

A Newton-like algorithm and algebraic methods for Structured Low-Rank Approximation

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Inria Nancy Grand-Est/LORIA/CNRS, project CAMEL

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Problem Statement

$$p, q, r \in \mathbb{N}$$

E a **linear/affine subspace** of $p \times q$ matrices with real entries

For $(M_{i,j})$ a $p \times q$ matrix, $\|M\|_F = \sqrt{\sum_{i,j} M_{i,j}^2}$,

$$\langle M_1, M_2 \rangle = \text{trace}(M_1 \cdot M_2^T)$$

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Structured Low-Rank Approximation

Given $M \in E$, compute a **matrix** $\hat{M} \in E$ such that

- $\text{Rank}(\hat{M}) \leq r$;
- $\|M - \hat{M}\|_F$ is **small**.

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“Behind every linear data modeling problem there is a (hidden) low-rank approximation problem: the model imposes relations on the data which render a matrix constructed from exact data rank deficient.”

Markovsky, 08

- $E =$ Sylvester matrices \rightsquigarrow univariate approximate GCD

$$\begin{bmatrix} a_3 & 0 & b_2 & 0 & 0 \\ a_2 & a_3 & b_1 & b_2 & 0 \\ a_1 & a_2 & b_0 & b_1 & b_2 \\ a_0 & a_1 & 0 & b_0 & b_1 \\ 0 & a_0 & 0 & 0 & b_0 \end{bmatrix}$$

- $E =$ **Sylvester matrices** \rightsquigarrow univariate approximate GCD
- $E =$ **Hankel matrices** \rightsquigarrow denoising, signal processing

$$\begin{bmatrix} a & b & c & d & e \\ b & c & d & e & f \\ c & d & e & f & g \\ d & e & f & g & h \\ e & f & g & h & i \end{bmatrix}$$

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- $E =$ **affine coordinate spaces** \rightsquigarrow matrix completion

$$\begin{bmatrix} 3 & ? & ? & 5 & 5 \\ 1 & 2 & 3 & 2 & ? \\ 10 & 4 & ? & 9 & -4 \\ 6 & ? & 3 & 9 & 10 \\ ? & 5 & -2 & ? & 9 \end{bmatrix}$$

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- $E =$ **Ruppert matrices** \rightsquigarrow multivariate factorization

$$\begin{bmatrix} 0 & -2 & -a & 0 & -2b & -d \\ -1 & 0 & c & -b & 0 & e \\ a & 2c & 0 & d & 2e & 0 \\ 0 & 0 & 0 & 1 & a & c \\ 0 & 0 & 0 & -b & -d & -e \end{bmatrix}$$

$XY^2 + aXY + bY^2 + cX + dY + e \in \mathbb{C}[X, Y]$ factors $\Leftrightarrow \text{rank} \leq 4$

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Which notion of “small”, for which **distance**?

\rightsquigarrow depends on **the application**

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Symbolical minimization

joint work with **Giorgio Ottaviani** and **Bernd Sturmfels**

↪ **algebraic complexity** of the problem

↪ gives useful information for **numerical algorithms** (e.g. bounds on the number of **local minima**)

Main results (numerical algorithm)

\mathcal{D}_r : **manifold** of $p \times q$ matrices of **rank r**
 E : **linear/affine subspace** of $p \times q$ matrices

Algorithm NewtonSLRA

NewtonSLRA: iterative algorithm with proven local **quadratic convergence** under mild **transversality assumptions**.

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More precisely: for any smooth point $\zeta \in \mathcal{D}_r \cap E$ where \mathcal{D}_r and E **intersect transversely**, there exists a small neighborhood $U \supset \zeta$ such that for any input matrix $M_0 \in U$,

- the sequence of iterates M_1, M_2, \dots **converges quadratically** towards $M_\infty \in \mathcal{D}_r \cap E$, i.e.

$$\|M_i - M_\infty\| \leq (1/2)^{2^{i-1}} \|M_0 - M_\infty\|$$

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- Let \hat{M} be the **nearest solution**;
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- $E \cap \mathcal{D}_r$ is **finite** \rightsquigarrow **MinRank problem**.
 \rightsquigarrow finite fields: Cryptology, Coding theory, ...
Bettale, Buss, Courtois, Frandsen, Gaborit, Goubin, Kipnis, Levy-dit-Vehel, Faugère, Perret, Ruatta, Safey, Shallit, Shamir, S., ...

