# Fast Algorithms for Discrete Differential Equations 

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Joint work with:
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Mohab Safey El Din (Sorbonne Université)

## Motivation: Enumerating discrete structures...

Counting walks in $\mathbb{N}$ with steps in $\{+1,-2\}$
$c_{n}:=\#\{n$ steps walks starting at 0 and ending at height 0$\}$
$G(t):=\sum_{n=0}^{\infty} c_{n} t^{n}$
generating function


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$G(t):=\sum_{n=0}^{\infty} c_{n} t^{n} \quad$ generating function


## Enumeration refinement

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\begin{aligned}
c_{n, d}:= & \#\{n \text { steps walks starting at } 0 \\
& \text { and ending at height } d\} \\
& =(t, u):=\sum_{n=0}^{\infty} \sum_{d=0}^{n} c_{n, d} u^{d} t^{n} \\
& \text { complete generating function }
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$F(t, u):=\sum_{n=0}^{\infty} \sum_{d=0}^{n} c_{n, d} u^{d} t^{n}$ complete generating function


## DDE of order 2

$$
c_{n, d}=c_{n-1, d-1}+c_{n-1, d+2}
$$

$$
\uparrow
$$

$$
\begin{aligned}
F(t, u)=1 & +t \cdot u \cdot F(t, u) \\
& +t \cdot \frac{F(t, u)-F(t, 0)-u \cdot \partial_{u} F(t, 0)}{u^{2}}
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$$
c_{n, 0}=c_{n} \quad \Longrightarrow \quad F(t, 0)=G(t)
$$

## ... yields challenging computational problems

$\mathbb{K}$ effective field of characteristic 0 .

$$
\mathbb{K}=\mathbb{Q}, \mathbb{Q}(y), \ldots
$$

Starting point: $F \in \mathbb{K}[u][[t]]$, solution of the discrete differential equation of order 2

$$
F(t, u)=1+t \cdot u \cdot F(t, u)+t \cdot \Delta^{(2)} F(t, u)
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where $\Delta F(t, u):=\frac{F(t, u)-F(t, 0)}{u}$ and $\Delta^{(2)} F(t, u)=\frac{F(t, u)-F(t, 0)-u \cdot \partial_{u} F(t, 0)}{u^{2}}$.

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Interest: Nature of $F(t, 0)$.

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Classical: $F, F(t, 0)$ and $\partial_{u} F(t, 0)$ are algebraic.
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## Goals:

- Compute a polynomial $R \in \mathbb{K}\left[t, z_{0}\right] \backslash\{0\}$ such that $R(t, F(t, 0))=0$.
- Estimate the size of $R$ for such DDEs.
- Complexity estimates (ops. in $\mathbb{K}$ ) for the computation of $R$.


## State of the art

Let $k \geq 1, f \in \mathbb{K}[u]$ and $Q \in \mathbb{K}\left[x, y_{1}, \ldots, y_{k}, t, u\right]$. For $F \in \mathbb{K}[u][[t]]$, define $\Delta(F):=(F-F(t, 0)) / u \in \mathbb{K}[u][[t]]$ and $\Delta^{(i)}(F):=\Delta \circ \Delta^{(i-1)}(F)$.

Theorem [Bousquet-Mélou, Jehanne '06]
There exists a unique solution $F \in \mathbb{K}[u][[t]]$ to

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F(t, u)=f(u)+t \cdot Q\left(F, \Delta(F), \ldots, \Delta^{(k)}(F), t, u\right)
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(DDE)
and moreover $F(t, u)$ is algebraic over $\mathbb{K}(t, u)$.

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\end{align*}
$$

[Tutte, Brown 60's], [Zeilberger '92]:
[Gessel, Zeilberger '14]:
Guess-and-prove
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[Brown '65], [Bender, Canfield '94]:
[Knuth '68], [Banderier, Flajolet '02],
[Bousquet-Mélou, Petkovšek '00]:
[Bousquet-Mélou, Jehanne '06]:
[Bostan, Chyzak,
Notarantonio, Safey El Din '22]:
Quadratic method
Kernel method (linear case)

