# First-Order Factors of Linear Mahler Operators

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Ínnía -

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Joint work with Th. Dreyfus, Ph. Dumas, and M. Mezzarobba

In dedication to Marko Petkovšek.

### Linear Mahler Operators and Mahler Function

#### Linear Mahler equation

$$\ell_r(x)y(x^{b^r}) + \dots + \ell_1(x)y(x^b) + \ell_0(x)y(x) = 0$$
 (L)

for a *radix*  $b \in \mathbb{N}_{\geq 2}$ , an *order*  $r \in \mathbb{N}_{\geq 0}$ , rational functions  $\ell_i \in \overline{\mathbb{Q}}(x)$ .

#### **Operator notation**

In the skew algebra  $\overline{\mathbb{Q}}(x)\langle M \rangle$  where  $Mx = x^b M$ , write

$$L := \ell_r(x)M^r + \cdots + \ell_1(x)M + \ell_0(x).$$

Action:  $My(x) = y(x^b)$ . (L)  $\Leftrightarrow Ly(x) = 0$ .

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# $\rightarrow$ Transcendence theory, Automata theory, "Divide-and-conquer" recurrences, Difference Galois theory, Computer algebra.

Mahler, Cobham, Christol, Kamae, Mendès France, Rauzy, Loxton, v. d. Poorten, Nishioka, Allouche, Shallit, Becker, Dumas, Bell, Coons, Philippon, Adamczewski, Faverjon, Dreyfus, Hardouin, Roques, Smertnig, ...

### Mahler-Hypergeometric Solutions and First-Order Factors

Mahler-Hypergeometric functions (w.r.t. a given base *b*)

The function y is *Mahler* if it satisfies some (L) of any order, *hypergeometric* if it satisfies some (L) of order 1.

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#### Problem

Given some skew polynomial L = L(x, M), several equivalent formulations:

• Find all hypergeometric solutions y of the linear Mahler equation

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- Find all first-order right-hand factors M u of L for  $u \in \overline{\mathbb{Q}}(x)$ .
- Find all rational solutions *u* of the Riccati Mahler equation

$$\ell_r(x)u(x)\cdots u(x^{b^{r-1}}) + \cdots + \ell_2(x)u(x)u(x^b) + \ell_1(x)u(x) + \ell_0(x) = 0.$$
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$$u = \frac{My}{y}$$
. Ihs of (R) = remainder in division of *L* by  $M - u$ .

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 (R)

 $u = \frac{My}{v}$ . Ihs of (R) = remainder in division of L by M - u.

We provide algorithms following two algorithmic approaches.

- Motivating examples
- First approach: generalizing Petkovšek's algorithm
- An effective difference algebra for solutions
- Second approach: structured Hermite-Padé approximants
- Comparison of the approaches and Application to hypertranscendence

# Part I

# **Motivating Examples**

## Paradigmatic Examples of Mahler Series

Thue–Morse sequence over the alphabet  $\{-1, 1\}$ 

$$y(x) = \prod_{j\geq 0} (1-x^{2^j})$$

fixpoint of the morphism  $a 
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Stern-Brocot sequence

(2-regular but not 2-automatic)

(2-automatic)

$$y(x) = \prod_{j \ge 0} (1 + x^{2^{j}} + x^{2^{j+1}})$$

explicit bijection  $\mathbb{N} \simeq \mathbb{Q}_{\geq 0}$ :  $n \mapsto [x^n]y/[x^{n+1}]y$ 

(2-Mahler but not 2-regular)

$$y(x)^{-1} = \prod_{j\geq 0} (1-x^{2^j})^{-1}$$

expressions of  $n \in \mathbb{N}$  in the form  $n = n_0 + n_1 2 + n_2 2^2 + \cdots$  where  $n_i \in \mathbb{N}$ 

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$$y(x)^{-1} = \prod_{j\geq 0} (1-x^{2^j})^{-1} \longrightarrow u(x) = 1-x$$

expressions of  $n \in \mathbb{N}$  in the form  $n = n_0 + n_1 2 + n_2 2^2 + \cdots$  where  $n_i \in \mathbb{N}$ 