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- **Optimization:** *Chu/Funderlic/Plemmons*

Eckart-Young theorem

Let $M = U \cdot S \cdot V^T$ be the **Singular Value Decomposition** of M , where $S = \text{Diag}(\sigma_1, \dots, \sigma_q)$ with $\sigma_1 \geq \dots \geq \sigma_q$.

Set $\hat{S} = \text{Diag}(\sigma_1, \dots, \sigma_r, 0, \dots, 0)$.

Then $\hat{M} = U \cdot \hat{S} \cdot V^T$ is the rank r matrix which **minimizes the Frobenius distance to M** .

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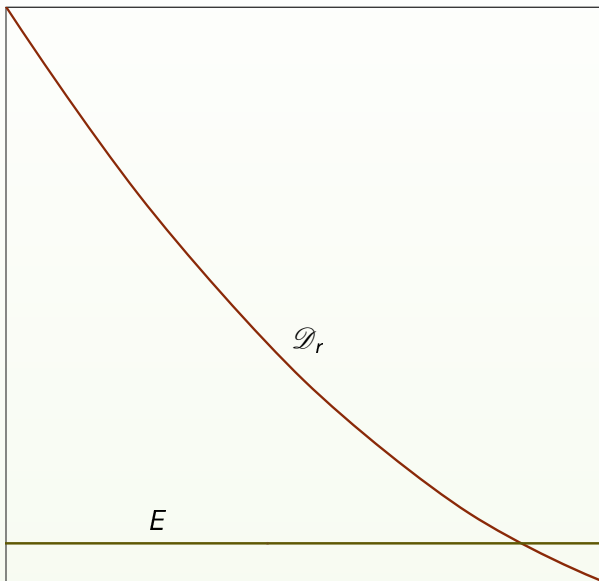
Cadzow's algorithm (*Cadzow, 88, Lewis/Mallick 08*):

- project on \mathcal{D}_r (the **manifold** of matrices of rank r) with **SVD**;
- project back on E .

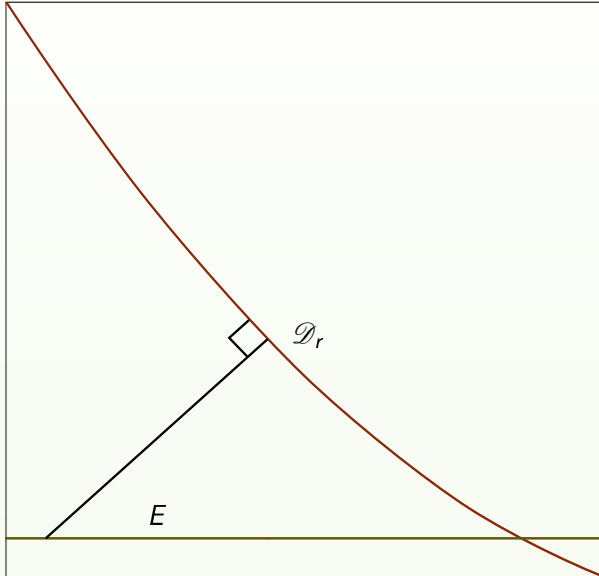
Converges **linearly** towards a point in $\mathcal{D}_r \cap E$.

Does not converge to the **nearest solution**.

