E.P., Zinn-Justin] (using complex analysis, following Kostov)


## This work:

- Exact solution for all $\omega$ (using algebraic methods)
- Exact solution for $\omega=0,1$ with new weight $v$
- Functional equations for all $\omega, v$.


## THE MODEL (H-QUADS)

## Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1



## THE MODEL (H-QUADS)

Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1

Aim: determine the generating function $\mathrm{Q}(t)=4 t+35 t^{2}+\ldots$ that counts height-labelled quadrangulations by faces.


## EXACT SOLUTION [E.P., Bousquet-Mélou, 2020]

Let $\mathrm{R}(t) \in t \mathbb{Z}[[t]]$ be the unique series satisfying

$$
t=\sum_{n=0}^{\infty} \frac{1}{n+1}\binom{2 n}{n}\binom{3 n}{n} \mathrm{R}(t)^{n+1}
$$

Theorem: The generating function of height-labelled quadrangulations is given by

$$
\mathrm{Q}(t):=q_{0}+q_{1} t+q_{2} t^{2}+\cdots=\frac{1}{3 t^{2}}\left(t-3 t^{2}-\mathrm{R}(t)\right) .
$$

Asymptotically,

$$
q_{n} \sim \kappa \frac{\mu^{n+2}}{n^{2}(\log n)^{2}},
$$

where $\kappa=1 / 18$ and $\mu=4 \sqrt{3} \pi$.

## THE WEIGHTED MODEL

## Recall: Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1


## Weights:

- A weight $v$ per local minimum
- A weight $\omega$ per alternating face



## THE WEIGHTED MODEL

## Recall: Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1


## Weights:

- A weight $v$ per local minimum
- A weight $\omega$ per alternating face



## THE WEIGHTED MODEL

## Recall: Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1


## Weights:

- A weight $v$ per local minimum
- A weight $\omega$ per alternating face


Alternating (weight $\omega$ )

## THE WEIGHTED MODEL

## Recall: Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1


## Weights:

- A weight $v$ per local minimum
- A weight $\omega$ per alternating face



## THE WEIGHTED MODEL

## Recall: Height-labelled quadrangulations:

- Each face has degree 4
- Adjacent labels differ by 1
- Root edge labelled from 0 to 1


## Weights:

- A weight $v$ per local minimum
- A weight $\omega$ per alternating face

Aim: determine the refined generating function

$$
\mathrm{Q}(t, \omega, v)=\left(2 v+\omega v+\omega v^{2}\right) t+\cdots
$$



## TALK OUTLINE

- Part 1: Combinatorics $\rightarrow$ Functional equations for $\mathrm{Q}(t, \omega, v)$
- Part 2: Solution for $\mathrm{Q}(t, 0, v)$ and $\mathrm{Q}(t, 1, v)$
- Part 3: Complex analytic version of functional equations, solution to $\mathrm{Q}(t, \omega, 1)$
- Bonus (if time permits): Bijections to Eulerian orientations and six vertex model


## Part 1: Combinatorics $\rightarrow$ Functional equations

## FUNCTIONAL EQUATIONS PREVIEW

Theorem: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, \nu][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]], \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

The series $\mathbf{Q}(t, \omega, v)$ is given by

$$
\mathrm{Q}(t, \omega, v)=t^{-2}\left[y^{-2}\right] \mathcal{M}(y)-v .
$$

## Functional equations preview

Theorem: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, \nu][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Meaning of $\mathcal{M}(\mathcal{M}(x))$ :
Writing $\mathcal{M}(x)=\sum_{n=1}^{\infty} \sum_{j=-n}^{\infty} m_{n, j}(\omega, v) x^{j} t^{n}$, we have

$$
\mathcal{M}(x)^{j} t^{n} \in x^{n}(t / x)^{j+n} \mathbb{Z}(\omega, v)[[x, t / x]]
$$

so

$$
\mathcal{M}(\mathcal{M}(x)):=\sum_{n=1}^{\infty} \sum_{j=-n}^{\infty} m_{n, j}(\omega, v) \mathcal{M}(x)^{j} t^{n} \in \mathbb{Z}(\omega, v)[[x, t / x]]
$$

is well defined.

