Introduction to integrable hierarchies

The example of combinatorial maps

Valentin Bonzom

LIGM – Université Gustave Eiffel

De Rerum Natura + Équations fonctionnelles et Interactions 11 juin 2024

- Every similarity with textbooks and existing articles from other authors is purely intentional.
- ▷ This is mostly a mini-course.
- ▷ Some work in progress, which could definitely benefit from this community!

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

Plan

- Combinatorial maps and functional equations
- Integrable systems and hierarchies
- Back to maps

 Combinatorial maps are graphs "properly" embedded in surfaces, up to deformation





▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

Combinatorial maps

 Combinatorial maps are graphs "properly" embedded in surfaces, up to deformation



▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

▷ The graph complement is a disjoint union of disks, called faces

Combinatorial maps

 Combinatorial maps are graphs "properly" embedded in surfaces, up to deformation



▷ The graph complement is a disjoint union of disks, called faces



▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

 Combinatorial maps are graphs "properly" embedded in surfaces, up to deformation



- ▷ The graph complement is a disjoint union of disks, called faces
- $\triangleright\,$ Encoded by cyclic order around vertices $\rightarrow\,$ permutations and representations of the symmetric group

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

Examples

- They are topological surfaces, nice interplay between combinatorics and topology
- $\triangleright\;$ Euler's formula for the genus $g\geq 0$



Planar triangulation



Planar bipartite map



Planar quadrangulation























Drawing in the plane of map with genus: Crossings



Map of genus 1



Map of genus 2

- ▷ Count maps by genus and size
- \triangleright E.g. planar maps by number of edges [Tutte 60s]

 $27t^2M(t)^2 + (1 - 18t)M(t) + 16t - 1 = 0$

implies $[t^n]M(t) = \frac{2 \cdot 3^n}{(n+1)(n+2)} {2n \choose n}$

- ▷ What kind of equations do the GF satisfy?
- ▷ Consider bipartite maps. The degree of a face is half its number of sides.
- ▷ A partition $\lambda = (\lambda_1, \lambda_2, ..., \lambda_l)$ with $\lambda_1 \ge \cdots \ge \lambda_l \ge 0$ like (3, 2, 2, 1)

▷ Encode the degrees of white vertices in a partition



A D > 4 回 > 4 回 > 4 回 > 1 回 9 Q Q

▷ Notice that the size, i.e. number of edges, is $n = \sum_{i=1}^{l} \lambda_i$.

Generating functions

▷ Consider an infinite set of indeterminates x₁, x₂, x₃,... where x_i is associated to each face of degree i

$$For \lambda = (\lambda_1, \lambda_2, \dots, \lambda_l)$$

$$x_{\lambda} = x_1 \cdots x_l$$

$$x_{(3,2,2,1)} = x_3 x_2^2 x_1$$

▷ Denote \mathcal{M}_{λ} the set of bip. maps, connected or not with face partition λ , having $n = \sum_{i} \lambda_i$ edges.

 $ho~ au\equiv au(t,u,v,x_1,x_2,\dots)$ the GF of labeled bip. maps, connected or not

$$\tau = \sum_{n\geq 0} \frac{t^n}{n!} \sum_{|\lambda|=n} \sum_{\mathcal{M}_{\lambda}} u^{V_0} v^{V_{\bullet}} x_{\lambda} \in \mathbb{Q}[u, v, x_1, x_2, \dots][[t]]$$



▷ Connected: $F = \log \tau$ ▷ Control genus $F^{(g)} = [w^{2-2g}]F_{|t \to t/w, x_i \to wx_i, u, v \to u/w, v/w}$

- ▷ "Rooting" operation: mark a corner in a face $\rightarrow x_i^* \equiv \frac{i\partial}{\partial x_i}$
- $ightarrow rac{ extsf{Thm}}{ extsf{Thm}} au$ is uniquely determined by the equations $L_i au = 0$ for $i \geq 0$

$$L_i = -x_{i+1}^* + t \sum_{j+k=i} x_j^* x_k^* + t \sum_{j \ge 1} x_j x_{i+j}^* + t(u+v) x_i^* + tuv \delta_{i,0}$$

- $\triangleright \operatorname{\underline{\mathsf{Proof}}} x_{i+1}^* \tau$ counts maps with a rooted face of degree i+1
- ▷ Remove the root edge and consider the different cases
- ▷ The root edge "joins" two different faces



- ▷ "Rooting" operation: mark a corner in a face $\rightarrow x_i^* \equiv \frac{i\partial}{\partial x_i}$
- $ightarrow rac{ extsf{Thm}}{ extsf{Thm}} au$ is uniquely determined by the equations $L_i au = 0$ for $i \geq 0$

$$L_i = -x_{i+1}^* + t \sum_{j+k=i} x_j^* x_k^* + t \sum_{j \ge 1} x_j x_{i+j}^* + t(u+v) x_i^* + tuv \delta_{i,0}$$

- \triangleright <u>Proof</u> $x_{i+1}^* \tau$ counts maps with a rooted face of degree i+1
- ▷ Remove the root edge and consider the different cases
- ▷ The root edge "cuts" a face



- ▷ "Rooting" operation: mark a corner in a face $\rightarrow x_i^* \equiv rac{i\partial}{\partial x_i}$
- $ightarrow rac{1}{2} r{1}{2} rac{1}{2} rac{1}{2}$

$$L_i = -x_{i+1}^* + t \sum_{j+k=i} x_j^* x_k^* + t \sum_{j \ge 1} x_j x_{i+j}^* + t(u+v) x_i^* + tuv \delta_{i,0}$$

- \triangleright <u>Proof</u> $x_{i+1}^* \tau$ counts maps with a rooted face of degree i+1
- > Remove the root edge and consider the different cases
- ▷ The root edge connects to a "new" vertex



- ▷ "Rooting" operation: mark a corner in a face $\rightarrow x_i^* \equiv \frac{i\partial}{\partial x_i}$
- $ightarrow rac{ extsf{Thm}}{ extsf{Thm}} au$ is uniquely determined by the equations $L_i au = 0$ for $i \geq 0$

$$L_i = -x_{i+1}^* + t \sum_{j+k=i} x_j^* x_k^* + t \sum_{j \ge 1} x_j x_{i+j}^* + t(u+v) x_i^* + tuv \delta_{i,0}$$

- $\triangleright \operatorname{\underline{\mathsf{Proof}}}_{i+1} x_{i+1}^* au$ counts maps with a rooted face of degree i+1
- Remove the root edge and consider the different cases
- ▷ The root face has degree 1



- $\triangleright \ [L_i, L_j] = t(i-j)L_{i+j-1}$
- ▷ Important remark: if we set degrees as follows:

$$\deg(x_i) = -i, \qquad \deg(x_i^*) = i$$

- \triangleright then $[t^n]\tau$ is homogeneous of degree -n
- \triangleright But L_i is not homogeneous, because it is inductive on the size

Applications

Cases

- 1. $x_i = 1$ for all $i \ge 1 \rightarrow$ all maps
- 2. $d \ge 2$ and keep x_1, \ldots, x_d formal and set $x_{d+1} = x_{d+2} = \cdots = 0$ allow only for a finite number of face degrees
- > Extract an equation in the planar sector

$$\sum_{i} z^{i} [w^{2}] e^{-F} L_{i} e^{F}_{|t \to t/w, x_{i} \to wx_{i}, u, v \to u/w, v/w} = 0$$

Applications

Cases

- 1. $x_i = 1$ for all $i \ge 1 \rightarrow$ all maps
- 2. $d \ge 2$ and keep x_1, \ldots, x_d formal and set $x_{d+1} = x_{d+2} = \cdots = 0$ allow only for a finite number of face degrees
- ▷ Gives a equation on $W(z) = \sum_{i \ge 1} z^i x_i^* F^{(0)}$ involving unknown series, said to have one catalytic variable

▷ Case 1

$$tzW(z)^{2} + (tz(u+v) - 1)W(z) + tz\frac{W(z) - W(1)}{z - 1} + tuv = 0$$

▷ Case 2

$$tzW(z)^{2} + \left(t\sum_{i=1}^{d} x_{i}z^{-i+1} + tz(u+v) - 1\right)W(z) - t\sum_{i=2}^{d}\sum_{j=1}^{i-1} x_{j}z^{-(i-1-j)}x_{j}^{*}F^{(0)} + tuv = 0$$

 \triangleright Quadratic equations, but with unknown/mysterious series in t!