### **Ramified Mahler-Hypergeometric Solutions**

Hypergeometric = infinite product + log-factor + a ramification order

$$y := (\ln x)^{\log_3 \lambda} x^{1/2} \prod_{k \ge 0} \frac{1 - 7x^{3^k}}{1 + 2x^{3^k}} \qquad (b = 3)$$

is annihilated by

$$\begin{split} L &:= (1 - 7x^3)M^2 + (2x - 14x^2 - \lambda x^3 - 2\lambda x^6)M + 2\lambda x^2(1 + 2x) \\ &= (M - 2x)\left((1 - 7x)M - \lambda x(1 + 2x)\right). \end{split}$$

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#### Linear equations with no ramification can need ramification to be solved. A ramified y with unramified u = My/y is possible.

## **Disproving Hypergeometricity**

Missing digit in ternary expansion (OEIS A005836)

 $L := 3(1 + x^2)^2 M^2 - (1 + 3x + 4x^2)M + x$  for b = 2 annihilates

$$y(x) := \sum_{n \ge 0} (n \text{-th positive integer written without 2 in base 3}) x^n$$
$$= 1x^1 + 3x^2 + 4x^3 + 9x^4 + 10x^5 + \cdots$$

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Unique monic right-hand first-order factor is  $M - \frac{1}{3(1+x)}$ 

$$\Rightarrow$$
 all hypergeometric solutions in  $\bar{\mathbb{Q}} \frac{(\ln x)^{\log_2(1/3)}}{1-x}$ 

 $\Rightarrow$  y(x) is not hypergeometric.

### Parametrized Mahler-Hypergeometric Solutions

Remember the differential case, 
$$D = \frac{d}{dx}$$
:  
 $Dx = xD + 1 \implies \forall r, D^2 = \left(D + \frac{1}{x+r}\right)\left(D - \frac{1}{x+r}\right),$   
in relation to:  $\bar{\mathbb{Q}} x \oplus \bar{\mathbb{Q}} 1 = \bigcup_{r \in \bar{\mathbb{Q}}} \bar{\mathbb{Q}} (x+r).$ 

### Parametrized Mahler-Hypergeometric Solutions

#### Parities of digit repetitions in ternary expansion

Adamczewski and Faverjon (2017) introduce

$$S_{a} := \left\{ n \mid \text{even number of } a \text{'s in ternary expansion of } n \right\}, \quad a = 1, 2,$$
  

$$y_{1}(x) := \sum_{n \in S_{1} \cap S_{2}} x^{n}, \quad y_{2}(x) := \sum_{n \in \tilde{S}_{1} \cap S_{2}} x^{n}, \quad y_{3}(x) := \sum_{n \in S_{1} \cap \tilde{S}_{2}} x^{n}, \quad y_{4}(x) := \sum_{n \in \tilde{S}_{1} \cap \tilde{S}_{2}} x^{n}$$
  
and show  

$$\boldsymbol{y}(x) = A(x)\boldsymbol{y}(x^{3}) \quad \text{for} \quad \boldsymbol{y}(x) = \begin{pmatrix} y_{1}(x) \\ y_{2}(x) \\ y_{3}(x) \\ y_{4}(x) \end{pmatrix}, \quad A(x) = \begin{pmatrix} 1 & x & 0 & x^{2} \\ x & 1 & x^{2} & 0 \\ 0 & x^{2} & 1 & x \\ x^{2} & 0 & x & 1 \end{pmatrix}.$$

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- ightarrow Common linear Mahler equation: order 4, degree 258.
- $\rightarrow$  Hypergeometric solutions correspond to a ratio u among

$$\frac{1}{1-x-x^2}, \quad \frac{1}{1+x-x^2}, \quad \frac{g_1+g_2x^3}{g_1+g_2x}\frac{1}{1+x^2+x^4} \text{ for } (g_1:g_2) \in \mathbb{P}^1(\bar{\mathbb{Q}}).$$

None of the  $y_i$  is hypergeometric.