## COUNTING HEIGHT-LABELLED QUADRANGULATIONS

Characterisation 1: There are series $\mathbf{P}(y) \in \mathbb{Z}[[y, \omega, v, t]]$ and $\mathrm{D}(x, y), \mathrm{E}(x, y) \in \mathbb{Z}[[x, y, \omega, v, t]]$, uniquely defined by:

$$
\begin{aligned}
\mathrm{D}(x, y) & =v+\frac{y}{v} \mathrm{D}(x, y)\left[z^{1}\right] \mathrm{D}(x, z)+y\left[x^{\geq 0}\right]\left(\frac{1}{x} \mathrm{D}(x, y) \mathrm{P}\left(\frac{t}{x}\right)\right), \\
(1-x)(\mathrm{D}(x, y)-v) & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) . \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right)
\end{aligned}
$$

The generating function $\mathrm{Q}(t, \omega, v)$ is given by

$$
\mathbf{Q}=\left[y^{1}\right] \mathbf{P}(y)-v .
$$

## COUNTING HEIGHT-LABELLED QUADRANGULATIONS

Characterisation 1: There are series $\mathbf{P}(y) \in \mathbb{Z}[[y, \omega, v, t]]$ and $\mathrm{D}(x, y), \mathrm{E}(x, y) \in \mathbb{Z}[[x, y, \omega, v, t]]$, uniquely defined by:

$$
\begin{aligned}
\mathrm{D}(x, y) & =v+\frac{y}{v} \mathrm{D}(x, y)\left[z^{1}\right] \mathrm{D}(x, z)+y\left[x^{\geq 0}\right]\left(\frac{1}{x} \mathrm{D}(x, y) \mathrm{P}\left(\frac{t}{x}\right)\right), \\
(1-x)(\mathrm{D}(x, y)-v) & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) . \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right)
\end{aligned}
$$

The generating function $\mathrm{Q}(t, \omega, v)$ is given by

$$
\mathrm{Q}=\left[y^{1}\right] \mathrm{P}(y)-v .
$$

I will show one element of the proof.

## COUNTING HEIGHT-LABELLED QUADRANGULATIONS

Characterisation 1: There are series $\mathbf{P}(y) \in \mathbb{Z}[[y, \omega, v, t]]$ and $\mathrm{D}(x, y), \mathrm{E}(x, y) \in \mathbb{Z}[[x, y, \omega, v, t]]$, uniquely defined by:

$$
\begin{aligned}
\mathrm{D}(x, y) & =v+\frac{y}{v} \mathrm{D}(x, y)\left[z^{1}\right] \mathrm{D}(x, z)+y\left[x^{\geq 0}\right]\left(\frac{1}{x} \mathrm{D}(x, y) \mathrm{P}\left(\frac{t}{x}\right)\right), \\
(1-x)(\mathrm{D}(x, y)-v) & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) . \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right)
\end{aligned}
$$

The generating function $\mathrm{Q}(t, \omega, v)$ is given by

$$
\mathrm{Q}=\left[y^{1}\right] \mathrm{P}(y)-v .
$$

I will show one element of the proof.

## D-PATCHES

$D$-patch: Digons are allowed next to the root vertex and the outer face may have any degree.


Restrictions:

- outer labels must be 0 or 1 .
- vertices adjacent to the root must be labelled 1 .

In $\mathrm{D}(x, y)$ :

- $x$ counts digons.
- $y$ counts the degree of the outer face (halved)
- $t, \omega, v$ same as before.


## DECOMPOSITION OF D-PATCHES

Colour the vertex two places clockwise from the root vertex around the outer face.


Restrictions:

- outer labels must be 0 or 1 .
- vertices adjacent to the root must be labelled 1 .

In $\mathrm{D}(x, y)$ :

- $x$ counts digons.
- $y$ counts the degree of the outer face (halved)
- $t, \omega, v$ same as before.


## DECOMPOSITION OF D-PATCHES

Highlight the maximal connected subgraph of nonpositive labels, containing the coloured vertex.


Restrictions:

- outer labels must be 0 or 1 .
- vertices adjacent to the root must be labelled 1 .

In $\mathrm{D}(x, y)$ :

- $x$ counts digons.
- $y$ counts the degree of the outer face (halved)
- $t, \omega, v$ same as before.


## DECOMPOSITION OF D-PATCHES

Add to the subgraph all vertices and edges contained in its inner face(s).


Restrictions:

- outer labels must be 0 or 1 .
- vertices adjacent to the root must be labelled 1 .

In $\mathrm{D}(x, y)$ :

- $x$ counts digons.
- $y$ counts the degree of the outer face (halved)
- $t, \omega, v$ same as before.


## Decomposition of D-patches

Record the subgraph with inverted labels.


## Decomposition of D-patches

Contract the highlighted map to a single vertex (labelled 0 ).


## Decomposition of D-PATCHES

Contract the highlighted map to a single vertex (labelled 0).


## Decomposition of D-PATCHES

Contract the highlighted map to a single vertex (labelled 0).