Polynomial elimination

Polynomial elimination, Hybrid guess-and-prove

## Modelization: from (DDE) of order $k$ to structured polynomial systems

We write $\quad P(u) \equiv P\left(F(t, u), F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, u\right) \quad$ and $\quad \overline{\mathbb{K}}\left[\left[t^{\frac{1}{\star}}\right]\right] \equiv \bigcup_{d \geq 1} \overline{\mathbb{K}}\left[\left[t^{\frac{1}{d}}\right]\right]$
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## General idea:

$\mathrm{U}(\mathbf{t}) \in \overline{\mathbb{K}}\left[\left[t^{\frac{1}{\star}}\right]\right] \backslash \overline{\mathbb{K}}$ solution in $u$ of $\partial_{1} P(u)=0$

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## The points

$\left(x_{1}, \mathbf{u}_{1}\right)=\left(F\left(t, \mathbf{U}_{1}\right), \mathbf{U}_{1}\right), \ldots,\left(x_{\ell}, \mathbf{u}_{\ell}\right)=\left(F\left(t, \mathbf{U}_{\ell}\right), \mathbf{U}_{\ell}\right) \in \overline{\mathbb{K}}\left[\left[t^{\frac{1}{\star}}\right]\right]^{2}$
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\forall 1 \leq i \leq \ell,\left\{\begin{array}{c}
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and $\prod_{i \neq j}\left(\mathbf{u}_{\mathrm{i}}-\mathbf{u}_{\mathrm{j}}\right) \neq 0$.

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$\mathbf{U}_{1}(\mathbf{t}), \ldots, \mathbf{U}_{\ell}(\mathbf{t}) \in$ $\overline{\mathbb{K}}\left[\left[t^{\frac{1}{*}}\right]\right] \backslash \overline{\mathbb{K}}$ distinct solutions in $u$ of $\partial_{1} P(u)=0$
are solutions of the conditions:
$\forall 1 \leq i \leq \ell, \quad\left\{\begin{array}{c}P\left(x_{i}, F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, \mathbf{u}_{\mathbf{i}}\right)=0, \\ \partial_{1} P\left(x_{i}, F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, \mathbf{u}_{\mathbf{i}}\right)=0, \\ \partial_{u} P\left(x_{i}, F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, \mathbf{u}_{\mathbf{i}}\right)=0 .\end{array}\right.$
and $\prod_{i \neq j}\left(\mathbf{u}_{\mathbf{i}}-\mathbf{u}_{\mathrm{j}}\right) \neq 0 . \ell=k \Longrightarrow 3 k$ equations and $3 k$ unknowns!

## Our contributions

$$
\begin{align*}
F(t, u)= & f(u)+t \cdot Q\left(F, \Delta(F), \ldots, \Delta^{(k)}(F), t, u\right)  \tag{DDE}\\
& \text { where } \Delta(F):=\frac{F(t, u)-F(t, 0)}{u}
\end{align*}
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Input: $P:=$ numerator(DDE),
Goal: Compute $R \in \mathbb{K}\left[t, z_{0}\right] \backslash\{0\}$ s.t. $R(t, F(t, 0))=0$.

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1. Geometric analysis of Bousquet-Mélou and Jehanne's algorithm yielding:

- Theoretical estimate for the degree of $R \in \mathbb{K}\left[t, z_{0}\right]$ s.t. $R(t, F(t, 0))=0$,
- Arithmetic complexity.

2. New algorithm based on algebraic elimination + Gröbner bases,
3. Implementations yielding practical improvements.

## An experimental observation...

Example: (walks in $\mathbb{N}$ with steps in $\{+1,-2\}$ )
We consider $P\left(F(t, u), F(t, 0), \partial_{u} F(t, 0), t, u\right)=0$

$$
u^{2}-\left(u^{2}-t\left(1+u^{3}\right)\right) \cdot F(t, u)-t \cdot F(t, 0)-t \cdot u \cdot \partial_{u} F(t, 0)=0
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Study the solutions of $\partial_{1} P\left(F(t, u), F(t, 0), \partial_{u} F(t, 0), t, u\right)=0$