# Part II

# First Approach: Generalizing Petkovšek's Algorithm

# Classical Algorithms by Gosper–Petkovšek Forms

#### shift $x \mapsto x + 1$ (Petkovšek, 1992) $u(x) = \eta \frac{C(x+1)}{C(x)} \frac{A(x)}{B(x)}$ + coprimality constraints *q*-shift $x \mapsto qx$ (Abramov, Paule, Petkovšek, 1998) $u(x) = \eta \frac{C(qx)}{C(x)} \frac{A(x)}{B(x)}$ + coprimality constraints Mahler (order 2) (Roques, 2018) $u(x^{b}) = \eta \frac{C(x^{b})}{C(x)} \frac{A(x)}{B(x)}$ + coprimality constraints

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#### All those algorithms:

- iterate on factors of A of  $\ell_0$  and B of  $\ell_r$  (or slight variations),
- determine a polynomial equation on  $\eta$  + a degree bound on C,
- solve an auxiliary linear functional equation for C.

$$\sum_{i=0}^{r} \ell_i(x) \prod_{j=0}^{i-1} u(x^{b^i}) = 0$$

Bounded Gosper–Petkovšek forms (exist for any  $u \in \mathbb{C}(x)$ )

$$\begin{cases} x = t^{b^{r-1}} \\ u(t^{b^{r-1}}) = \eta \frac{C(t^b)}{C(t)} \frac{A(t^{b^{r-1}})}{B(t)} \end{cases} \begin{cases} \gcd(A(t^{b^{r-1}}), C(t)) = \gcd(B(t), C(t^b)) = 1 \\ \gcd(A(t^{b^i}), B(t)) = 1 \\ \gcd(A(t^b)) = \gcd(C(t), C(t^b)) = 1 \end{cases}$$

1}

$$\sum_{i=0}^{r} \ell_i(t^{b^{r-1}}) \, \eta^i \, C(t^{b^i}) \left( \prod_{j=0}^{i-1} A(t^{b^{r-1+j}}) \right) \left( \prod_{j=i}^{r-1} B(t^{b^j}) \right) = 0$$

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#### Sketch of new algorithm

- for all monic  $A(t) \mid \ell_0(t)$ , for all monic  $B(t) \mid \ell_r(t)$ :
  - determine potential degrees for C from the degrees of A, B,  $\ell_i$ ,
  - for all obtained candidate degrees:
    - extract the leading coefficient w.r.t. t and solve as an equation in  $\eta$ ,
    - for all candidates  $\eta$ , solve equation for C by linear algebra;
- return  $(\eta, A(t), B(t), C(t))$  after removing redundancy.

$$\sum_{i=0}^{r} \ell_i(t^{b^{r-1}}) \eta^i C(t^{b^i}) \left(\prod_{j=0}^{i-1} A(t^{b^{r-1+j}})\right) \left(\prod_{j=i}^{r-1} B(t^{b^j})\right) = 0$$

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#### NB: parameters in $C \rightarrow$ continuous family of u.

# **Efficiency Improvements**

#### Pruning the set of (A, B)

- Factor  $\ell_0$  and  $\ell_r$  into irreducible.
- Some factors of one forbid other factors of the other.
- Iterate on tuples of exponents.

Removing repetitions in the found  $(\eta, A, B, C)$ 

Some (A, B) make other (A', B') useless.

Avoiding redundant computations of degree bounds for *C* 

Newton polygon for different (A, B) are related.

#### Taking degree bounds into account

When choosing (A, B), after getting potential degrees for C.

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Number of cases to test still exponential in the degrees of the  $\ell_i$ .

# Part III

# An Effective Difference Algebra for Solutions

### Where to Look for Solutions of the Linear Equation?

Field of Puiseux series: 
$$\mathcal{P} := \bigcup_{q \in \mathbb{N}_{\neq 0}} \overline{\mathbb{Q}}((x^{1/q})).$$
  
 $e_{\lambda} := (\ln x)^{\log_b \lambda}, \quad Me_{\lambda} = \lambda e_{\lambda}, \qquad \ell := \log_b \ln x, \quad M\ell = \ell + 1$   
 $e_{\lambda}e_{\lambda'} = e_{\lambda\lambda'}. \qquad (M-1)^2 \ell = 0.$ 

Regular singular Mahler systems (Roques, 2018)

 $\mathcal{U} := \mathcal{P}[(e_{\lambda})_{\lambda \in \bar{\mathbb{Q}}_{\neq 0}}, \ell]$  is a universal Picard–Vessiot ring for the regular singular Mahler systems over  $\mathcal{P}$ : "enough" solutions, same constants.