## Decomposition of D-PATCHES

Contract the highlighted map to a single vertex (labelled 0 ).


## Decomposition of D-PATCHES

Contract the highlighted map to a single vertex (labelled 0 ). The new vertex may be adjacent to digons.


## Decomposition of D-patches

Merge the new vertex with the root vertex.


## Decomposition of D-patches

Merge the new vertex with the root vertex.


## Decomposition of D-patches

Merge the new vertex with the root vertex.


## Decomposition of D-patches

Merge the new vertex with the root vertex.


## Decomposition of D-patches

Merge the new vertex with the root vertex.


## Decomposition of D-PATCHES

Merge the new vertex with the root vertex.


## Decomposition of D-patches

Merge the new vertex with the root vertex. This new map is a D-patch!


## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{aligned}
\mathrm{D}(x, y) & =v+\frac{y}{v} \mathrm{D}(x, y)\left[z^{1}\right] \mathrm{D}(x, z)+y\left[x^{\geq 0}\right]\left(\frac{1}{x} \mathrm{D}(x, y) \mathrm{P}\left(\frac{t}{x}\right)\right) \\
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right)
\end{aligned}
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{aligned}
\mathrm{D}\left(\frac{t}{x}, y\right) & =v+\frac{y}{v} \mathrm{D}\left(\frac{t}{x}, y\right)\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right)+y\left[x^{\leq 0}\right]\left(\frac{x}{t} \mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right) \\
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right)
\end{aligned}
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{aligned}
\frac{t}{x} \mathrm{D}\left(\frac{t}{x}, y\right) & =\frac{t v}{x}+\frac{t y}{v x} \mathrm{D}\left(\frac{t}{x}, y\right)\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right)+y\left[x^{<0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right) \\
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right)
\end{aligned}
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{aligned}
\frac{t}{x} \mathrm{D}\left(\frac{t}{x}, y\right) & =\frac{t v}{x}+\frac{t y}{v x} \mathrm{D}\left(\frac{t}{x}, y\right)\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right)+y\left[x^{<0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right) \\
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\mathrm{E}(x, y)=\mathrm{E}(y, x) & =\frac{1}{v}\left[x^{\geq 0}\right]\left(\mathrm{D}\left(\frac{t}{x}, y\right) \mathrm{P}(x)\right) \\
\frac{t}{x y} \mathrm{D}\left(\frac{t}{x}, y\right)+v \mathrm{E}(x, y) & =\frac{t v}{x y}+\left(\mathrm{D}\left(\frac{t}{x}, y\right)\left(\frac{t}{x v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right)+\mathrm{P}(x)\right)\right)
\end{aligned}
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{aligned}
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\frac{t}{x y} \mathrm{D}\left(\frac{t}{x}, y\right)+v \mathrm{E}(x, y) & =\frac{t v}{x y}+\left(\mathrm{D}\left(\frac{t}{x}, y\right)\left(\frac{t}{x v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right)+\mathrm{P}(x)\right)\right)
\end{aligned}
$$

## Simplifying EQUATIONS

Equations:

$$
\begin{aligned}
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\frac{t}{x y} \mathrm{D}\left(\frac{t}{x}, y\right)+v \mathrm{E}(x, y) & =\frac{t v}{x y}+\left(\mathrm{D}\left(\frac{t}{x}, y\right)\left(\frac{t}{x v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right)+\mathrm{P}(x)\right)\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

that is

$$
\mathcal{M}\left(\frac{t}{x}\right)=x \mathrm{P}(x)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right) .
$$

## Simplifying EQUATIONS

Equations:

$$
\begin{aligned}
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(y \mathrm{P}(y)+y-v y+\omega \frac{t}{y}+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{y}, z\right)\right) \\
\frac{t}{x y} \mathrm{D}\left(\frac{t}{x}, y\right)+v \mathrm{E}(x, y) & =\frac{t v}{x y}+\mathrm{D}\left(\frac{t}{x}, y\right) \frac{1}{x} \mathcal{M}\left(\frac{t}{x}\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, v]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

that is

$$
\mathcal{M}\left(\frac{t}{x}\right)=x \mathrm{P}(x)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right) .
$$