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u^{2}=t\left(1+u^{3}\right) \Longrightarrow u=U_{1}(t), U_{2}(t) \in\{\sqrt{t}+O(t),-\sqrt{t}+O(t)\}
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Hence $\left(x_{1}, u_{1}, x_{2}, u_{2}\right)=\left(F\left(t, U_{1}\right), U_{1}, F\left(t, U_{2}\right), U_{2}\right)$ is a solution of the constraints $\mathcal{T}$
$\mathcal{T}: \quad$ For $1 \leq i \leq 2,\left\{\begin{array}{rl}P\left(x_{i}, F(t, 0), \partial_{u} F(t, 0), t, u_{i}\right) & =0, \\ \partial_{1} P\left(x_{i}, F(t, 0), \partial_{u} F(t, 0), t, u_{i}\right) & =0, \\ \partial_{u} P\left(x_{i}, F(t, 0), \partial_{u} F(t, 0), t, u_{i}\right) & =0 .\end{array} \quad m \cdot\left(u_{1}-u_{2}\right)=1\right.$,

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Permuting $\left(x_{1}, u_{1}\right)$ and $\left(x_{2}, u_{2}\right)$ does not change the solution set $\Longrightarrow \mathfrak{S}_{2}$ acts on $V(\mathcal{T})$ and preserves the $\left\{z_{0}, z_{1}, t\right\}$-coordinate space.

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Hence $\left(x_{1}, u_{1}, x_{2}, u_{2}\right)=\left(F\left(t, U_{1}\right), U_{1}, F\left(t, U_{2}\right), U_{2}\right)$ is a solution of the constraints $\mathcal{T}$
$\mathcal{T}: \quad$ For $1 \leq i \leq 2,\left\{\begin{array}{rl}P\left(x_{i}, F(t, 0), \partial_{u} F(t, 0), t, u_{i}\right) & =0, \\ \partial_{1} P\left(x_{i}, F(t, 0), \partial_{u} F(t, 0), t, u_{i}\right) & =0, \\ \partial_{u} P\left(x_{i}, F(t, 0), \partial_{u} F(t, 0), t, u_{i}\right) & =0 .\end{array} \quad m \cdot\left(u_{1}-u_{2}\right)=1\right.$,

Permuting $\left(x_{1}, u_{1}\right)$ and $\left(x_{2}, u_{2}\right)$ does not change the solution set $\Longrightarrow \mathfrak{S}_{2}$ acts on $V(\mathcal{T})$ and preserves the $\left\{z_{0}, z_{1}, t\right\}$-coordinate space.

## ... yielding theoretical improvements

Denote by $\mathcal{I}$ the ideal generated by the $k$ duplications of $\left(P, \partial_{1} P, \partial_{u} P\right)$ and $m \cdot \prod_{i \neq j}\left(u_{i}-u_{j}\right)-1=0$.

Assume that:

- there exist $k$ distinct solutions $u=U_{1}, \ldots, U_{k} \in \overline{\mathbb{K}}\left[\left[t^{\frac{1}{\star}}\right]\right]$ of $\partial_{1} P(u)=0$,
- $\mathcal{I}$ is radical and of dimension 0 over $\mathbb{K}(t)$. ( $3 k$ equations and $3 k$ unknowns)

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- $\mathcal{I}$ is radical and of dimension 0 over $\mathbb{K}(t)$.
( $3 k$ equations and $3 k$ unknowns)

Theorem [Bostan, N., Safey El Din '23]

- Let $\delta:=\operatorname{deg}(P)$. There exists a nonzero polynomial $R \in \mathbb{K}\left[t, z_{0}\right]$ whose partial degrees are bounded by $\delta^{\mathrm{k}}(\delta-1)^{2 \mathrm{k}} / \mathrm{k}$ ! and such that $R(t, F(t, 0))=0$.
- There exists an algorithm computing $\boldsymbol{R}$ in $\mathrm{O}\left(\delta^{6 \mathrm{k}}\left(\mathrm{k}^{2} \delta^{\mathrm{k}+3}+\delta^{1.89 \mathrm{k}} / \mathrm{k}!\right)\right)$ ops. in $\mathbb{K}$.