Field of Hahn series: 
$$\mathcal{H} := \left\{ f \in \bar{\mathbb{Q}}^{\mathbb{Q}} \mid \operatorname{supp} f \text{ is well-founded} \right\}.$$

#### Local structure of Mahler systems (Roques, 2016)

Solving general systems requires  $\mathcal{H}$  and solutions of all  $(M - \lambda)^k y = 0$ .

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Solving general systems requires  $\mathcal{H}$  and solutions of all  $(M - \lambda)^k y = 0$ .

Remark:  $(e_{\lambda} + e_{-\lambda})(e_{\lambda} - e_{-\lambda}) = 0$ , so  $\mathcal{U}$  cannot be a field.

# Structure of Hypergeometric Solutions

Write: 
$$\overline{\mathbb{Q}}((x^{1/*})) := \mathcal{P}, \quad \mathfrak{D} := \mathcal{P}[(e_{\lambda})_{\lambda \in \overline{\mathbb{Q}}_{\neq 0}}] = \bigoplus_{\lambda \in \overline{\mathbb{Q}}_{\neq 0}} (\ln x)^{\log_{b} \lambda} \overline{\mathbb{Q}}((x^{1/*})).$$

#### similarity, hypergeometricity

- $y_1$  and  $y_2$  are similar if  $\exists q \in \mathbb{Q}(x)_{\neq 0}, y_2 = qy_1$ .
- *y* is hypergeometric if  $\exists u \in \mathbb{Q}(x)$ , My = uy.

#### Structure of hypergeometric solutions in $\mathfrak D$

$$\{ \text{ hypergeometric solutions of (L) in } \mathfrak{D} \} = \{0\} \sqcup \coprod_{j=1}^{m} (\mathfrak{H}_{j})_{\neq 0}$$

where:

- Each  $(\mathfrak{H}_j)_{\neq 0}$  is a class of similar hypergeometric solutions.
- The vector spaces  $\mathfrak{H}_j$  are in direct sum in  $\mathfrak{D}$ .
- The sum of the  $d_j := \dim \mathfrak{H}_j$  add up to at most the order of *L*.

• 
$$\mathfrak{H}_j \subset (\ln x)^{\log_b \lambda_j} \overline{\mathbb{Q}}((x^{1/*}))$$
 for a suitable  $\lambda_j$ .

m

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Fix:  $\mathbb{Q}(x) \subset F \subset \mathfrak{D}$  with field *F* stable under *M*.

#### F-similarity, F-hypergeometricity

- $y_1$  and  $y_2$  are *F*-similar if  $\exists q \in F_{\neq 0}, y_2 = qy_1$ .
- *y* is *F*-hypergeometric if  $\exists u \in F$ , My = uy.

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### Structure of Solutions to the Riccati Equation

$$\begin{split} \rho: (\ln x)^{\log_b \lambda} \bar{\mathbb{Q}}((x^{1/*})) \to \bar{\mathbb{Q}}((x^{1/*})) & \text{ is well-defined for each } \lambda. \\ y \mapsto My/y \end{split}$$

Transport of the solution structure, given  $\mathbb{Q}(x) \subset F \subset \mathfrak{D}$ 

$$\{(\text{some}) \text{ solutions of } (\mathsf{R})\} = \prod_{j=1}^{m} \mathfrak{R}_j$$

where:

- $\mathfrak{R}_j := \rho((\mathfrak{H}_j)_{\neq 0})$
- $\rho$  induces a one-to-one parametrization of  $\mathfrak{R}_j$  by  $\mathbb{P}(\mathfrak{H}_j) \simeq \mathbb{P}^{d_j-1}(\overline{\mathbb{Q}})$ .