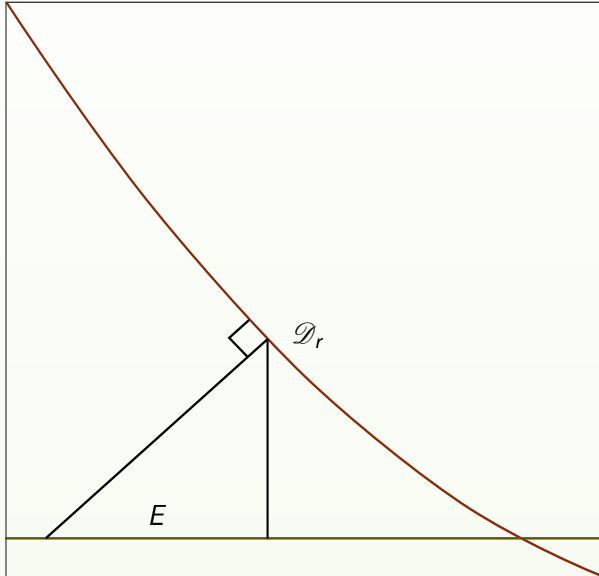
Cadzow's algorithm



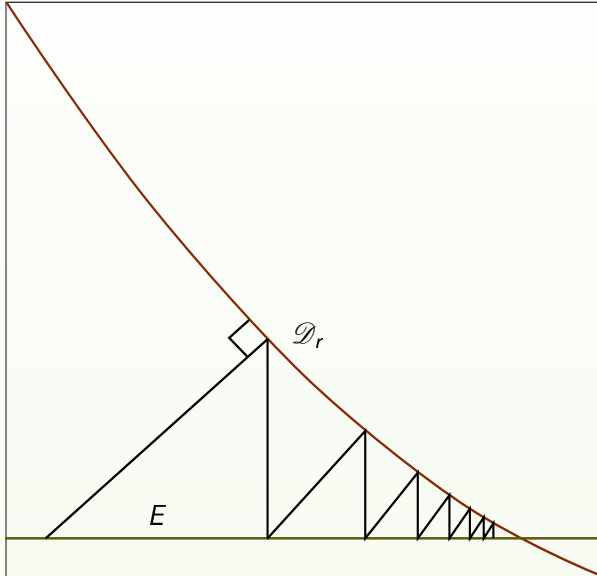
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Newton's method

Classical **Newton's method** for $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$N_f(x) = Df(x)^{-1}(f(x)).$$

Quadratic convergence when Df is locally invertible.

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Newton's method for **underdetermined systems**:

$f : \mathbb{R}^m \rightarrow \mathbb{R}^n$, $N_f(x) = Df(x)^\dagger(f(x))$.

Df^\dagger : **Moore-Penrose pseudo-inverse**.

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If x_0 is the starting point of the iteration, let

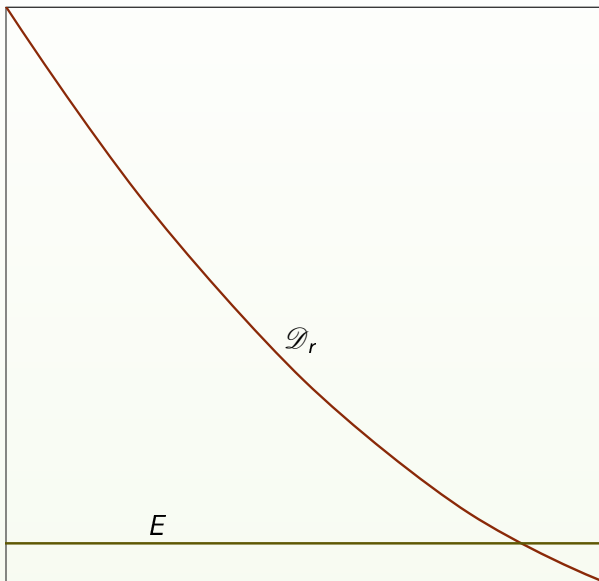
$$\hat{x} = \operatorname{argmin}_{f(y)=0} \|y - x_0\|.$$

Does not converge to the nearest solution \hat{x} , but

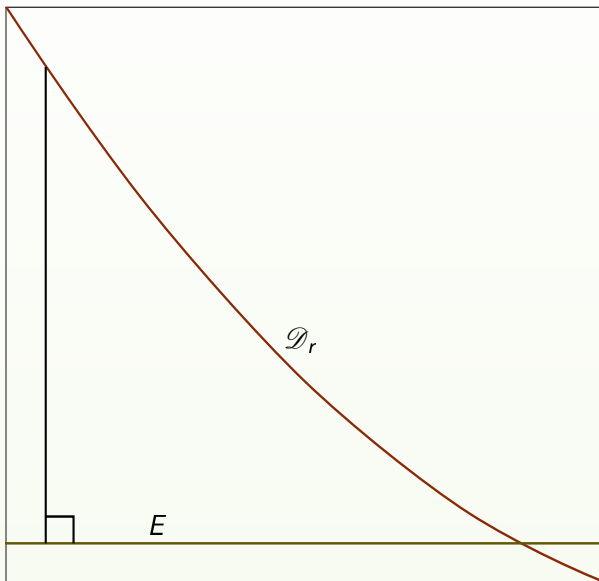
$$\|x_\infty - \hat{x}\| = O(\|x_0 - \hat{x}\|^2).$$