Ideas of the proof:
$\rightarrow$ Bézout bound $+\mathfrak{S}_{k}$ acts on $V\left(\mathcal{I}_{\text {dup }}\right)$ and preserves the $z_{0}$-coordinate space.
$\rightarrow$ Parametric geometric resolution [Schost '03], [Giusti, Lecerf, Salvy '01]

$$
z_{0}=V(t, \lambda) / \partial_{\lambda} W(t, \lambda), W(t, \lambda)=0
$$

$\rightarrow$ Change of monomial ordering: Stickelberger's theorem [Cox '21] $R=\operatorname{Sqfree}\left(\operatorname{Res}_{\lambda}\left(z_{0} \cdot \partial_{\lambda} W-V, W\right)\right)$

+ bivariate resultants [Villard '18], [van der Hoeven, Lecerf '21]

Summary of the initial problem: $\quad \underline{z} \equiv z_{0}, \ldots, z_{k-1} ; P=$ "numer" $(D D E) \in \mathbb{K}(t)[x, \mathbf{u}, \underline{z}]$ There exist $k$ solutions $(x, \mathbf{u}) \in \overline{\mathbb{K}}(t)^{2}$ with distinct $\mathbf{u}$-coordinates to

$$
\left\{\begin{aligned}
P\left(x, \mathbf{u}, F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0)\right) & =0 \\
\partial_{1} P\left(x, \mathbf{u}, F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0)\right) & =0, \quad \mathbf{u} \neq 0, \\
\partial_{u} P\left(x, \mathbf{u}, F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0)\right) & =0
\end{aligned}\right.
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$$

Define

$$
\begin{aligned}
& \pi_{x}:(x, \mathbf{u}, \underline{z}) \in \overline{\mathbb{K}}(t)^{k+2} \mapsto(\mathbf{u}, \underline{z}) \in \overline{\mathbb{K}}(t)^{k+1} \\
& \pi_{u}:(\mathbf{u}, \underline{z}) \in \overline{\mathbb{K}}(t)^{k+1} \mapsto(\underline{z}) \in{\overline{\mathbb{K}}(t)^{k}}^{k}
\end{aligned}
$$

and consider $\mathbf{W}:=\pi_{x}\left(V\left(P, \partial_{1} P, \partial_{u} P\right) \backslash V(\mathbf{u})\right)$.

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\end{aligned}
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$$
\# \pi \bar{u}^{-1}\left(\alpha_{\underline{z}}\right) \cap \mathrm{W}=2
$$

Summary of the initial problem: $\quad \underline{z} \equiv z_{0}, \ldots, z_{k-1} ; P=$ "numer" $(D D E) \in \mathbb{K}(t)[x, \mathbf{u}, \underline{z}]$ There exist $k$ solutions $(x, \mathbf{u}) \in \overline{\mathbb{K}}(t)^{2}$ with distinct $\mathbf{u}$-coordinates to

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\end{aligned}
$$

and consider $\mathbf{W}:=\pi_{x}\left(V\left(P, \partial_{1} P, \partial_{u} P\right) \backslash V(\mathbf{u})\right)$.


## Objective:

Characterize with polynomial constraints

$$
\mathcal{F}_{k}:=\left\{\alpha_{\underline{z}} \in \overline{\mathbb{K}}(t)^{k} \mid \# \pi_{u}^{-1}\left(\alpha_{\underline{z}}\right) \cap \mathbf{W} \geq k\right\}
$$

$$
\# \pi \bar{u}^{-1}\left(\alpha_{\underline{z}}\right) \cap \mathrm{W}=2
$$

## Getting some intuition through our toy example...

Example: (Walks in $\mathbb{N}$ with steps in $\{+1,-2\}$ )

$$
P:=(1-x) u^{2}+t u^{3} x+t\left(x-z_{0}-u z_{1}\right) \in \mathbb{K}(t)\left[x, u, z_{0}, z_{1}\right], \quad k=2 .
$$

$G_{u}$ Gröbner basis of $\left\langle P, \partial_{1} P, \partial_{u} P, m u-1\right\rangle \cap \mathbb{K}\left[u, t, z_{0}, z_{1}\right]$ for $\{u\} \succ_{\text {lex }}\left\{t, z_{0}, z_{1}\right\}$ :

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$$
\begin{aligned}
& \mathbf{B}_{\mathbf{0}}: \\
& \mathbf{B}_{\mathbf{1}}:\left\{\begin{array}{c}
\gamma_{0} \\
\beta_{1} \cdot u+\gamma_{1} \\
\vdots \\
\beta_{r} \cdot u+\gamma_{r}
\end{array}, \gamma_{i}, \beta_{j} \in \mathbb{K}\left[t, z_{0}, z_{1}\right] \quad \text { "At }\left(z_{0}, z_{1}\right) \text { fixed in } \overline{\mathbb{K}}(t)^{2},\right. \\
& \text { there exist two distinct roots in } u \text { " }
\end{aligned}
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\text { there exist two distinct roots in } u \text { " }
\end{array}\right.
\end{aligned}
$$