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Given a basis  $(y_1, \ldots, y_d)$  of  $\mathfrak{H} := \mathfrak{H}_j$ , with dimension  $d := d_j$ :

$$(g_1:\cdots:g_d)\mapsto rac{g_1My_1+\cdots+g_dMy_d}{g_1y_1+\cdots+g_dy_d}$$

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#### **Puiseux series solutions**

 $F:=\bar{\mathbb{Q}}((x^{1/*}))$ 

#### **Rational solutions**

 $\lambda$  + Newton polygon  $ightarrow q_{\lambda} \in \mathbb{N}$ 

$$q := \operatorname{lcm}_{\lambda} q_{\lambda} \to F := \overline{\mathbb{Q}}((x^{1/q}))$$

# Useful Solving Algorithms (old) and Bounds (new)

$$L \in \overline{\mathbb{Q}}[x]\langle M \rangle$$
 deg<sub>x</sub>  $L = d$  deg<sub>M</sub>  $L = r$ 

Arithmetic complexity of solving the linear equation (CDDM, 2018)

- Basis of polynomial solutions:  $\tilde{O}(b^{-r}d^2 + M(d))$  ops.
- Basis of approximate formal power series:  $O(r^2d + r^2M(r))$  ops.
- Also: rational solutions, Puiseux series solutions.

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#### Ramification order of Puiseux series solutions (old + new)

Each  $(\ln x)^{\log_b \lambda}$  implies some  $\overline{\mathbb{Q}}((x^{1/q_\lambda}))$  for  $q_\lambda$  read on a Newton polygon.

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### Degree bounds for rational solutions *u* of the Riccati equation (new)

	numerators	denominators	both
<i>b</i> = 2	$(1+2^{-r})(2d)$	2 <i>d</i>	<i>O</i> ( <i>d</i> )
$b \ge 3$	$(1+b^{-1})\frac{d}{b^{r-2}}$	$\frac{d}{b^{r-2}}$	$O(d/b^r)$

# Part IV

# Second Approach: Structured Hermite–Padé Approximants

#### Parametrization of the search space

$$\rho: (\ln x)^{\log_b \lambda} \bar{\mathbb{Q}}((x^{1/q})) \to \bar{\mathbb{Q}}((x^{1/q}))$$
$$y \mapsto \frac{My}{y}$$

#### Parametrization of the search space

$$\begin{split} \rho: \{y \in (\ln x)^{\log_b \lambda} \bar{\mathbb{Q}}((x^{1/q})) \mid Ly = 0\} &\to \bar{\mathbb{Q}}((x^{1/q})) \\ & \cup & \cup \\ \mathfrak{H}_j \to \mathfrak{R}_j \subset \bar{\mathbb{Q}}(x) \end{split}$$

#### Parametrization of the search space

$$\rho: \operatorname{span}((\ln x)^{\log_b \lambda} Z_1, \dots, (\ln x)^{\log_b \lambda} Z_d) \to \overline{\mathbb{Q}}((x^{1/q}))$$
$$\cup \qquad \cup$$
$$\mathfrak{H}_j \to \mathfrak{H}_j \subset \overline{\mathbb{Q}}(x)$$

#### Parametrization of the search space

$$\rho: \operatorname{span}((\ln x)^{\log_b \lambda} Z_1, \dots, (\ln x)^{\log_b \lambda} Z_d) \to \overline{\mathbb{Q}}((x^{1/q}))$$
$$y \mapsto \frac{My}{y} \in \overline{\mathbb{Q}}(x) ?$$

#### Parametrization of the search space

$$\rho: \bar{\mathbb{Q}}^t \to \bar{\mathbb{Q}}((x^{1/q}))$$

$$(a_1, \dots, a_t) \mapsto \lambda \frac{a_1 M z_1 + \dots + a_t M z_t}{a_1 z_1 + \dots + a_t z_t} \in \bar{\mathbb{Q}}(x) ?$$