*Ben-Israel 66, Allgower/Georg 90, Beyn 93,
Shub/Smale 96, Dedieu/Shub 00, Dedieu/Kim 02, Dedieu 06*

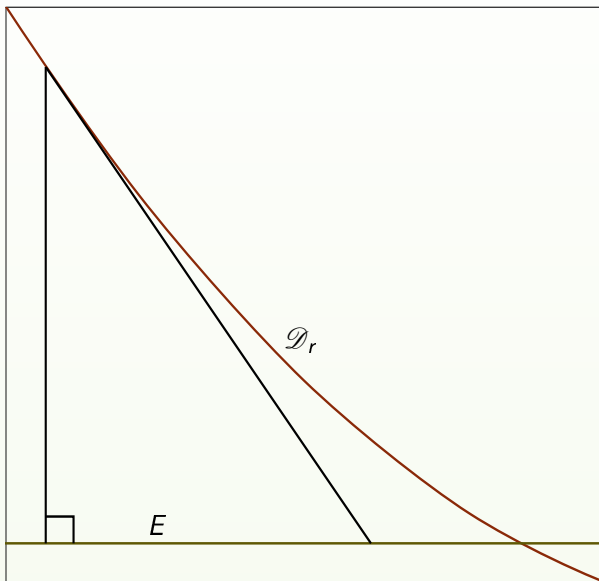
Newton's method



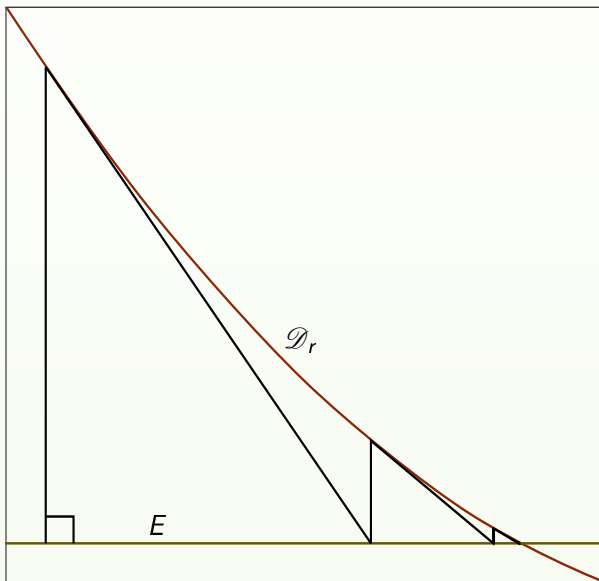
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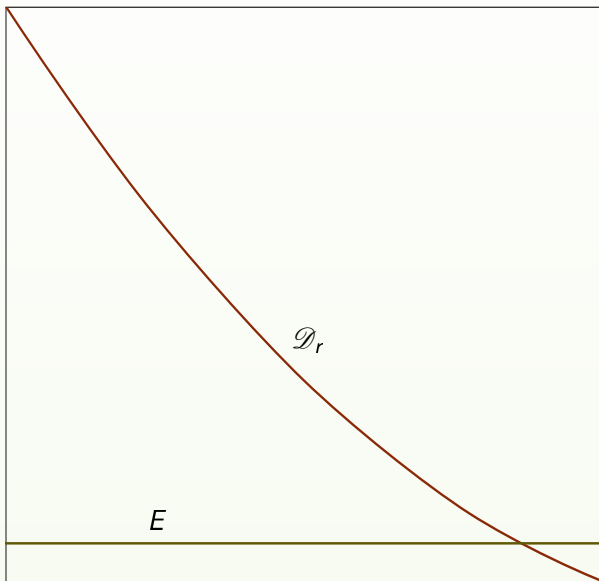