More on this

- <u>Thm</u> [Bousquet-Mélou-Jehanne] The mysterious series are algebraic (and there is an algorithm to produce the system).
- \triangleright "Trivial" cases: one mysterious series in case 1 and case 2 with $x_k = x \delta_{k,2}$

$$tzW(z)^{2} + (tz(u+v) - 1)W(z) + tz\frac{W(z) - W(1)}{z - 1} + tuv = 0$$

$$tzW(z)^{2} + (txz^{-1} + tz(u+v) - 1)W(z) - tx(x_{1}^{*}F^{(0)}) + tuv = 0$$

all bip. maps and bip. quadrangulations

 \triangleright "Non-trivial" cases, e.g. $x_k = x \delta_{k,3}$ i.e. bipartite hexangulations

$$tzW(z)^{2} + \left(txz^{-2} + tz(u+v) - 1\right)W(z) - tx(z^{-1}x_{1}^{*}F^{(0)} + x_{2}^{*}F^{(0)}) + tuv = 0$$

・ロト ・ 日 ・ モ ヨ ト ・ 日 ・ う へ つ ・

▷ In general in case 2, the mysterious series are $x_1^* F^{(0)}, \ldots, x_{d-1}^* F^{(0)}$.

- ▷ How would this look in higher genus?
- ▷ Do we need to solve for mysterious series and how?
- ▷ What would be an equivalent of the BMJ thm?
- ▷ Typically polynomial equations become differential equations

$$W(z)^k
ightarrow rac{d^k}{dz^k}\psi(z)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

▷ "Quantization"

▷ Same method as above involves $x_i^* x_j^* F^{(0)}$ at genus 1, $x_i^* x_j^* x_k^* F^{(1)}$ at genus 2, and so on.

$$\sum_{j+k=i} x_j^* x_k^* e^F \rightarrow \sum_{j+k=i} x_j^* F x_k^* F + (x_j^* x_k^* F)$$

- ▶ Much less explicit results
- ▷ Thm [Bender-Canfield-Richmond] In case 1, $x_1^* F^{(g)}$ is rational w.r.t. algebraic series (of trees)
- ▷ Proof of BCR relies on writing equations $L_i \tau = 0$ as inductive system on genus and number of marked faces
- Bijective proof of BCR at fixed genus by Albenque-Lepoutre/Lepoutre, bypasses the constraints! (How dare they!)

- ▷ Same method as above involves $x_i^* x_j^* F^{(0)}$ at genus 1, $x_i^* x_j^* x_k^* F^{(1)}$ at genus 2, and so on.
- ▷ Nowadays, in case 2, there is an algorithm to calculate the series with n marked face and genus g w.r.t. 2g + n (Eynard & co.) called topological recursion (TR)
- This procedure applies well beyond the world of maps, in *enumerative* geometry
- \triangleright Proof of TR relies on writing equations $L_i \tau = 0$ as inductive system on genus and number of marked faces
- TR does everything it can to eliminate the mysterious series, but here we want the opposite!

(ロ)、(同)、(E)、(E)、(E)、(O)へ(C)

Some recurrence formula for maps

 $\models t_g^n = |\{ \# \text{ triangulations of genus } g \text{ with } n \text{ triangles} \}| \\ [Kazakov-Kostov-Nekrasov99 in appendix, Goulden-Jackson08]$

$$(n+1)t_g^n = 4n(3n-2)(3n-4)t_{g-1}^{n-1} + 4\sum_{\substack{i+j=n-2\\h+k=g}} (3i+2)(3j+2)t_h^i t_k^j$$

 $m_g^n = |\{\# \text{ maps of genus } g \text{ with } n \text{ edges } \& \text{ weight } u \text{ per vertex}\}|$ [Carrell-Chapuy14, Kazarian-Zograf15]

$$(n+1)m_{g}^{n} = 2(1+u)(2n-1)m_{g}^{n-1} + \frac{1}{2}(2n-3)(2n-2)(2n-1)m_{g-1}^{n-2} + 3\sum_{\substack{i+j=n-2\\h+k=g}} (2i+1)(2j+1)m_{h}^{i}m_{k}^{j}$$

▷ $b_g^n = \{\# \text{ bip. maps, weight } u \text{ per white vertex } \& v \text{ per black vertex}\}|$ [Kazarian-Zograf15]

$$(n+1)b_{g}^{n} = \alpha^{n}(u,v)b_{g-1}^{n} + \beta^{n}(u,v)b_{g-2}^{n} + \gamma^{n}b_{g-2}^{n-1} + \sum_{i+j=n-2\atop h+k=g} \mu_{i}\mu_{j}b_{h}^{j}b_{k}^{j}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

- Remarkably simple! Bypass the TR/marked faces thing
- \triangleright Coefficients are independent of genus \rightarrow ODEs!
- \triangleright ODE on $\frac{dF}{dt}$ for the "trivial" cases (w.r.t. the planar case):
 - \triangleright For bipartite maps: case 1 and case 2 with $x_k = x \delta_{k,2}$ i.e. bip. quadrangulations
 - \triangleright For general maps: case $x_k = 1$ and case $x_k = x \delta_{k,3}$ i.e. triangulations
- ▷ "Trivial" cases again for orientable and non-orientable maps [VB-Chapuy-Dołęga]

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● ○ ○ ○

- \triangleright ODE in case 2, but with shifts on u, v [Louf19]
- <u>Question</u>: ODE for general case 2?
 <u>Looks like yes</u>
 Evidence of principle, explicit algorithms still buffering

A table

Rooted maps of genus g with n edges, orientable or not

n∖g	5/2	3	7/2	4
5	8229	0	0	0
6	516958	166377	0	0
7	19381145	1 3093972	4016613	0
8	562395292	595145086	382630152	113044185
9	1 3929564070	20431929240	2 05 4 9 34 85 78	12704958810
10	309411522140	587509756150	818177659640	790343495467
11	6344 70 77 86 94 5	14923379377192	26881028060634	35 91 87 79 73 761 0
12	1 22 35 74 81 54 58 72	345651571125768	770725841809552	1 330964 564 9401 40
13	2247532739398856	7452363840633244	19946409152977346	4 2611 0024 351 245 52
14	39681114425793904	1 51 71 74862 05 70 97 30	476412224477845444	1220973091185233106
15	677939355268197412	2946794762696249280	10665684328125155376	32054128913697072040
16	11265765391845733784	55029552840385680100	226357454725004343024	783804517126931727890

▷ The constraints $L_i \tau = 0$ determine τ , so... Yet, not able with $L_i \tau = 0$ only!!

Use KP equation as a black box instead

$$-F_{3,1}+F_{2,2}+\frac{1}{2}F_{1,1}^2+\frac{1}{12}F_{1^4}=0$$

with $f_i \equiv \frac{\partial f}{\partial x_i}$

Details to come, be patient!

- \triangleright Recall degrees such that $[t^n] au$ is homogeneous of degree n
- \triangleright The operator L_i is not, because the constraints are inductive on the size
- ▷ deg $\left(\frac{\partial}{\partial x_i}\right) = i \Rightarrow$ the KP equation is homogeneous
- ▷ Use the constraints to rewrite these terms as polynomials in F and its derivatives w.r.t. t to get an ODE

▷ Proposition

Example
$$x_k = x \delta_{k,2}$$
. Denote $\overline{f} \equiv f_{|x_k = x \delta_{k,2}}.$

 $\overline{F_{3,1}}$, $\overline{F_{2,2}}$, $\overline{F_{1,1}}$ and $\overline{F_{1^4}}$ are differential polynomials in $\frac{d\overline{F}}{dt}$.