## Simplifying EQUATIONS

## Equations:

$$
\begin{aligned}
{\left[y^{>0}\right](1-x) \mathrm{D}(x, y) } & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(\mathcal{M}\left(\frac{t}{y}\right)+y-v y+\omega \frac{t}{y}\right) \\
\frac{t}{x y} \mathrm{D}\left(\frac{t}{x}, y\right)+v \mathrm{E}(x, y) & =\frac{t v}{x y}+\mathrm{D}\left(\frac{t}{x}, y\right) \frac{1}{x} \mathcal{M}\left(\frac{t}{x}\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, v]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

that is

$$
\mathcal{M}\left(\frac{t}{x}\right)=x \mathrm{P}(x)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right) .
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{aligned}
0 & =\left[y^{>0}\right] \mathrm{D}(x, y)\left(-1+x+\mathcal{M}\left(\frac{t}{y}\right)+y-v y+\omega \frac{t}{y}\right) \\
v \mathrm{E}(x, y) & =\frac{t v}{x y}+\mathrm{D}\left(\frac{t}{x}, y\right)\left(\frac{1}{x} \mathcal{M}\left(\frac{t}{x}\right)-\frac{t}{x y}\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

that is

$$
\mathcal{M}\left(\frac{t}{x}\right)=x \mathrm{P}(x)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right) .
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{aligned}
0 & =\left[y^{<0}\right] \mathrm{D}\left(x, \frac{t}{y}\right)\left(-1+x+\mathcal{M}(y)+\frac{t}{y}-\frac{v t}{y}+\omega y\right) \\
v-\frac{v t}{x y} \mathrm{E}\left(\frac{t}{x}, \frac{t}{y}\right) & =\mathrm{D}\left(x, \frac{t}{y}\right)\left(1-\frac{1}{y} \mathcal{M}(x)\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

that is

$$
\mathcal{M}\left(\frac{t}{x}\right)=x \mathrm{P}(x)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}\left(\frac{t}{x}, z\right) .
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{aligned}
0 & =\left[y^{<0}\right] \mathrm{D}\left(x, \frac{t}{y}\right)\left(-1+x+\mathcal{M}(y)+\frac{t}{y}-\frac{v t}{y}+\omega y\right) \\
v-\frac{v t}{x y} \mathrm{E}\left(\frac{t}{x}, \frac{t}{y}\right) & =\mathrm{D}\left(x, \frac{t}{y}\right)\left(1-\frac{1}{y} \mathcal{M}(x)\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{gathered}
\mathrm{D}\left(x, \frac{t}{y}\right)\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
v-\frac{v t}{x y} \mathrm{E}\left(\frac{t}{x}, \frac{t}{y}\right)=\mathrm{D}\left(x, \frac{t}{y}\right)\left(1-\frac{1}{y} \mathcal{M}(x)\right)
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, v]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{aligned}
& \mathrm{D}\left(x, \frac{t}{y}\right)\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
& \mathrm{D}\left(y, \frac{t}{x}\right)\left(1-\frac{1}{x} \mathcal{M}(y)\right)=\mathrm{D}\left(x, \frac{t}{y}\right)\left(1-\frac{1}{y} \mathcal{M}(x)\right)
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, v]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

## Simplifying equations

Equations:

$$
\begin{aligned}
& \mathrm{D}\left(x, \frac{t}{y}\right)\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
& y \mathrm{D}\left(y, \frac{t}{x}\right)(x-\mathcal{M}(y))=x \mathrm{D}\left(x, \frac{t}{y}\right)(y-\mathcal{M}(x))
\end{aligned}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{gathered}
\mathrm{D}\left(x, \frac{t}{y}\right)\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
y \mathrm{D}\left(y, \frac{t}{x}\right)(x-\mathcal{M}(y))=x \mathrm{D}\left(x, \frac{t}{y}\right)(y-\mathcal{M}(x)) \\
\mathcal{M}(x) \mathrm{D}\left(\mathcal{M}(x), \frac{t}{x}\right)(x-\mathcal{M}(\mathcal{M}(x)))=0
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, v]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

## SIMPLIFYING EQUATIONS

Equations:

$$
\begin{gathered}
\left.\mathrm{D}\left(x, \frac{t}{y}\right)\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]]\right] \\
y \mathrm{D}\left(y, \frac{t}{x}\right)(x-\mathcal{M}(y))=x \mathrm{D}\left(x, \frac{t}{y}\right)(y-\mathcal{M}(x)) \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{gathered}
\mathrm{D}\left(x, \frac{t}{y}\right)\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
y(x-\mathcal{M}(y)) / \mathrm{D}\left(x, \frac{t}{y}\right)=x(y-\mathcal{M}(x)) / \mathrm{D}\left(y, \frac{t}{x}\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{gathered}
y(x-\mathcal{M}(y))\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
y(x-\mathcal{M}(y)) / \mathrm{D}\left(x, \frac{t}{y}\right)=x(y-\mathcal{M}(x)) / \mathrm{D}\left(y, \frac{t}{x}\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z)
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{gathered}
y(x-\mathcal{M}(y))\left(x-1+\mathcal{M}(y)+\frac{(1-v) t}{y}+\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