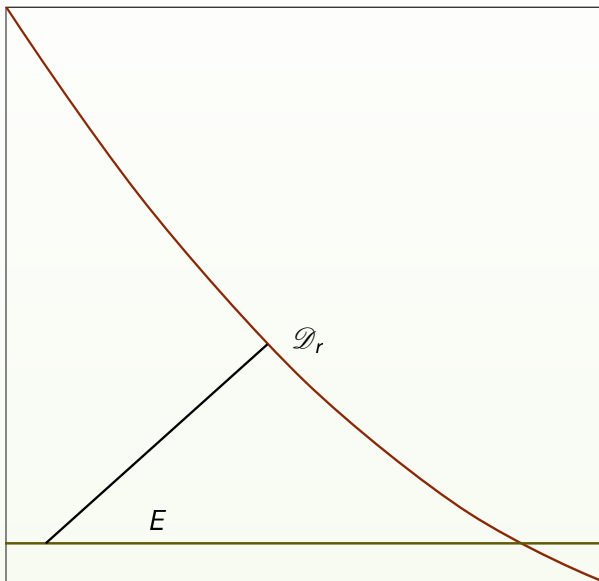
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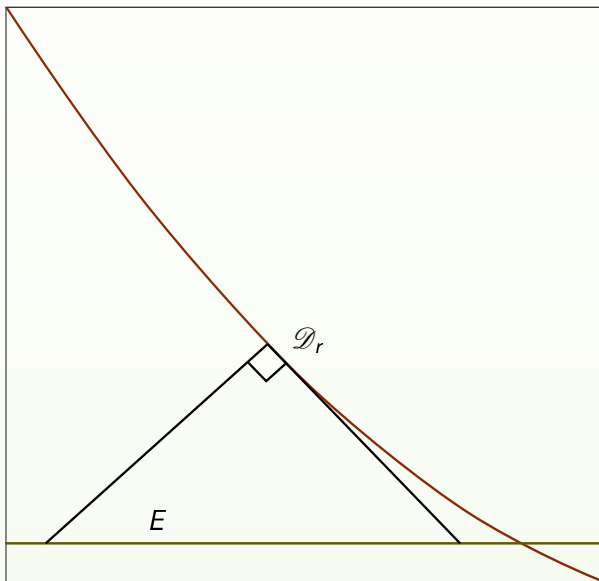


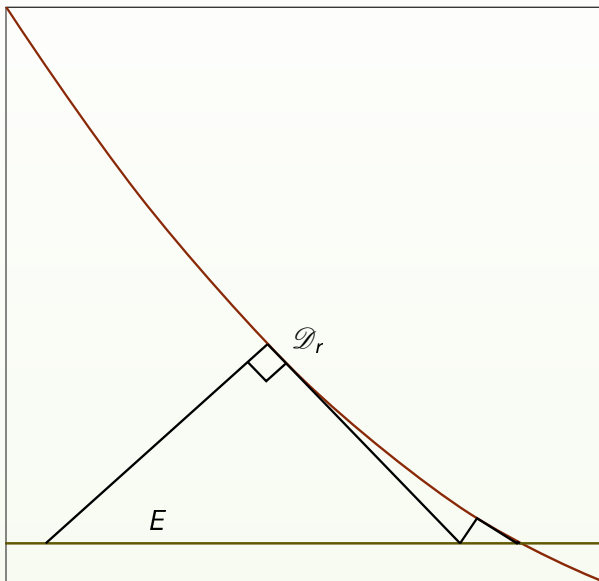
Newton's method











$\overline{\mathcal{D}}_r$: **algebraic variety** of matrices of rank **at most** r .

\rightsquigarrow well-studied in **algebraic geometry/commutative algebra**

Bruns, Conca, Eisenbud, Herzog, Lascoux, Room, Sturmfels, . . .

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Classical theorem

Let M be $p \times q$ matrix of rank r .

Then the **normal space** to \mathcal{D}_r at M is

$$\text{Ker}(M^T) \otimes \text{Ker}(M).$$

Bases of the kernels of M and M^T can be read off from the **Singular Value Decomposition** of M .