Warning: take derivatives before evaluating!

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三回 のへで

Proof in the case $x_k = x \delta_{k,2}$

homogeneity:
$$t\frac{dF}{dt} = \sum_{i\geq 1} ix_iF_i$$
, L_0 : $F_1 = t^2\frac{dF}{dt} + tuv$
 L_1 : $2F_2 = t\sum_{i\geq 1} (i+1)x_iF_{i+1} + t(u+v)F_1$

▷ Homogeneity implies $\overline{F_2} = \frac{t}{2x} \frac{d\overline{F}}{dt}$. Taking the x₂-derivative

$$t\frac{d\overline{F_2}}{dt} = 2\overline{F_2} + 2x\overline{F_{2,2}} \implies \overline{F_{2,2}} = \frac{t}{4x^2} \left(t\frac{d^2\overline{F}}{dt^2} - \frac{d\overline{F}}{dt} \right)$$

 \triangleright L₀ gives by induction: $\overline{F_{1^k}} = t^2 \frac{d\overline{F_{1^{k-1}}}}{dt} + tuv \delta_{k,1}$

$$\overline{F_{1^k}} = \left(t^2 \frac{d}{dt}\right)^{k-1} \left(t^2 \frac{d\overline{F}}{dt} + tuv\right) \Rightarrow \overline{F_{1,1}} \text{ and } \overline{F_{1,1,1,1}}$$

- ▷ x₁-derivative of homogeneity gives
- \triangleright Take x₁-derivative of L₁

$$t\frac{dF_1}{dt} = \overline{F_1} + x\overline{F_{2,1}}$$
$$2\overline{F_{2,1}} = t\overline{F_2} + 3tx\overline{F_{3,1}} + t(u+v)\overline{F_{1,1}}$$

<u>Claim</u> (to be checked explicitly) There is a closed recursive system for $x_k = x \delta_{k,3}$.

homogeneity:
$$t \frac{dF}{dt} = \sum_{i \ge 1} ix_i F_i$$
, L_0 : $F_1 = t^2 \frac{dF}{dt} + tuv$
 L_1 : $2F_2 = t \sum_{i \ge 1} (i+1)x_i F_{i+1} + t(u+v)F_1$
 L_2 : $3F_3 = t \sum_{i \ge 1} (i+2)x_i F_{i+2} + t(u+v)F_2$

- ▷ Homogeneity and L₀ give t d F = 3x F = 1/t F - uv

 ▷ L₁ gives 2F = 4tx F + t(u + v)F - 1/F + t(u + v)F +
- ▷ Not able to prove directly that $\overline{F_2}$, $\overline{F_{2,2}}$ are differential polynomials in $\frac{d\overline{F}}{dt}$...
- ▷ But able to write $\overline{F_{3,2}}, \overline{F_{4,2}}, \overline{F_{4,1}}, \overline{F_{5,1}}, \overline{F_{3^k,1^{\prime}}}$ as differential polynomials in $\overline{F_2}$ and $\overline{F_{2,2}}$ and $\frac{d\overline{F}}{dt}$

More KP equations!

▷ It is a bit like in Bousquet-Mélou-Jehanne with several unknown series
 "Need" to involve more equations to eliminate the dependence in F₂ and F_{2,2}
 ▷ The KP equation is accompanied by an infinite number of compatible PDEs

$$-F_{4,1}+F_{3,2}+F_{2,1}F_{1,1}+\frac{1}{6}F_{2,1}=0$$

> They are labeled by partitions. Here is another one

$$-6F_{5,1} + 4F_{4,2} + 2F_{3,3} + 4F_{3,1}F_{1,1} + \frac{2}{3}F_{3,1^3} + 4F_{2,1}^2 + 2F_{2,2}F_{1,1} + F_{2,2,1,1} + \frac{1}{3}F_{1,1}^3 + \frac{1}{6}F_{1^4}F_{1^2} + \frac{1}{180}F_{1^6} = 0$$

- ▷ Get a system of 3 ODEs involving \overline{F} , $\overline{F_2}$, $\overline{F_{2,2}}$. Resultants for ODEs?
- ▷ What is the algo for general d?
- ▷ Main idea: as $d(x_d \text{ is last non-vanishing } x_i)$ grows, Virasoro constraints create some inflation in the order of the derivatives $\overline{F_{\lambda_1,\lambda_2,\dots}}$ required.
- Still, only require a finite number
- \triangleright Use the KP equations which are homogeneous in $\lambda_1+\lambda_2+\cdots$ to close the system.

Plan

- ▷ All those KP equations are called the KP *hierarchy*
- \triangleright What I propose now: re-reading textbooks adapted to CS
- ▷ Two typical approaches to the KP hierarchy
 - Algebraic combinatorics, very useful to prove that a GF satisfies those PDEs not today!

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● ○ ○ ○

- Lax pair and pseudo-differential operators, could be useful to extract recurrence formulas? today's proposal!
- Lax pair approach to integrable systems
- > Toda lattice hierarchy, KdV hierarchy, KP hierarchy

Bibliography

- ▷ It's complicated. And nothing about FPS AFAIK
- ▷ Classical integrable systems, Babelon, Bernard, Talon
- ▷ Solitons, Jimbo, Miwa, Date
- ▷ Infinite dimensional Lie algebras Bombay lectures, Kac, Raina

Warning!!

- Classical integrability is part of symplectic geometry
- $\triangleright\,$ Here, avoid symplectic geometry as much as possible
- $\triangleright~$ So if anything unclear $\rightarrow~$ symplectic geometry
- \triangleright Classical system described by a set of "positions" (q_1, \ldots, q_n) and momenta (p_1, \ldots, p_n)
- ▷ Time evolution given by equations of motion (EOM)

$$rac{dq_i}{dt}=p_i,\qquad rac{dp_i}{dt}=f_i(q_1,p_1,\dots)$$

Example Two-body problem aka Kepler problem

- \triangleright Two bodies in 3D space and gravitational attraction
- ▷ In center of mass frame, three coordinates x_1, x_2, x_3 and their momenta p_1, p_2, p_3

▷ Let
$$r = \sqrt{x_1^2 + x_2^2 + x_3^2}$$
 and $V(r) = C/r$, and $H = \frac{1}{2} (\sum_{i=1}^3 p_i^2) + V(r)$

Equations of motion

$$\frac{dx_i}{dt} = p_i, \qquad \frac{dp_i}{dt} = -\frac{\partial V(r)}{\partial x_i}, \text{ i.e. } \quad \frac{d^2 \vec{x}}{dt^2} = -\vec{\nabla} V(r)$$

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● ○ ○ ○

- \triangleright Liouville/Classical integrability: Existence of *n* conserved quantities I_1, \ldots, I_n which are indpdt and "Poisson commute"
- \triangleright Conservation: for all i = 1, ..., n, $\frac{dl_i}{dt} = 0$
- ▷ Independence: the dl; are linearly independent everywhere
- ▷ Liouville theorem: Solution by quadratures
- ▷ There exists a change of variables

$$(q_1, p_1, \ldots, q_n, p_n) \mapsto (I_1, \psi_1, I_2, \psi_2, \ldots, I_n, \psi_n)$$

where the equations of motion are

$$\frac{dI_i}{dt} = 0 \qquad \frac{d\psi_i}{dt} = f_i(I_1, \dots, I_n) = \text{Const}$$