## SIMPLIFYING EQUATIONS

Equations:
$x^{2} y-x\left(y-(1-v) t-\omega y^{2}\right)+y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]]$

$$
\mathcal{M}(\mathcal{M}(x))=x
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

## SIMPLIFYING EQUATIONS

## Equations:

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Define $\mathcal{M}(x) \in \frac{t}{x} \mathbb{Z}[\omega, \nu]\left[\left[\frac{t}{x}, x\right]\right]$ by

$$
\mathcal{M}(x)=\frac{t}{x} \mathrm{P}\left(\frac{t}{x}\right)+\frac{t}{v}\left[z^{1}\right] \mathrm{D}(x, z),
$$

## Characterisation of $\mathcal{M}(x)$

Theorem: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, \nu][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

The series $\mathbf{Q}(t, \omega, v)$ is given by

$$
\mathrm{Q}(t, \omega, v)=t^{-2}\left[y^{-2}\right] \mathcal{M}(y)-v .
$$

## Characterisation of $\mathcal{M}(x)$

Theorem: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, \nu][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

The series $\mathbf{Q}(t, \omega, v)$ is given by

$$
\mathrm{Q}(t, \omega, v)=t^{-2}\left[y^{-2}\right] \mathcal{M}(y)-v
$$

Next section: Solution for $\omega=0,1$
Following section: Solution for $v=1$ Still open: General solution

## Part 2: Solution for $\omega=0,1$

(Eulerian (partial) orientations by edges and vertices).

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(y))=y
\end{gathered}
$$

The series $\mathbf{Q}(t, \omega, v)$ is given by

$$
\mathrm{Q}(t, \omega, v)=t^{-2}\left[y^{-2}\right] \mathcal{M}(y)-v .
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(y))=y
\end{gathered}
$$

The series $\mathrm{Q}(t, 0, v)$ is given by

$$
\mathrm{Q}(t, 0, v)=t^{-2}\left[y^{-2}\right] \mathcal{M}(y)-v .
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(y))=y
\end{gathered}
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]], \\
\mathcal{M}(\mathcal{M}(y))=y
\end{gathered}
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{aligned}
& y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]], \\
& \quad(1-\mathcal{M}(y))(y \mathcal{M}(y)-t(v-1)) \in K[[y]],
\end{aligned}
$$

$$
\mathcal{M}(\mathcal{M}(y))=y
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]], \\
R(y):=(1-y)(1-\mathcal{M}(y))(y \mathcal{M}(y)-t(v-1)) \in K[[y]],
\end{gathered}
$$

$$
\mathcal{M}(\mathcal{M}(y))=y
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]], \\
R(y):=(1-y)(1-\mathcal{M}(y))(y \mathcal{M}(y)-t(v-1)) \in K[[y]],
\end{gathered}
$$

$$
\mathcal{M}(\mathcal{M}(y))=y
$$

So, $R(y) \in K[[y]]$ satisfies $R(\mathcal{M}(y))=R(y) \in K[[y]]$, which is only possible if $R(y)$ doesn't depend on $y$.

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]] \\
(1-y)(1-\mathcal{M}(y))(y \mathcal{M}(y)-t(v-1))=R \in t \mathbb{Z}[v][[t]], \\
\mathcal{M}(\mathcal{M}(y))=y
\end{gathered}
$$

So, $R(y) \in K[[y]]$ satisfies $R(\mathcal{M}(y))=R(y) \in K[[y]]$, which is only possible if $R(y)$ doesn't depend on $y$.

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]] \\
(1-y)(1-\mathcal{M}(y))(y \mathcal{M}(y)-t(v-1))=R \in t \mathbb{Z}[v][[t]], \\
\mathcal{M}(\mathcal{M}(y))=y
\end{gathered}
$$

Solution for $\mathcal{M}(y)$ :

$$
\begin{aligned}
M(y) & =\frac{y+t(v-1)}{2 y}\left(1-\sqrt{1-4 y \frac{t(v-1)+R /(1-y)}{(y+t(v-1))^{2}}}\right) \\
& =\frac{t v-t}{y}+\sum_{n, k, j \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{n+j}{n} t^{k}(v-1)^{k} R^{n+1} y^{j-n-k-1}
\end{aligned}
$$

## SOLUTION FOR $\omega=0$

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[v][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)-y \mathcal{M}(y)^{2}-(1-v) t \mathcal{M}(y) \in K[[y]], \\
(1-y)(1-\mathcal{M}(y))(y \mathcal{M}(y)-t(v-1))=R \in t \mathbb{Z}[v][[t]], \\
\mathcal{M}(\mathcal{M}(y))=y,
\end{gathered}
$$