- 1: **procedure** NewtonSLRA($M \in E$, (E_1, \dots, E_d) an orthonormal basis of E , $r \in \mathbb{N}$)
- 2: $(U, S, V) \leftarrow \text{SVD}(M)$
- 3: $S_r \leftarrow r \times r$ top-left submatrix of S
- 4: $U_r \leftarrow$ first r columns of U
- 5: $V_r \leftarrow$ first r columns of V
- 6: $\tilde{M} \leftarrow U_r \cdot S_r \cdot V_r^T$
- 7: $\tilde{u}_1, \dots, \tilde{u}_{p-r} \leftarrow$ last $p - r$ columns of U
- 8: $\tilde{v}_1, \dots, \tilde{v}_{q-r} \leftarrow$ last $q - r$ columns of V
- 9: **for** $i \in \{1, \dots, p - r\}, j \in \{1, \dots, q - r\}$ **do**
- 10: $N_{(i-1)(q-r)+j} \leftarrow \tilde{u}_i \cdot \tilde{v}_j^T$
- 11: **end for**
- 12: $A \leftarrow (\langle N_i, E_j \rangle)_{i,j}$
- 13: $b \leftarrow (\langle N_i, \tilde{M} - M \rangle)_i$
- 14: **return** $M + [E_1 \ \dots \ E_d] \cdot A^\dagger \cdot b$
- 15: **end procedure**

Quadratic convergence

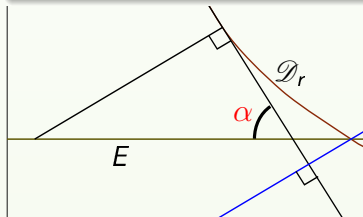
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Sketch of proof:

- lower bound for α ;
- Taylor approximation of $\Pi_{\mathcal{D}_r}$;
- manage corrective terms when $\dim(\mathcal{D}_r \cap E) > 0$.

Main features of NewtonSLRA

- Combines the **generality of alternating projections** and the **quadratic convergence of Newton's method**.
- Computationally most intensive step: **computing the SVD** (polynomial in p, q at fixed precision).
- Algorithm for SLRA with **proven quadratic rate of convergence**.

Approximate GCD

Let $m, n, d \in \mathbb{N}$, $f, g \in \mathbb{R}[x]$ with $\deg(f) = m, \deg(g) = n$.
Find $f^*, g^* \in \mathbb{R}[x]$, $\deg(f^*) = m, \deg(g^*) = n$ such that

$$\deg(\text{GCD}(f^*, g^*)) \geq d$$

and (f^*, g^*) are close to (f, g) .

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- **Euclidean distance** on the pairs (f, g) :

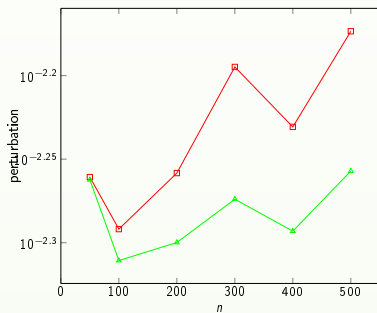
$$\left\| \left(\sum_{i=0}^m f_i x^i, \sum_{j=0}^n g_j x^j \right) \right\|^2 = \sum_{i=0}^m f_i^2 + \sum_{j=0}^n g_j^2.$$

- What does “close” mean
 - ↪ quasi-GCD, *Schönhage 85*
 - ↪ ε -GCD, *Emiris/Galligo/Lombardi 97, Zeng/Dayton 04, Bini/Boito 06-09*
 - ↪ nearest pair for a given norm, *Karmarkar/Lakshman 98, Kaltofen/Zhi/Yang 05-08, Terui 09*

Comparison with GPGCD, Terui, ISSAC'09.

iteration	sizes of iteration steps	
	NewtonSLRA	GPGCD
1	0.9e-1	0.9e-1
2	0.5e-3	0.5e-3
3	0.6e-8	0.2e-5
4	0.1e-17	0.8e-8
5	0.1e-36	0.4e-10