 \triangleright Space of solutions parametrized by I_1,\ldots,I_n

Summary

- ▷ Idea: "enough independent conserved quantities which commute"
- \triangleright Calculating the ψ_i only involves solving algebraic systems and integrals
- > In the two-body problem, three conserved quantities
- \triangleright Introduce the angular momentum $\vec{J} = \vec{x} \times \vec{p}$

$$J_1 = x_2 p_3 - x_3 p_2, \quad J_2 = x_3 p_1 - x_1 p_3, \dots$$

$$I_1 = H, \quad I_2 = \overline{J}^2, \quad I_3 = J_3$$



> In spherical coordinates, the action reads

$$S(r, \theta, \phi, I_1, I_2, I_3) = \int^r 2\sqrt{\left(H - V(r)\right) - \frac{\tilde{J}^2}{r'^2}} dr' + \int^{\theta} \sqrt{\tilde{J}^2 - \frac{J_z^2}{\sin^2 \theta'}} d\theta' + \int^{\phi} J_z d\phi'$$

and

$$\psi_1 = \frac{\partial S}{\partial H}, \quad \psi_2 = \frac{\partial S}{\partial J^2}, \quad \psi_3 = \frac{\partial S}{\partial J_z}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ ○三 のへで

- ▷ Modern and unifying approach to integrable systems
- ▷ Way to obtain conserved quantities directly
- \triangleright Encode your degrees of freedom into a matrix or an operator *L*, such that there exists *M* such that

$$\frac{dL}{dt} = [M, L] := ML - LM$$

 \triangleright If you have a notion of trace, satisfying cyclicity tr AB =tr BA, then

$$I_i := \operatorname{tr}(L^i) \Rightarrow \frac{dI_i}{dt} = 0$$

"Isospectral flow": symmetric polynomials in eigenvalues are conserved

Isospectral deformations

Example: the open Toda lattice

N particles on the real line, positions q₁,..., q_N, momenta p₁,..., p_N
 Particle i interacts with i − 1 and i + 1 with exponential potential

$$\underline{\mathsf{EOM}} \qquad \frac{dq_i}{dt} = p_i, \qquad \frac{dp_i}{dt} = e^{q_{i-1}-q_i} - e^{q_i-q_{i+1}}$$

and $rac{dp_1}{dt}=-e^{q_1-q_2}$ and $rac{dp_N}{dt}=e^{q_{N-1}-q_N}$

- Other boundary conditions can be used and lead to different Lax pairs and solutions
- \triangleright Initial configuration: values of $q_1, p_1, \ldots, q_N, p_N$ at time t = 0
- \triangleright Energy is a conserved quantity $\frac{dH}{dt}=0$

$$H = \frac{1}{2} \sum_{i=1}^{N} p_i^2 + \sum_{k=1}^{N-1} e^{q_i - q_{i+1}}$$

Final configuration satisfies

$$q_{i+1} - q_i o \infty$$
 as $t o \infty$

which is stationary $\frac{dp_i}{dt} = 0$, and each p_i converges.

Lax pair for open Toda lattice

▷ Change of variables: $a_i = \frac{1}{2}e^{(q_i-q_{i+1})/2}$ for i = 1, ..., N-1 and $b_i = -\frac{1}{2}p_i$ for i = 1, ..., N

$$\frac{da_i}{dt} = a_i(b_{i+1} - b_i), \qquad \frac{db_i}{dt} = 2(a_i^2 - a_{i-1}^2)$$

Set L as a tridiagonal matrix

$$L = \begin{pmatrix} b_{1} & a_{1} & 0 & \dots & 0 \\ a_{1} & b_{2} & a_{2} & 0 & \vdots \\ 0 & a_{2} & b_{3} & a_{3} & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots \end{pmatrix} \qquad M = L_{+} - L_{-} = \begin{pmatrix} 0 & a_{1} & 0 & \dots & 0 \\ -a_{1} & 0 & a_{2} & 0 & \vdots \\ 0 & -a_{2} & 0 & a_{3} & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots \end{pmatrix}$$

▷ Proposition

Lax equation $\frac{dL}{dt} = [M, L]$ reproduces the open Toda lattice EOM.

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

Example at N = 3

$$\mathbb{P} \ \ L = \begin{pmatrix} b_1 & a_1 & 0 \\ a_1 & b_2 & a_2 \\ 0 & a_2 & b_3 \end{pmatrix}, M = \begin{pmatrix} 0 & a_1 & 0 \\ -a_1 & 0 & a_2 \\ 0 & -a_2 & 0 \end{pmatrix}$$
$$ML = \begin{pmatrix} 0 & a_1 & 0 \\ -a_1 & 0 & a_2 \\ 0 & -a_2 & 0 \end{pmatrix} \begin{pmatrix} b_1 & a_1 & 0 \\ a_1 & b_2 & a_2 \\ 0 & a_2 & b_3 \end{pmatrix} = \begin{pmatrix} a_1^2 & a_1 b_2 & a_1 a_2 \\ -a_1 b_1 & -a_1^2 + a_2^2 & a_2 b_3 \\ -a_1 a_2 & -a_2 b_2 & -a_2^2 \end{pmatrix}$$
$$LM = \begin{pmatrix} b_1 & a_1 & 0 \\ a_1 & b_2 & a_2 \\ 0 & a_2 & b_3 \end{pmatrix} \begin{pmatrix} 0 & a_1 & 0 \\ -a_1 & 0 & a_2 \\ 0 & -a_2 & 0 \end{pmatrix} = \begin{pmatrix} -a_1^2 & a_1 b_1 & a_1 a_2 \\ -a_1 b_2 & a_1^2 - a_2^2 & a_2 b_2 \\ -a_1 a_2 & -a_2 b_3 & a_2^2 \end{pmatrix}$$

▷ Hence

$$[M, L] = \begin{pmatrix} 2a_1^2 & a_1(b_2 - b_1) & 0\\ a_1(b_2 - b_1) & 2(a_2^2 - a_1^2) & a_2(b_3 - b_2)\\ 0 & a_2(b_3 - b_2) & -2a_2^2 \end{pmatrix}$$

Toda flows

- ▷ L tridiagonal, M = skew(L)
- \triangleright *M* "generates" the time evolution. Do other time evolutions exist?
- ▷ Consider $M_k = \text{skew}(L^k)$ and the "evolution equation" for L tridiagonal

$$rac{\partial L}{\partial t_k} = [M_k, L] \quad ext{for } k = 1, \dots, N$$

 $\triangleright t = t_1$ original time

▷ Are they consistent with one another?

$$\frac{\partial^2 L}{\partial t_l \partial t_k} = \frac{\partial^2 L}{\partial t_k \partial t_l} \quad \Leftrightarrow \quad \left[L, \frac{\partial M_k}{\partial t_l} - \frac{\partial M_l}{\partial t_k} + [M_k, M_l]\right] = 0$$

$$\triangleright \text{ Here for } M_k = \text{skew}(L^k)$$

$$\frac{\partial M_k}{\partial t_l} - \frac{\partial M_l}{\partial t_k} + [M_k, M_l] = 0$$

Toda flows

- ▷ L tridiagonal, M = skew(L)
- \triangleright *M* "generates" the time evolution. Do other time evolutions exist?
- ▷ Consider $M_k = \text{skew}(L^k)$ and the "evolution equation" for L tridiagonal

$$rac{\partial L}{\partial t_k} = [M_k, L] \quad ext{for } k = 1, \dots, N$$

- $\triangleright t = t_1$ original time
- Given a solution to the original system, flow with respect to the other times to generate other solutions
- \triangleright The I_k are conserved with respect to all Toda times
- ▷ Are the $I_k = tr(L^k)$ independent?
- ▷ If all $a_i = 0$, then the I_k are power-sums

$$I_k = \sum_{i=1}^N b_i^k$$

▷ Write the solutions "simply" in terms of the conserved quantities

With PDEs now

- ▷ Shift paradigm from conserved quantities to symmetries
- \triangleright Conserved quantities: sum over particles \rightarrow integrals
- \triangleright Example: advection equation (describes propagation at speed c)

$$\frac{\partial u(x,t)}{\partial t} + c \frac{\partial u(x,t)}{\partial t} = 0$$