## Necessary condition:

At $\alpha \in V\left(G_{u} \cap \mathbb{K}\left[t, z_{0}, z_{1}\right]\right)$ fixed, there exist two roots in $u$

$$
\Longrightarrow \beta_{i}, \gamma_{j}=0 \quad \text { (equations) }
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$\mathbf{B}_{\mathbf{2}}: \quad$ there exist two distinct roots in $u$ "
$g_{2}:=u^{2}+\beta_{r+1} \cdot u+\gamma_{r+1}$

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$$
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## Extension theorem:

The pre-image of $\alpha$ by $\pi_{u}$ is well-defined $\Longrightarrow$ LeadingCoeff ${ }_{u}\left(g_{2}\right) \neq 0$
Distinct roots in $u \Longrightarrow \operatorname{disc}_{u}\left(g_{2}\right) \neq 0$ (inequations)

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Distinct roots in $u \Longrightarrow \operatorname{disc}_{u}\left(g_{2}\right) \neq 0$ (inequations)

After adding these constraints to $G_{u}$ and eliminating $u$ and $z_{1}$ :

$$
\mathbf{R}\left(\mathbf{t}, \mathbf{z}_{\mathbf{0}}\right)=\mathbf{t}^{3} \mathbf{z}_{0}^{3}-\mathbf{z}_{\mathbf{0}}+\mathbf{1} \text { satisfies } \mathbf{R}(\mathbf{t}, \mathbf{F}(\mathbf{t}, \mathbf{0}))=\mathbf{0}
$$

- Projecting: Elimination theorem
- Lifting points of the projections: Extension theorems

Cardinality conditions on the fibers:

- Extension theorem (Gröbner bases version)
- $g\left(u, \alpha_{\underline{z}}\right) \in \overline{\mathbb{K}(t)}[u]$ of degree $k+j$ has at least $k$ distinct roots
$\Longleftrightarrow$ One of the $(k \times k)$-minors of the Hermite quadratic form associated with $g$ does not vanish at $\alpha_{\underline{z}}$
$\square$

Ideals, Varieties, and Algorithms
An Introduction to Computational Algebraic Geometry and Commutative Algebra
Fourth Edition

- Projecting: Elimination theorem
- Lifting points of the projections: Extension theorems

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Ideals, Varieties, and Algorithms
An Introduction to Computational Algebraic Geometry and Commutative Algebra
Fourth Edition
[Bostan, N., Safey El Din '23] :
Conjunctions of polynomial equations and inequations whose zero set is $\mathcal{F}_{k}$

## First implementations yielding practical improvements

| 3-Tamari, $k=3$ |  |  |  |
| :---: | :---: | :---: | :---: |
| A | T | $\mathbf{d}_{\mathbf{t}}$ | $\mathbf{d}_{\mathrm{z}_{0}}$ |
| D | 2 d 2 h | 5 | 16 |
| DE | 2 m | 5 | 16 |
| HGP + DE | 1 h 40 m | 5 | 16 |

5-constellations, $k=\mathbf{4}$

| A | $\mathbf{T}$ | $\mathbf{d}_{\mathbf{t}}$ | $\mathbf{d}_{\mathbf{z}_{0}}$ |
| :---: | :---: | :---: | :---: |
| D | $\infty$ | - | - |
| DE | $\infty$ | $26 \bullet$ | $53 \bullet$ |
| HGP + DE | 6 h 7 m | 2 | 5 |

- : data obtained after a computation $\bmod p=65521$.
- A: Algorithm used (D: duplication, DE: direct elimination, HGP: Hybrid Guess-and-Prove [Bostan, Chyzak, N., Safey El Din '22]),
- $\mathbf{T}$ : total timing needed to obtain an output in $\mathbb{Q}\left[t, z_{0}\right]$,
- dz: degree in $Z \in\left\{t, z_{0}\right\}$ of output $R \in \mathbb{Q}\left[t, z_{0}\right]$ s.t. $R(t, F(t, a))=0$,

Intel® Xeon ® Gold CPU 6246R v4 © 3.40 GHz and 1.5 TB of RAM with a single thread.
Gröbner bases computations are performed using the C library msolve, and all guessing computations are performed using the gfun Maple package.