Solution for $\mathcal{M}(y)$ :

$$
\begin{aligned}
M(y) & =\frac{y+t(v-1)}{2 y}\left(1-\sqrt{1-4 y \frac{t(v-1)+R /(1-y)}{(y+t(v-1))^{2}}}\right) \\
& =\frac{t v-t}{y}+\sum_{n, k, j \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{n+j}{n} t^{k}(v-1)^{k} R^{n+1} y^{j-n-k-1} \\
t v & =\left[y^{-1}\right] \mathcal{M}(y)=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k}{n} t^{k}(v-1)^{k} R^{n+1}
\end{aligned}
$$

## SOLUTION FOR $\omega=0$

Solution for $\mathcal{M}(y)$ :

$$
\begin{aligned}
M(y) & =\frac{y+t(v-1)}{2 y}\left(1-\sqrt{1-4 y \frac{t(v-1)+R /(1-y)}{(y+t(v-1))^{2}}}\right) \\
& =\frac{t v-t}{y}+\sum_{n, k, j \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{n+j}{n} t^{k}(v-1)^{k} R^{n+1} y^{j-n-k-1} \\
t v & =\left[y^{-1}\right] \mathcal{M}(y)=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k}{n} t^{k}(v-1)^{k} R^{n+1}
\end{aligned}
$$

## SOLUTION FOR $\omega=0$

Solution for $\mathcal{M}(y)$ :

$$
\begin{aligned}
M(y) & =\frac{y+t(v-1)}{2 y}\left(1-\sqrt{1-4 y \frac{t(v-1)+R /(1-y)}{(y+t(v-1))^{2}}}\right) \\
& =\frac{t v-t}{y}+\sum_{n, k, j \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{n+j}{n} t^{k}(v-1)^{k} R^{n+1} y^{j-n-k-1} \\
t v & =\left[y^{-1}\right] \mathcal{M}(y)=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k}{n} t^{k}(v-1)^{k} R^{n+1}
\end{aligned}
$$

Solution for generating function Q :
$\mathrm{Q}(t, 0, v)=t^{-2}\left[y^{-2}\right] \mathcal{M}(y)-v$.

$$
=-v+\frac{1}{t^{2}} \sum_{n, k} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k-1}{n} t^{k}(v-1)^{k} R^{n+1}
$$

## SOLUTION FOR $\omega=0$

Theorem: Let $R(t, v) \in \mathbb{Z}[v][[t]]$ be the unique series with constant term 0 satisfying

$$
t v=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k}{n} t^{k}(v-1)^{k} R^{n+1}
$$

The generating function $\mathrm{Q}(t, 0, v)$ for height-labelled quadrangulations (with no alternating faces) counted by faces and local minima is given by
$\mathrm{Q}(t, 0, v)=-v+\frac{1}{t^{2}} \sum_{n, k} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k-1}{n} t^{k}(v-1)^{k} R^{n+1}$.
Corollary: $\mathrm{Q}(t, 0, v)$ and $R(t, v) \mathrm{D}$-algebraic in $t, v$.

## SOLUTION FOR $\omega=0$

Theorem: Let $R(t, v) \in \mathbb{Z}[v][[t]]$ be the unique series with constant term 0 satisfying

$$
t v=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k}{n} t^{k}(v-1)^{k} R^{n+1}
$$

The generating function $\mathrm{Q}(t, 0, v)$ for height-labelled maps counted by edges and faces is given by
$\mathrm{Q}(t, 0, v)=-v+\frac{1}{t^{2}} \sum_{n, k} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k-1}{n} t^{k}(v-1)^{k} R^{n+1}$.
Corollary: $\mathrm{Q}(t, 0, v)$ and $R(t, v) \mathrm{D}$-algebraic in $t, v$.

## SOLUTION FOR $\omega=0$

Theorem: Let $R(t, v) \in \mathbb{Z}[v][[t]]$ be the unique series with constant term 0 satisfying

$$
t v=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k}{n} t^{k}(v-1)^{k} R^{n+1}
$$

The generating function $\mathrm{Q}(t, 0, v)$ for Eulerian orientations counted by edges and vertices is given by
$\mathrm{Q}(t, 0, v)=-v+\frac{1}{t^{2}} \sum_{n, k} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{2 n+k-1}{n} t^{k}(v-1)^{k} R^{n+1}$.
Corollary: $\mathrm{Q}(t, 0, v)$ and $R(t, v) \mathrm{D}$-algebraic in $t, v$.