 \triangleright Conserved quantities (assuming finitess) for $n\geq 1$

$$\frac{d}{dt} \int u(x,t)^n dx = 0$$

- ▷ How about formal power series?
- ▷ Use the notion of symmetry/infinitesimal transformation

$$rac{\partial L}{\partial t_k} = [M_k, L] \quad ext{ for } k \geq 1$$

 \triangleright Let $u \equiv u(t, x)$ satisfying the KdV equation

$$\frac{\partial u}{\partial t} = 6u\frac{\partial u}{\partial x} - \frac{\partial^3 u}{\partial x^3}$$

▷ KdV hierarchy is an infinite set of non-linear, consistent PDEs for $u \equiv u(t, x, x_1, x_3, x_5, ...)$

$$\frac{\partial u}{\partial x_k} = K_k[u], \qquad \frac{\partial K_k[u]}{\partial x_l} = \frac{\partial K_l[u]}{\partial x_k}$$

 $\triangleright \ {\cal K}_1[u]=(\partial u) \ {\rm with} \ \partial\equiv \frac{\partial}{\partial x} \ {\rm so} \ x_1 \ {\rm is \ identified \ with} \ x$

 \triangleright $K_3[u] = 6u(\partial u) - (\partial^3 u)$ so x_3 is identified with t

$$\triangleright \ K_5[u] = 10u(\partial^3 u) - 20(\partial u)(\partial^2 u) - 30u^2(\partial u) - (\partial^5 u)$$

Infinite set of commuting symmetries

- ▷ Lax representation using pseudo-differential operators
- Example in combinatorics: Kontsevich-Witten's intersection numbers on moduli space of Riemann surfaces

Pseudo-differential operators

- \triangleright Let R be an algebra of functions of x, stable under derivatives
- \triangleright Typically for us $R = \mathbb{Q}[x, x_1, x_2, x_3, \dots][[t]]$ (not very typical in integrable systems though)
- ▷ Consider the algebra $R[\partial]$, product being defined via the usual $\partial f = (\partial f) + f \partial$
- ▷ Consider the symbol ∂^{-1} defined by

$$\partial^{-1}\partial = \partial\partial^{-1} = 1, \qquad \partial^{-1}f = \sum_{i=0}^{\infty} (-1)^{i} (\partial^{i}f)\partial^{-i-1}$$
$$\partial^{-1}c = c\partial^{-1} \qquad \partial^{-1}x = x\partial^{-1} - \partial^{-2}$$
$$\partial^{-1}x^{2} = x^{2}\partial^{-1} - 2x\partial^{-2} + 2\partial^{-3}$$
Consider $R((\partial^{-1}))$, formal Laurent series in ∂^{-1}
$$A = \sum a_{i}(x)\partial^{m-i}$$

▷ It is an associative algebra and

$$\partial^k f = \sum_{i \ge 0} \binom{k}{i} (\partial^i f) \partial^{k-i}$$

Monic elements are invertible

$$A = \partial^m + \sum_{i \ge 1} a_i(x) \partial^{m-i}, \qquad A^{-1} = \partial^{-m} + \sum_{j \ge 1} \overline{a}_j(x) \partial^{-m-j}$$

then $A^{-1}A = 1$ gives

$$A^{-1}A = \sum_{i,j,l \ge 0} \binom{-m-i}{l} \bar{a}_i(x)(\partial^l a_j(x))\partial^{-i-j-l}$$

hence $ar{a}_1 = -a_1$, $ar{a}_2 = a_1^2 - a_2 + m(\partial a_1)$

 \triangleright More generally, set degrees as deg $a_i = \deg \bar{a}_i = \deg \partial^i = i$

$$ar{a}_i = -a_i + ext{diff. pol}_i(a_1, ar{a}_1, \dots, a_{i-1}, ar{a}_{i-1}) \ = -a_i + p_i(a_1, \dots, a_{i-1}, (\partial a_1), \dots)$$

 $\triangleright \ G = 1 + igoplus_{n \geq 1} R \partial^{-n}$ is a group

 \triangleright Monic elements of degree *m* have *m*-th roots. Set

$$B = \partial + \sum_{i \ge 1} b_i \partial^{1-i}$$

then
$$B^2 = \partial^2 + 2b_1 \partial + (2b_2 + b_1^2 + \partial b_1) + (2b_3 + 2b_1b_2 + \partial b_2)\partial^{-1} + \cdots$$

If $A = B^2$, then

$$a_i = 2b_i + \text{diff. pol}_i(b_1, \dots, b_{i-1})$$

 $2b_i = a_i + p'_i(a_1, \dots, a_{i-1}, (\partial a_1), \dots)$

 \triangleright Example $A = \partial^2 + \sum_{i \ge 1} a_i(x) \partial^{2-i}$

 \triangleright

$$A^{\frac{1}{2}} = \partial + \frac{a_1}{2} + \left(a_2 - \frac{a_1^2}{4} - \frac{(\partial a_1)}{2}\right)\frac{\partial^{-1}}{2} + \left(a_3 - \frac{a_1a_2}{2} + \frac{a_1^3}{8} + \frac{a_1\partial a_1}{2} - \frac{\partial a_2}{2} + \frac{(\partial^2 a_1)}{4}\right)\frac{\partial^{-2}}{2} + \cdots$$

Back to KdV

▷ Lax pair for KdV lives on $R((\partial^{-1}))$. Let $u \in R$

$$L = \partial^2 + u, \qquad M_k = (L^{k/2})_+$$

where M_+ is the differential part.

▶ Let us go directly to KP....

 $\triangleright~L^{1/2} = (\partial^2 + u)^{1/2}$ as a series in ∂^{-1}

$$egin{aligned} \mathcal{L}^{1/2} &= \partial + \sum_{i=1}^\infty b_i \partial^{-i+1} \ &= \partial + rac{u}{2} \partial^{-1} - rac{1}{4} (\partial u) \partial^{-2} + rac{1}{8} ((\partial^2 u) - u^2) \partial^{-3} + \mathcal{O}(\partial^{-5}) \end{aligned}$$

Gives

$$L_{+}^{1/2} = \partial, \quad L_{+}^{3/2} = \partial^{3} + \frac{3}{2}u\partial + \frac{3}{4}(\partial u)$$

- Prove that the symmetries commute!
- ▷ Express all derivatives $\frac{\partial u}{\partial x_k}$ wrt x_k as polynomials in $u, (\partial u), (\partial^2 u), \ldots$

Kadomtsev-Petviashvili (KP) hierarchy

▷ This is where things get a little dicey... For $i \ge 2$, let $q_i \equiv q_i(x, x_1, x_2, ...) \in R$ and

$$L = \partial + \sum_{i \ge 1} q_{i+1} \partial^{-i}, \qquad \frac{\partial L}{\partial x_k} := \sum_{i \ge 1} \frac{\partial q_{i+1}}{\partial x_k} \partial^{-i} = [(L^k)_+, L]$$

which means

$$\frac{\partial q_{i+1}}{\partial x_k} = [\partial^{-i}][(L^k)_+, L]$$

 \triangleright Example: $(L^1)_+ = \partial$ then

$$rac{\partial L}{\partial x_1} = [L_+, L] = [\partial, L] = \sum_{i \geq 1} (\partial q_{i+1}) \partial^{-i} \; \Rightarrow \; rac{\partial q_{i+1}}{\partial x_1} = (\partial q_{i+1})$$

identifies x_1 with x

 \triangleright Evolution with respect to x_2 and x_3

 $(L^2)_+ = \partial^2 + 2q_2, \quad (L^3)_+ = \partial^3 + 3q_2\partial + 3(\partial q_2) + 3q_3$

 \triangleright In general $(L^i)_+ = \partial^j + j q_2 \partial^{j-2} + \mathcal{O}(\partial^{j-3})$

 \triangleright Evolution with respect to x_2

$$rac{\partial q_2}{\partial x_2} = \partial^2 q_2 + 2\partial q_3, \quad rac{\partial q_3}{\partial x_2} = \partial^2 q_3 + 2\partial q_4 + 2q_2\partial q_2$$

 \triangleright Evolution with respect to x_3

$$\frac{\partial q_2}{\partial x_3} = \partial^3 q_2 + 3\partial^2 q_3 + 3\partial q_4 + 6q_2\partial q_2$$

▷ Set degrees as deg ∂ = 1, deg q_i = i
 ▷ Then ∂q_i/∂x_j is homogeneous of degree i + j
 ∂q_i/∂x_j = homogeneous polynomial of degree i + j, in (∂^kq_l)
 = g_{i < j} + j∂q_{i+j-1}
 + homogeneous polynomial of degree i + j, in (∂^kq_l) with l < i + j - 1
 ▷ Please someone help generate them!