#### Parametrization of the search space

For each  $\lambda$ , using the suitable ramification order  $q = q_{\lambda}$ :

$$\rho: \bar{\mathbb{Q}}^t \to \bar{\mathbb{Q}}((x^{1/q}))$$

$$(a_1, \dots, a_t) \mapsto \lambda \frac{a_1 M z_1 + \dots + a_t M z_t}{a_1 z_1 + \dots + a_t z_t} \in \bar{\mathbb{Q}}(x) ?$$

Other formulation, after renormalizing *L* so that  $\lambda = 1$  and  $z_i \in \overline{\mathbb{Q}}[[x]]$ 

Describe  $(a_1, \ldots, a_t) \neq 0$  such that  $\exists P/Q \in \overline{\mathbb{Q}}(x)_{\neq 0}$ ,

$$(-a_1P) z_1 + \cdots + (-a_tP) z_t + (a_1Q) M z_1 + \cdots + (a_tQ) M z_t = 0.$$

### **Relaxation of the problem**

#### Two-stage relaxation

Solutions

$$(-a_1P) z_1 + \cdots + (-a_tP) z_t + (a_1Q) M z_1 + \cdots + (a_tQ) M z_t = 0$$

are structured instances of the syzygies

$$P_1 z_1 + \dots + P_t z_t + Q_1 M z_1 + \dots + Q_t M z_t = 0,$$

which are approximated by approximate syzygies

$$P_1 z_1 + \cdots + P_t z_t + Q_1 M z_1 + \cdots + Q_t M z_t = O(x^{\sigma}).$$

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#### Motivation

- **9** For  $\sigma \gg 1$ , approximate syzygies of "low" degree are exact syzygies.
- Structured syzygies are linear combinations of syzygies.

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#### Motivation

- **9** For  $\sigma \gg 1$ , approximate syzygies of "low" degree are exact syzygies.
- Structured syzygies are linear combinations of syzygies.

### We search for structured syzygies as recombinations of approximate syzygies.

### Structure and computation of approximate syzygies

### Minimal basis of approximate syzygies

Algorithms find a basis of the module of approximate syzygies to order  $\sigma$ :

$$\begin{pmatrix} P_{1,1},\ldots,P_{1,t} & Q_{1,1},\ldots,Q_{1,t} \\ \vdots & \vdots \\ P_{t,1},\ldots,P_{t,t} & Q_{t,1},\ldots,Q_{t,t} \\ P_{t+1,1},\ldots,P_{t+1,t} & Q_{t+1,1},\ldots,Q_{t+1,t} \\ \vdots & \vdots \\ P_{2t,1},\ldots,P_{2t,t} & Q_{2t,1},\ldots,Q_{2t,t} \end{pmatrix} \begin{pmatrix} z_1 \\ \vdots \\ z_t \\ Mz_1 \\ \vdots \\ Mz_t \end{pmatrix} = \begin{pmatrix} O(x^{\sigma}) \\ \vdots \\ O(x^{\sigma}) \\ \vdots \\ O(x^{\sigma}) \\ \vdots \\ O(x^{\sigma}) \end{pmatrix}$$

(Derksen, 1994), (Beckermann, Labahn, 1994, 2000), Neiger (2016).

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(Derksen, 1994), (Beckermann, Labahn, 1994, 2000), Neiger (2016).

#### Properties (module)

The module of the rows: (i) has rank 2t for all  $\sigma$ ; (ii) is ultimately decreasing with  $\sigma$ ; (iii) has the module of (exact) syzygies as a limit (with rank < 2t).

### Reduction to a polynomial system

### Properties (vector space)

The vector space of the rows of "low" degree: (*i*) is nonincreasing; (*ii*) has the vector space of exact syzygies of "low" degree as a limit.

W := submatrix of (independent) rows of "low" degree.  $\rho$  := rank of the module of rows generated by W.