## SOLUTION FOR $\omega=1$

Theorem: Let $R(t, v) \in \mathbb{Z}[v][[t]]$ be the unique series with constant term 0 satisfying (in some domain)

$$
t=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{3 n+2 k}{n+k} t^{k}(v-1)^{k} R^{n+1} .
$$

The generating function $\mathrm{Q}(t, 1, v)$ for height-labelled quadrangulations counted by faces and local minima is given by
$\mathrm{Q}(t, 1, v)=-v+\frac{1}{t^{2}} \sum_{n, k} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{3 n+2 k-1}{2 n+k} t^{k}(v-1)^{k} \mathrm{R}_{1}^{n+1}$.
Corollary: $\mathrm{Q}(t, 1, v)$ and $R(t, v) \mathrm{D}$-algebraic in $t, v$.

## SOLUTION FOR $\omega=1$

Theorem: Let $R(t, v) \in \mathbb{Z}[v][[t]]$ be the unique series with constant term 0 satisfying (in some domain)

$$
t=\sum_{n, k \geq 0} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{3 n+2 k}{n+k} t^{k}(v-1)^{k} R^{n+1} .
$$

The generating function $\mathrm{Q}(t, 1, v)$ for Eulerian partial orientations counted by edges and vertices is given by
$\mathrm{Q}(t, 1, v)=-v+\frac{1}{t^{2}} \sum_{n, k} \frac{1}{n+1}\binom{2 n}{n}\binom{2 n+k}{k}\binom{3 n+2 k-1}{2 n+k} t^{k}(v-1)^{k} \mathrm{R}_{1}^{n+1}$.
Corollary: $\mathrm{Q}(t, 1, v)$ and $R(t, v) \mathrm{D}$-algebraic in $t, v$.

## Part 3: Analytic functional equations



## ANALYTIC FUNCTIONAL EQUATIONS

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, \nu][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Claim: For sufficiently small $t$, there is an even meromorphic function $\chi$ on $\mathbb{C}$ and some $\gamma \in i \mathbb{R}_{>0}$ satisfying

$$
\mathcal{M}(\chi(z))=\chi(\gamma-z)
$$

and

$$
1+\frac{t(v-1)}{\chi(z)}=\chi(\gamma+z)+\omega \chi(z)+\chi(z-\gamma)
$$

## ANALYTIC FUNCTIONAL EQUATIONS

Recall: There is a unique series $\mathcal{M}(y) \in \frac{t}{y} \mathbb{Z}[\omega, \nu][[y, t / y]]$ with $\left[y^{-1}\right] \mathcal{M}(y)=t v$ satisfying

$$
\begin{gathered}
y \mathcal{M}(y)\left(1-\mathcal{M}(y)-\frac{(1-v) t}{y}-\omega y\right) \in K[[y]] \\
\mathcal{M}(\mathcal{M}(x))=x
\end{gathered}
$$

Claim: For sufficiently small $t$, there is an even meromorphic function $\chi$ on $\mathbb{C}$ and some $\gamma \in i \mathbb{R}_{>0}$ satisfying

$$
\mathcal{M}(\chi(z))=\chi(\gamma-z)
$$

and

$$
1+\frac{t(v-1)}{\chi(z)}=\chi(\gamma+z)+\omega \chi(z)+\chi(z-\gamma)
$$

Last section: Solved for $\omega=0,1$.
Next section: Solution for $v=1$.
Still open: All other values $\omega, v$.

## Part 4: Six vertex model $(v=1)$

(Previous solution: Kostov (2000)/EP and Zinn-Justin (2019)).

## Recall: Solutions at $\omega=0,1$

The generating function $\mathrm{Q}(t, 0,1)$ is given by

$$
\begin{aligned}
t & =\sum_{n=0}^{\infty} \frac{1}{n+1}\binom{2 n}{n}^{2} \mathrm{R}_{0}(t)^{n+1} \\
\mathrm{Q}(t, 0,1) & =\frac{1}{2 t^{2}}\left(t-2 t^{2}-\mathrm{R}_{0}(t)\right)
\end{aligned}
$$

The generating function $\mathrm{Q}(t, 1,1)$ is given by

$$
\begin{aligned}
t & =\sum_{n=0}^{\infty} \frac{1}{n+1}\binom{2 n}{n}\binom{3 n}{n} \mathrm{R}_{1}(t)^{n+1}, \\
\mathrm{Q}(t, 1,1) & =\frac{1}{3 t^{2}}\left(t-3 t^{2}-\mathrm{R}_{1}(t)\right) .
\end{aligned}
$$