 \triangleright Evolution with respect to x_2

$$\frac{\partial q_2}{\partial x_2} = 2\partial q_3 + \partial^2 q_2, \quad \frac{\partial q_3}{\partial x_2} = 2\partial q_4 + \partial^2 q_3 + 2q_2\partial q_2$$

▷ Evolution with respect to x₃

$$\frac{\partial q_2}{\partial x_3} = 3\partial q_4 + 3\partial^2 q_3 + \partial^3 q_2 + 6q_2\partial q_2$$

▷ Look at $\frac{\partial^2 q_2}{\partial x_2^2}$

$$\frac{\partial^2 q_2}{\partial x_2^2} = 4\partial^2 q_4 + 4\partial^3 q_3 + \partial^4 q_2 + 4\partial(q_2\partial q_2)$$

▷ Eliminate $4\partial^2 q_4 + 4\partial^3 q_3$ using $\frac{\partial^2 q_2}{\partial x_3 \partial x_1}$ ▷ Let $u := -2q_2$, then this is the KP equation

$$3\frac{\partial^2 u}{\partial x_2^2} = \frac{\partial}{\partial x_1} \left(4\frac{\partial u}{\partial x_3} + 6u\frac{\partial u}{\partial x_1} - \frac{\partial^3 u}{\partial x_1^3} \right)$$

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

▷ Want to prove

$$\frac{\partial M_i}{\partial x_j} - \frac{\partial M_j}{\partial x_i} + [M_j, M_i] = 0 \quad \text{for } M_i = (L^i)_+$$

▷ For all polynomials P, $\frac{\partial P(L)}{\partial x_k} = [(L^k)_+, P(L)]$. Then

$$\frac{\partial (L^k)_+}{\partial x_l} = \left(\frac{\partial L^k}{\partial x_l}\right)_+ = [(L')_+, L^k]_+$$

so that

$$\frac{\partial(L^i)_+}{\partial x_j} - \frac{\partial(L^j)_+}{\partial x_i} = [(L^j)_+, L^j]_+ + [L^j, (L^i)_+]_+$$

▷ Use
$$L^{i} = (L^{i})_{+} + (L^{i})_{-}$$

$$\frac{\partial(L^{i})_{+}}{\partial x_{j}} - \frac{\partial(L^{j})_{+}}{\partial x_{i}} = [(L^{j})_{+}, (L^{i})_{+}]_{+} + [(L^{j})_{+}, (L^{i})_{-}]_{+} + [L^{j}, (L^{i})_{+}]_{+}$$

$$= [(L^{j})_{+}, (L^{i})_{+}] + [(L^{j})_{+}, (L^{i})_{-}]_{+} - [L^{j}, (L^{i})_{-}]_{+}$$

$$= [(L^{j})_{+}, (L^{i})_{+}] + [(L^{j})_{-}, (L^{i})_{-}]_{+}$$

$$= [(L^{j})_{+}, (L^{i})_{+}]$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

Wave function

▷ Let $\Phi \in R((\partial^{-1}))$ such that

$$L = \Phi \partial \Phi^{-1}, \qquad \Phi = 1 + \sum_{i \geq 1} w_i \partial^{-i}$$

called a dressing transformation

▷ This gives

$$q_{i+1} = (\partial w_i) + \mathsf{diff.} \hspace{0.1 in} \mathsf{pol}_i(w_1, \ldots, w_{i-1})$$

- $\triangleright \ L$ determines Φ up to $\Phi
 ightarrow \Phi C$ with $C = 1 + \sum_{i \geq 1} c_i \partial^{-i}$
- \triangleright KP-flows for Φ

$$\frac{\partial \Phi}{\partial x_i} = -(L^i)_- \Phi$$

- ▷ Extract $[\partial^{-j}]$ to get $\frac{\partial w_j}{\partial x_i}$
- ▷ It is a homogeneous polynomial of degree i + j in $(\partial^k w_l)$

$$\frac{\partial w_j}{\partial x_i} = w_{i+j} + a(\partial w_{i+j-1}) + bw_1 w_{i+j-1} + \cdots$$

Tau functions and generating series

 \triangleright Sato's formula There exists a function $au(x_1, x_2, \dots) \in R$ such that

$$\psi(z) \coloneqq 1 + \sum_{i \ge 1} w_i z^{-i} = \frac{\tau(x_1 - z^{-1}, x_2 - z^{-2}, x_3 - z^{-3}, \dots)}{\tau(x_1, x_2, x_3, \dots)}$$

z-dependence is related to x_i -dependences

 \triangleright Write log $\psi(z) = \sum_{i \geq 1} \gamma_i z^{-i}$ then

$$rac{\partial \log \tau}{\partial x_i} = -i\gamma_i - \sum_{j=1}^{i-1} rac{\partial \gamma_{i-j}}{\partial x_j}$$

- \triangleright Consistent definition of au thanks to the KP flows
- $ho\,$ Still leaves some constraints on au
- $\begin{tabular}{ll} \hline \hline Thm (in which space?) \\ \Phi \ satisfies the KP flows iff τ satisfies Hirota's bilinear equations. \end{tabular}$

Consider two sets of indeterminates $x_1, y_1, x_2, y_2, \ldots$

 $[z^{-1}]e^{-2\sum_{i\geq 1}\frac{z^{i}}{i}y_{i}}e^{\sum_{i\geq 1}z^{-i}\frac{\partial}{\partial y_{i}}}\tau(x_{1}-y_{1},x_{2}-y_{2},\dots)\tau(x_{1}+y_{1},x_{2}+y_{2},\dots)=0$

 \triangleright Looks non-local (translations by y_i and z^i)

 \triangleright Extract coefficients w.r.t. y_1, y_2, \ldots gives a finite number of derivatives

$$[y_3] [z^{-1}] e^{-2\sum_{i\geq 1} \frac{z^i}{r} y_i} e^{\sum_{i\geq 1} z^{-i} \frac{\partial}{\partial y_i}} \tau(x_1+y_1, x_2+y_2, \dots) \tau(x_1-y_1, x_2-y_2, \dots)}$$

= $\left(\frac{\partial^4}{\partial u_1^4} + 3\frac{\partial^2}{\partial u_2^2} - 4\frac{\partial^2}{\partial u_1\partial u_3}\right) \tau(x_1+u_1, x_2+u_2, \dots) \tau(x_1-u_1, x_2-u_2, \dots)|_{u_1=u_2=\dots=0}$

▷ Set $u = 2 \frac{\partial^2}{\partial x_i^2} \log \tau$ to recover the KP equation

 \triangleright The other two equations I showed before are from $[y_4]$ and $[y_5]$.