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Search for structured approximate syzygies, hoping that they are exact

Given  $a := (a_1, \ldots, a_t) \neq 0$ , the following are equivalent:

- $\exists P/Q \in \overline{\mathbb{Q}}(x)_{\neq 0}$  such that (-aP, aQ) is in the module  $\overline{\mathbb{Q}}[x]^{1 \times \rho} W$ ,
- *W*<sub>+</sub> has a nontrivial left kernel, where *W*<sub>+</sub> is *W* stacked above

$$\begin{pmatrix} a_1,\ldots,a_t & 0\\ 0 & a_1,\ldots,a_t \end{pmatrix},$$

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$$\begin{pmatrix} a_1,\ldots,a_t & 0\\ 0 & a_1,\ldots,a_t \end{pmatrix}$$

• *a* is a solution of the quadratic homogeneous polynomial system  $\Sigma := \left\{ \text{coefficients w.r.t } x \text{ of the minors of size } \rho + 2 \text{ of } W_+ \right\} \subset \overline{\mathbb{Q}}[a].$ 

# A Polynomial System with a Linear Variety of Solutions

$$V(\Sigma) = \bigcup_{j} I_j$$
 ( $I_j$  = irreducible component)

#### Properties

When  $\sigma$  increases,  $V(\Sigma)$  stabilizes. At the limit:

- each  $I_j$  is a subspace of  $\overline{\mathbb{Q}}^t$ ,
- the *I<sub>j</sub>* are in direct sum,
- each *I<sub>i</sub>* parametrizes a subset of rational solutions of (R),
- the images of the *I<sub>j</sub>* form a partition of the rational solutions of (R).

### Adjust the precision $\sigma$ to be able to solve

• Primary decomposition: obtain Gröbner bases for prime ideals  $p_j$  s.t.

$$\sqrt{(\Sigma)} = \bigcap_{i} \mathfrak{p}_{j} \subset \overline{\mathbb{Q}}[a_{1}, \ldots, a_{t}].$$

(Gianni, Trager, Zacharias, 1988): implementation over  $\bar{\mathbb{Q}}$  in Singular.

• If any Gröbner basis contains a nonlinear element,  $\sigma$  is too small.

# Sketch of the algorithm (for a given $\lambda$ )

### **Obtain all rational** $u = \lambda x^{\alpha} + \cdots$ **s.t.** M - u is a right-hand factor of *L*:

- Compute a basis of truncated series solutions (z<sub>1</sub>,..., z<sub>t</sub>) to some initial order σ<sub>0</sub>.
- For  $\sigma$  in a geometric sequence  $\phi^k \sigma_0$ :
  - Prolong the basis to order  $\sigma$ .
  - Compute a minimal basis of the module of approximate syzygies.
  - Extract the "low"-degree rows into a matrix *W* of rank  $0 \le \rho \le 2t$ .
  - $ho \in \{0, 2t-1, 2t\}$  are special cases dealt with separately.
  - Compute minors of *W*<sub>+</sub>, then their coefficients to obtain Σ.
  - Compute the primary decomposition  $\sqrt{(\Sigma)} = \bigcap_{j} \mathfrak{p}_{j}$  over  $\overline{\mathbb{Q}}$ .
  - If any  $p_j$  shows a nonlinear polynomial, increase  $\sigma$ .
  - For each *j*:
    - Solve p<sub>j</sub> to get a matrix S and a parametrization a = Sg for g in some Q
      <sup>v</sup>.
    - Solve for the left kernel of  $W_+$  at a = Sg. If incompatible result, increase  $\sigma$ .
    - Get a candidate P/Q (with param. g) from the basis element of the kernel.
    - If degrees of u := P/Q are too high, or if u does not satisfy (R), increase  $\sigma$ .
  - Convert all obtained *u* from solutions of  $L_{\lambda}$  into solutions of *L*.
  - Quit and return the solutions.