## Conclusion and future works

## Conclusion

- New geometric interpretations of the problem "solving a DDE",
- New algorithm based on algebraic elimination and Gröbner bases,
- Some promising practical results,
- (In the preprint) New geometric algorithm based on Stickelberger's theorem.


## Future works

- Study the minimality and the genericity of the introduced assumptions,
- Provide a maple package for solving DDEs, together with a tutorial paper.


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Input: $P\left(F(t, u), F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, u\right)=0, \delta:=\operatorname{deg}(P)$. Output: $R \in \mathbb{K}\left[t, z_{0}\right] \backslash\{0\}$ annihilating $F_{0}=F(t, 0)$, i.e. $R\left(t, F_{0}\right)=0$.

## Hybrid Guess-and-prove

Input: $P\left(F(t, u), F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, u\right)=0, \delta:=\operatorname{deg}(P)$. Output: $R \in \mathbb{K}\left[t, z_{0}\right] \backslash\{0\}$ annihilating $F_{0}=F(t, 0)$, i.e. $R\left(t, F_{0}\right)=0$.

## geometry

(1) Functional equation
$\downarrow$
(2) Polynomial system
$\downarrow$
(3) Bounds

- $\operatorname{deg}_{t}(R) \leq b_{t}$,
- $\operatorname{deg}_{z_{0}}(R) \leq b_{z}$.

Input: $P\left(F(t, u), F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, u\right)=0, \delta:=\operatorname{deg}(P)$. Output: $R \in \mathbb{K}\left[t, z_{0}\right] \backslash\{0\}$ annihilating $F_{0}=F(t, 0)$, i.e. $R\left(t, F_{0}\right)=0$.
geometry
(1) Functional equation
$\downarrow$
(2) Polynomial system $\downarrow$
(3) Bounds

- $\operatorname{deg}_{t}(R) \leq b_{t}$,
- $\operatorname{deg}_{z_{0}}(R) \leq b_{z}$.
guess-and-prove
(4) Expand $F_{0}$
(5) Compute $R \in \mathbb{K}\left[t, z_{0}\right]$

$$
R\left(t, F_{0}\right)=O\left(t^{\sim b_{t} b_{z}}\right)
$$

$$
\downarrow
$$

(6) Certify that $R\left(t, F_{0}\right)=0$

Input: $P\left(F(t, u), F(t, 0), \ldots, \partial_{u}^{k-1} F(t, 0), t, u\right)=0, \delta:=\operatorname{deg}(P)$.
Output: $R \in \mathbb{K}\left[t, z_{0}\right] \backslash\{0\}$ annihilating $F_{0}=F(t, 0)$, i.e. $R\left(t, F_{0}\right)=0$.


## Solving our toy example using the Hybrid Guess-and-Prove strategy

Counting walks in $\mathbb{N}$ with steps in $\{+1,-2\}$

$$
F(t, u)=1+t \cdot u \cdot F(t, u)+t \cdot \frac{F(t, u)-F(t, 0)-u \cdot \partial_{u} F(t, 0)}{u^{2}}
$$

- Draw a random $c=1341$, and a prime number $p=19541$,
- Using the new algorithm based on elimination theory, we obtain:
- $R(t, c) \bmod p=t^{3}+15794$,
- $R\left(c, z_{0}\right) \bmod p=z_{0}^{3}+18182 z_{0}+1319$.
- Set $b_{t}=3, b_{z_{0}}=3$,
- Compute

$$
F(t, 0)=1+t^{3}+3 t^{6}+12 t^{9}+55 t^{12}+273 t^{15}+1428 t^{18}+O\left(t^{2 \cdot b_{t} \cdot b_{z_{0}}+1}\right)
$$

- Guess $A:=t^{3} z_{0}^{3}-z 0+1$ such that $A(t, F(t, 0))=O\left(t^{\left(b_{t}+1\right) \cdot\left(b_{z_{0}}+1\right)-1}\right)$,
- Check that $A(t, F(t, 0))=O\left(t^{2 \cdot b_{t} \cdot b_{z_{0}}+1}\right)$

The output $A$ is certified.