- \triangleright In general, extract $[y_{\lambda_1}y_{\lambda_2}\cdots]$ \rightarrow partitions
- ▷ Question: How come that they are quadratic while the KP flows are not?

$$[z^{-1}]e^{-2\sum_{i\geq 1}\frac{z^{i}}{r}y_{i}}e^{\sum_{i\geq 1}z^{-i}\frac{\partial}{\partial y_{i}}}\tau(x_{1}-y_{1},x_{2}-y_{2},\dots)\tau(x_{1}+y_{1},x_{2}+y_{2},\dots)$$

▷ Set
$$p_i = x_i + y_i, q_i = x_i - y_i,$$

$$[z^{-1}]e^{\sum_{i\geq 1} \frac{z^i}{r}(q_i - p_i)}\tau(q_1 - z^{-1}, q_2 - z^{-2}, \dots)\tau(p_1 + z^{-1}, p_2 + z^{-2}, \dots)$$

$$\sim [z^{-1}]\psi(z, q_1, q_2, \dots)e^{\sum_{i\geq 1} \frac{z^i}{r}q_i}\psi^*(z, p_1, p_2, \dots)e^{-\sum_{i\geq 1} \frac{z^i}{r}p_i}$$

$$\triangleright \text{ The function } \Psi \equiv \psi(z, q_1, q_2, \dots)e^{\sum_{i\geq 1} \frac{z^i}{r}q_i} \text{ satisfies } \frac{\partial\Psi}{\partial x_i} = (L^i)_+\Psi$$

▷ It is enough to check

$$[z^{-1}]\partial^i \left(\psi(z)e^{\sum_{i\geq 1}\frac{z^i}{i}q_i}\right)\psi^*(z)e^{-\sum_{i\geq 1}\frac{z^i}{i}p_i}=0$$

From KP flows to Hirota

▷ It is enough to check

$$[z^{-1}]\partial^i \left(\psi(z)e^{\sum_{i\geq 1}\frac{z^i}{i}q_i}\right)\psi^*(z)e^{-\sum_{i\geq 1}\frac{z^i}{i}p_i}=0$$

▷ How to transform this into pseudo-differential operators?

- $\triangleright \ \, {\sf Define} \ \, \partial^{-k} \cdot e^{xz} = z^{-k} e^{xz}, \ {\sf then} \ \, \partial^i(\psi(z)e^{xz}) = (\partial^i\Phi) \cdot e^{xz}$
- \triangleright Moreover, define the antihomomorphism * by $(a(x)\partial^{i})^{*} = (-\partial)^{i}a(x)$, then

$$[z^{-1}]\left(\sum_{i}\alpha_{i}z^{i}\right)\left(\sum_{j}\beta_{j}(-z)^{j}\right) = [\partial^{-1}]\left(\sum_{i}\alpha_{i}z^{i}\right)\left(\sum_{j}\beta_{j}z^{i}\right)^{*}$$

▶ Eventually

$$[z^{-1}]\partial^{i}\left(\psi(z)e^{\sum_{i\geq 1}\frac{z^{i}}{i}q_{i}}\right)\psi^{*}(z)e^{-\sum_{i\geq 1}\frac{z^{i}}{i}p_{i}}=[\partial^{-1}]\partial^{i}\Phi\Phi^{-1}=0$$

- ▷ Where are our generating series? If I give you a combinatorial problem, how do you may find the KP hierarchy?
- Desting the KP equation is a good start
- ▷ The Japanese school came with new objects and a new point of view!
- $\triangleright\,$ There exists a geometric approach to τ which in practice is useful to prove KP

Grassmanianns in finite dimensions

▷ Consider Gr(k, n) the set of k-dimensional vector spaces in \mathbb{C}^n like

 $P(v_1,\ldots,v_k) = \operatorname{span}(v_1,\ldots,v_k)$ for k linearly indpt vectors

- \triangleright Recall the exterior product $v_1 \wedge v_2 = v_1 \otimes v_2 v_2 \otimes v_1 \in \mathbb{C} \otimes \mathbb{C}$
- \triangleright It is non-zero iff v_1 and v_2 are linearly independent
- \triangleright Think of elements of Gr(k, n) via the map

 $\Sigma: P(v_1,\ldots,v_k) \rightarrow [v_1 \wedge v_2 \wedge \cdots \wedge v_k] \in \mathbb{P}\Lambda^k \mathbb{C}^n$

 $\triangleright \mathsf{E.g.} v_1 \wedge (v_2 + v_1) \wedge \cdots \wedge v_k = v_1 \wedge v_2 \wedge \cdots \wedge v_k$

- ▷ How to identify $Gr(k, n) \subset \mathbb{P}\Lambda^k \mathbb{C}^n$? Plücker embedding
- ▷ Notice that if $v \in P(v_1, ..., v_k)$ then

$$v \wedge (v_1 \wedge v_2 \wedge \cdots \wedge v_k) = 0$$

▷ If $u \in P(v_1, \ldots, v_k)^\perp$ then

$$\iota_u(v_1 \wedge v_2 \wedge \cdots \wedge v_k) = 0$$

where $\iota_u v_1 \wedge v_2 \wedge \cdots = \langle u, v_1 \rangle v_2 \wedge \cdots - \langle u, v_2 \rangle v_1 \wedge \cdots + \cdots$

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

- ▷ Let (e_1, \ldots, e_n) be the can. basis of \mathbb{C}^n and denote $\psi_i w = e_i \land w$ and $\psi_i^* w = \iota_{e_i} w$
- ▷ Let $\omega \in \mathbb{P}\Lambda^k \mathbb{C}^n$. There exists $P \in Gr(k, n)$ such that $\omega = \Sigma(P)$ iff

$$\sum_{i=1}^n \psi_i \omega \otimes \psi_i^* \omega = 0$$

In coordinates, Plücker relations

▷ Representation of GL_n on $\mathbb{P}\Lambda^k \mathbb{C}^n$

$$\rho(A)(v_1 \wedge \cdots \wedge v_k) = (Av_1) \wedge (Av_2) \wedge \cdots \wedge (Av_k)$$

Extend linearly.

▷ Let $\omega \in \mathbb{P}\Lambda^k \mathbb{C}^n$. There exists $P \in Gr(k, n)$ such that $\omega = \Sigma(P)$ iff

$$\exists A \in GL_n \quad \omega = [\rho(A) \underbrace{(e_1 \wedge \cdots \wedge e_k)}_{\text{reference vector}}$$

i.e. ω is in the orbit of GL_n .

 \triangleright Consider $V=C^{\infty}=igoplus_{n\in\mathbb{Z}}\mathbb{C}$ and GL_{∞} its group of automorphisms

 $\textit{GL}_{\infty} = \{(\textit{a}_{ij})_{i,j \in \mathbb{Z}}, \text{invertible and only a finite number}$

of diagonal elements not 1 and off diag. not 0}

Plücker relations for Sato's Grassmaniann

$$\sum_{i\in\mathbb{Z}}\psi_i\omega\otimes\psi_i^*\omega=0$$

- \triangleright Equivalence between this and being in the orbit of a reference vector under GL_∞
- Correspondence boson-fermion maps

S: Sato's Grassmaniann $\rightarrow \mathbb{C}[x_1, x_2, \dots]$

and maps Plücker relations on ω to Hirota equations on au

 \triangleright Gives rise to the bosonic representation ρ_B of GL_∞ on $\mathbb{C}[x_1, x_2, \dots]$

$$S \circ \rho = \rho_B \circ S$$

▷ <u>Theorem</u> – $\tau \in \mathbb{C}[x_1, x_2, ...]$ satisfies the Hirota equations iff it comes from an element of GL_{∞}

$$\exists A \in GL_{\infty} \quad \tau(x_1, x_2, \dots) = \rho_B(A) \cdot 1$$

- \triangleright Extension to FPS in my HDR dissertation: $\overline{\textit{GL}_{\infty}} \rightarrow \text{KP}$
- \triangleright Prove KP in for a specific problem \leftarrow Find an element of $\overline{\mathit{GL}_{\infty}}$ as above
- ▷ In combinatorics, $\tau(x_1, x_2, ...)$ is a GF of objects which are connected or not and $F(x_1, x_2, ...) = \log \tau(x_1, x_2, ...)$ is the GF of same, connected objects
- $\triangleright \psi(z)$ is the GF of derivatives of F of fixed order

$$\psi(z) \coloneqq 1 + \sum_{i \ge 1} w_i z^{-i} = rac{ au(x_1 - z^{-1}, x_2 - z^{-2}, x_3 - z^{-3}, \dots)}{ au(x_1, x_2, x_3, \dots)} \in R[[z^{-1}]]$$