# Part V

# Comparison of the Approaches and Application to Hypertranscendence

			IP		HP				
example	br	d	tot	fst	dim	$\sigma$	rfn	syz	tot
Baum_Sweet	22 22	1	0.10		(1, 1)	(6, 6) 0			
Rudin_Shapiro		1			(1, 0)	(6, †)0			
Stern_Brocot_b2	22	4			(1)			0.10	
no_2s_in_3_exp	22	4	0.25		(1, 1)	(33, 9)0			
Dilcher_Stolarsky		4	0.11		(2)			0.27	
Stern_Brocot_b4	42	26		0.15	(1)			0.23	
Katz_Linden	24	14				†,69,†,†)0			
Adamczewski_Faverjon	34	258		0.31	(4)	(163) 0		2.0	3.3
lclm_3rat_1log	33	121		0.12	(3)	(140) 0		2.8	3.4
lclm_3rat_2log		122		0.14	(2, 1)	(88, 52)0			1.0
lclm_2rat_trunc_s10	24	56		0.16	(4)	(294)	1.8	12	14
lclm_2rat_trunc_sl1	24	61	965						>2 d
lclm_3rat_trunc_sl1	35	1260		0.36	(3, 2)	(574, 268)		47	56
lclm_4pow_b2	27	107		0.37	(1, 4)	(429, 739)0		3.5	4.1
lclm_4pow_b3	36	727		0.85	(1, 4)	(108, 174)			2.9
lclm_4pow_b4	45	989		0.47	(4)	(223) 0			2.2
lclm_4pow_b5		3103	>2 d		(1, 4)	(44, 289)	21	1.2	37
lclm_5pow_b4		17270	>2 d	84	(1, 5)	(274, 1326)		8.3	226
dft_Baum_Sweet	42	6	0.15		(2)	(124) 0			
dft_Rudin_Shapiro	42	7		0.07	(1, 0)	(88, †)0			
dft_Stern_Brocot_b2	42	24		0.13	(1)			0.14	
dft_no_2s_in_3_exp	42	20		0.09	(1, 1)	(85, 33) 0			
	162	50	4275		(2)	(666) 0		4.6	5.0
dft_Stern_Brocot_b4			43213	0.26	(1)	(239) 0	.17	2.2	2.7
rmo_2_1	23	19	6.1						>2 d
rmo_3_1	33	37		0.10	(3)	(111) 0	.24	517	518
rmo_2_2		44	17						>2 d
rmo_3_2		82		0.12	(3)	(247)	2.1	10100	
rmo_2_3	23	69	31						>2 d
rmo_3_3	33	127		0.12	(3)	(386)	6.8	60102	
rmo_2_4		94	49						>2 d
rmo_3_4		172	131						>2 d
rmo_2_5		119	70						>2 d
rmo_3_5	33	217	194						>2 d

Caveat:

- timings with a heuristic for absolute decomposition,
- ongoing work: calling Singular from Maple.

## **Differentially Algebraic Independence**

Hypertranscendence (a.k.a. differential transcendence)

 $f \in \mathbb{C}(x)$  is hypertranscendental over  $\mathbb{C}(x) \Leftrightarrow f$  admits no polynomial differential equation over  $\mathbb{C}(x)$ 

Corollary of a criterion (Roques, 2018) on the difference Galois group of L

Assume:

- $y(x^{b^2}) + A(x)y(x^b) + B(x)y(x) = 0$  admits a nonzero solution  $f \in \overline{\mathbb{Q}}[[x]]$ .
- No rational function u(x) is solution of one of the Riccati equations

$$\begin{split} & u(x)u(x^{b}) + A(x)u(x) + B(x) = 0, \\ & u(x)u(x^{b^{2}}) + \left(\frac{B(x^{b^{2}})}{A(x^{b^{2}})} - A(x^{b}) + \frac{B(x^{b})}{A(x)}\right)u(x) + \frac{B(x)B(x^{b})}{A(x)^{2}} = 0. \end{split}$$

Then, f and Mf are differentially algebraically independent. In particular, f is hypertranscendental, which was already proven in (Adamczewski, Dreyfus, and Hardouin, 2021).

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$$u(x)u(x^{b}) + A(x)u(x) + B(x) = 0,$$
  
$$u(x)u(x^{b^{2}}) + \left(\frac{B(x^{b^{2}})}{A(x^{b^{2}})} - A(x^{b}) + \frac{B(x^{b})}{A(x)}\right)u(x) + \frac{B(x)B(x^{b})}{A(x)^{2}} = 0.$$

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Independence for the Baum–Sweet, Rudin–Shapiro, and Dilcher–Stolarsky examples!