## SOLUTION FOR $\mathrm{Q}(t, \omega, 1)$

Define

$$
\vartheta(z, q)=\sum_{n=0}^{\infty}(-1)^{n}\left(e^{(2 n+1) i z}-e^{-(2 n+1) i z}\right) q^{(2 n+1)^{2} / 8}
$$

Let $q=q(t, \alpha)$ be the unique series satisfying

$$
t=\frac{\cos \alpha}{64 \sin ^{3} \alpha}\left(-\frac{\vartheta(\alpha, q) \vartheta^{\prime \prime \prime}(\alpha, q)}{\vartheta^{\prime}(\alpha, q)^{2}}+\frac{\vartheta^{\prime \prime}(\alpha, q)}{\vartheta^{\prime}(\alpha, q)}\right) .
$$

Define $\mathrm{R}(t, \gamma)$ by

$$
\mathrm{R}(t,-2 \cos (2 \alpha))=\frac{\cos ^{2} \alpha}{96 \sin ^{4} \alpha} \frac{\vartheta(\alpha, q)^{2}}{\vartheta^{\prime}(\alpha, q)^{2}}\left(-\frac{\vartheta^{\prime \prime \prime}(\alpha, q)}{\vartheta^{\prime}(\alpha, q)}+\frac{\vartheta^{\prime \prime \prime}(0, q)}{\vartheta^{\prime}(0, q)}\right) .
$$

Then

$$
\mathbf{Q}(t, \gamma)=\frac{1}{(\gamma+2) t^{2}}\left(t-(\gamma+2) t^{2}-\mathbf{R}(t, \gamma)\right)
$$

## Thank you!

# Bijection 1: height-labelled quadrangulations to weakly height-labelled maps 

(Miermont (2009)/Ambjørn and Budd (2013)).

## QUADRANGULATIONS TO MAPS

Start with a height-labelled quadrangulation.


## H-QuAdrangulations to H-maps

Start with a height-labelled quadrangulation.


## H-QuAdrangulations to H-maps

Draw a red edge in each face according to the rule.


## H-QuAdrangulations to H-maps

Remove all of the original edges.


## H-QuAdrangulations to H-maps

Remove any isolated vertices.


## H-QUADRANGULATIONS TO H-MAPS

The new map is a weakly height-labelled map (adjacent labels differ by at most 1 ).


## H-QUADRANGULATIONS TO H-MAPS

The new map is a weakly height-labelled map (adjacent labels differ by at most 1 ).


These are counted by edges $(t)$, mono-value edges $(\omega)$ and faces $(v)$.

# Bijection 2: H-maps to Eulerian orientations (EO-maps) Same Bijection: H-quads to EO-quarts 

(EP and Gutmann (2018)).

## EO-QUARTS

EO-quarts: each vertex has two incoming and two outgoing edges.
Counted by vertices $(t)$, alternating vertices $(\omega)$ and clockwise faces
(v)


## H-QUADS TO EO-QUARTS

Start with a height-labelled quadrangulation.


## BIJECTION TO THE ICE MODEL

Draw the dual with edges oriented according to the rule.


## BIJECTION TO THE ICE MODEL

Each red vertex has two incoming and two outgoing edges.


## BIJECTION TO THE ICE MODEL

Each red vertex has two incoming and two outgoing edges.


## BIJECTION TO THE ICE MODEL

Each vertex has two incoming and two outgoing edges.


## Bonus Slide: BIJECTION TO A LOOP MODEL

Let $\mathrm{C}(t, \omega)$ be the generating function for partially oriented cubic maps in which each vertex is one of the following types.


## Bonus Slide: BIJECTION TO A LOOP MODEL

Let $\mathrm{C}(t, \omega)$ be the generating function for partially oriented cubic maps in which each vertex is one of the following types.


Theorem: $\mathbf{Q}\left(t, \omega^{2}+\omega^{-2}\right)=\mathbf{C}(t, \omega)$.

# Bijection 3: A loop model 

(Kostov (2000)).

## Bonus Slide: BIJECTION TO A LOOP MODEL

Theorem: $\mathbf{Q}\left(t, \omega^{2}+\omega^{-2}\right)=\mathbf{C}(t, \omega)$


## Bonus Slide: BIJECTION TO A LOOP MODEL

Theorem: $\mathbf{Q}\left(t, \omega^{2}+\omega^{-2}\right)=\mathbf{C}(t, \omega)$

(weight $t$ )

(weight $\gamma t$ )

(weight $t$ )

(weight $\omega^{2} t$ )


(weight $\omega^{-2} t$ )