⊳ <u>Thm</u>

 $\tau(t, u, v, x_1, x_2, ...)$ of bipartite maps satisfies the bilinear Hirota equation. \triangleright What is $\psi(z)$? By Sato's formula

$$\psi(z) = \frac{\tau(t, u, v, x_1 - z^{-1}, x_2 - z^{-2}, \dots)}{\tau(t, u, v, x_1, x_2, \dots)}$$

= $\tau^{-1} e^{-\sum_{i \ge 1} z^{-i} \frac{\partial}{\partial x_i}} \tau$
= $\tau^{-1} \sum_{(\lambda_1 \ge \lambda_2 \ge \dots \ge \lambda_l)} (-1)^l \frac{z^{-\lambda_1 - \lambda_2 - \dots - \lambda_l}}{\text{Combi. factor}} x_{\lambda_1}^* x_{\lambda_2}^* \cdots x_{\lambda_l}^* \tau$

 \triangleright Turn the constraints into an equation on $\psi(z)$

$$L_{i}\tau = \left(-x_{i+1}^{*} + t\sum_{j+k=i} x_{j}^{*}x_{k}^{*} + t\sum_{j\geq 1} x_{j}x_{i+j}^{*} + t(u+v)x_{i}^{*} + tuv\delta_{i,0}\right)\tau = 0$$

▲□▶ ▲圖▶ ▲臣▶ ▲臣▶ ―臣 – のへ⊙

All genera equation aka quantum spectral curve

▷ Differential, or "quantum" version of the planar equation!

$$tzW(z)^{2} + \left(t\sum_{i=1}^{d} x_{i}z^{-i+1} + tz(u+v) - 1\right)W(z) + tuv$$
$$-t\sum_{i=2}^{d}\sum_{j=1}^{i-1} x_{j}z^{-(i-1-j)}x_{j}^{*}F^{(0)} = 0$$

 \triangleright The constraints $L_i au = 0$ for $i \ge 0$ give

$$z^{2}t\frac{d^{2}\psi}{dz^{2}} - \left(t\sum_{i=1}^{d}p_{i}z^{i+1} + tz(u+v-1) - z^{2}\right)\frac{d\psi}{dz} + tuv\psi - t\sum_{i=2}^{d}p_{i}\sum_{j=1}^{i-1}z^{i-j}(x_{j}^{*}\psi + \psi x_{j}^{*}F) = 0$$

▷ All genera version of the unknown series in Bousquet-Mélou-Jehanne

All genera equation aka quantum spectral curve

> Differential, or "quantum" version of the planar equation!

$$tzW(z)^{2} + \left(t\sum_{i=1}^{d} x_{i}z^{-i+1} + tz(u+v) - 1\right)W(z) + tuv$$
$$-t\sum_{i=2}^{d}\sum_{j=1}^{i-1} x_{j}z^{-(i-1-j)}x_{j}^{*}F^{(0)} = 0$$

▷ Then recursion for $i \ge 0$

$$(ti(i + u + v) + tuv)w_i + t\sum_{k=1}^{d} (k+i)x_k w_{k+i} - (i+1)w_{i+1}$$
$$- t\sum_{k=2}^{d} \sum_{j=1}^{k-1} x_k (x_j^* w_{k-j+i} + w_{k-j+i} x_j^* F) = 0$$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- ▷ Lemma $x_j^* w_{k-j+i}$ and $x_j^* F$ are polynomials in $\partial^m w_l$ of degree k + i and j respectively.
- ▷ Example: $F_2 = w_2 \frac{1}{2}(w_1^2 + (\partial w_1))$

Revisit the "trivial" case $x_k = x \delta_{k,2}$

$$2txw_{2} - w_{1} + tuv - tx(w_{1}^{2} + (\partial w_{1})) = 0$$

$$3txw_{3} + (t(u + v + 1) + tuv)w_{1} - 2w_{2} - tx(w_{1}w_{2} + (\partial w_{2})) = 0$$

$$(i + 1)txw_{i+1} + (t(i - 1)(u + v + i - 1) + tuv)w_{i-1} - iw_{i}$$

$$- tx(w_{i}w_{1} + (\partial w_{i})) = 0$$

▷ Express all w_i s for $i \ge 2$ as a polynomial in $w_1, \partial w_1, \partial^2 w_1, \ldots$

Take the flow

$$\frac{\partial w_2}{\partial x_2} = -[\partial^{-2}](\Phi \partial^2 \Phi^{-1})_- \Phi$$
$$= w_1(\partial^2 w_1) - w_1^2(\partial w_1) + (\partial^2 w_2) + 2(\partial w_3) - 2w_2(\partial w_1) + w_1 w_3$$

and replace all w_2, w_3 in terms of $w_1, (\partial w_1), \ldots$

- $\triangleright \text{ Take } \frac{\partial}{\partial x_2} \text{ of the first equation} \qquad 2tx \frac{\partial w_2}{\partial x_2} = 2tw_2 \frac{\partial w_1}{\partial x_2} + \cdots$
- ▷ Use the flow $\frac{\partial w_1}{\partial x_2} = (\partial^2 w_1) + 2(\partial w_2) 3w_1(\partial w_1)$ and the first equation to express everything in terms of $w_1, (\partial w_1), \ldots$
- ▷ Equating those two ways of evaluating $\frac{\partial w_2}{\partial x_2}$ produces an ODE of order 3 and degree 4.

Example: $x_k = x\delta_{k,3}$

$$\begin{aligned} 3txw_3 - w_1 - tx(\text{things in } w_1 \partial w_1, \partial^2 w_1, \partial w_2, w_1 w_2) &= 0 \\ 4txw_4 - 2w_2 + t(uv + u + v + 1)w_1 \\ &- tx((\partial w_3) + w_3w_1 + x_2^*w_2 + w_2(w_2 - \frac{1}{2}(w_1^2 + (\partial w_1)))) = 0 \end{aligned}$$

▷ (∂w₃), w₃ in the 2nd eq. are given by the first eq.
 ▷ Inductively all w₃, w₄, w₅,... are given as differential polynomials in w₁, w₂
 ▷ Take x₂* of first eq.

$$3txx_2^*w_3 \underset{\mathsf{KP}}{=} 2(\partial w_4) + 2(\partial^2 w_3) + \ldots = 2\frac{\partial w_1}{\partial x_2} + \cdots$$

 \triangleright Take x_3^* of first eq. $x_3^*w_3 = (\partial w_5) + \dots$

$$3txx_3^*w_3 = 3(\partial w_5) + \ldots = 3\frac{\partial w_1}{\partial x_3} + \cdots$$

 \triangleright This gives an infinite number of equations involving $\partial^k w_1, \partial^l w_2$ only

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへ⊙

Conclusion

- ▷ KP flows as a tool for some combinatorial systems
- ▷ Infinite number of commuting symmetries, generated by a Lax pair
- > Application to maps still w.i.p., devise general algorithm
- Close the Virasoro constraints which have growing number of derivatives using KP flows which are homogeneous
- ▷ All genera analog of the unknown series of BMJ, with diff. eq. instead of algebraic
- ▷ Did not find a handbook of KP flows, nor a program writing the equations
- > Other systems?
- \triangleright Maps decorated with the Ising model \rightarrow M. Albenque's talk!
- ▷ Revisit some "old" (Tutte's) recurrence for *q*-properly colored *planar* maps

$$q(n+1)(n+2)h_{n+2} = q(q-4)(3n-1)(3n-2)h_{n+1} + 2\sum_{i=1}^{n} i(i+1)(3n-3i+1)h_{i+1}h_{n+2-i}$$

- > Lax pair with spectral parameter: rational function with matrix coefficients
- ▷ How to identify systems satisfying KP?
- Reduction of KP to more specific hierarchies like KdV, Boussinesq, etc. (combinatorial examples?)

- ▷ *B*-type for non-oriented maps [VB-Chapuy-Dołęga]
- ▷ Modern works on (q, t)-deformation, etc.