$n = m = 25, d = 10.$

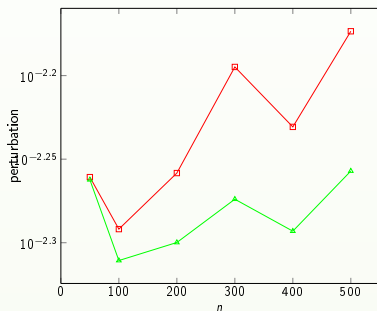


$n = m = 2d.$

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Fast convergence towards $\mathcal{D}_r \cap E$

↪ starting point for a certified **Gauss-Newton iteration**

Auroux/Chèze/Masmoudi/Yakoubsohn 06

Unknown matrix of **rank** r :

$$\begin{bmatrix} ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix}$$

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Uncover m **entries** at random.

Unknown matrix of **rank r** :

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How many entries do we need? How to reconstruct the matrix?

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Uncover m **entries** at random.

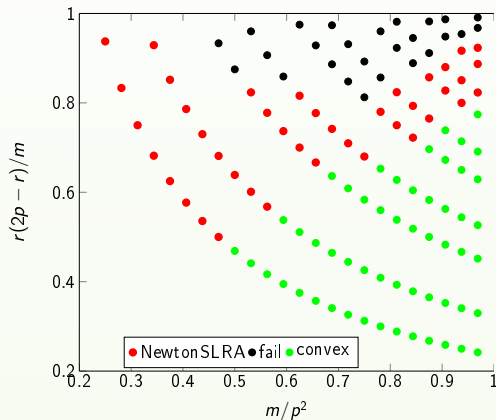
How many entries do we need? How to reconstruct the matrix?

- Algebraic structure, *Merle/Giusti, '81*
- Alternating minimization, *Jain, Netrapalli, Sanghavi, 12*
- Riemannian optimization,
Absil/Amodei/Meyer 12, Vandereycken 12
- Convex relaxation, *Candes, Tao, Plan, Recht, 09-13*

Overdetermined SLRA problems

Transversality assumption do not hold \rightsquigarrow no quadratic convergence.

Square matrix of size $p = 40$



The Euclidean distance degree

Draisma/Horobet/Ottaviani/Sturmfels/Thomas 13

$V \in \mathbb{C}^n$ an algebraic variety, $\mathbf{u} \in \mathbb{C}^n$ a generic point. The **EDdegree** of V is the number of **complex critical points** of the function

$$\lambda_1(x_1 - u_1)^2 + \cdots + \lambda_n(x_n - u_n)^2$$

on the smooth locus of V .

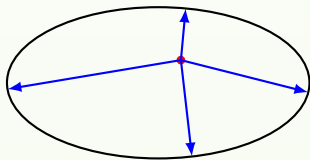
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$$\text{EDdegree}(\text{ellipse}) = 4.$$

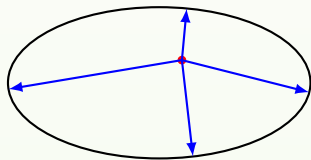
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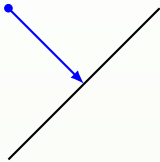


EDdegree(ellipse) = 4.

Nearest solution of SLRA:

critical point of the distance function on a **linear section of a determinantal variety** $\mathcal{D}_r \cap E$.

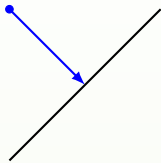
The EDdegree as a complexity measure



Line

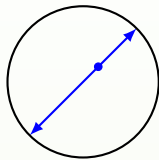
EDdegree = 1

The EDdegree as a complexity measure



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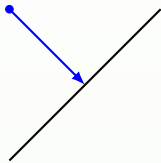
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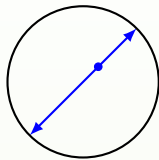
Circle

EDdegree= 2

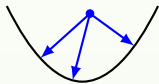
The EDdegree as a complexity measure



Line
EDdegree= 1

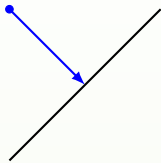


Circle
EDdegree= 2



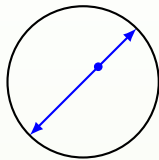
Parabola
EDdegree= 3

The EDdegree as a complexity measure



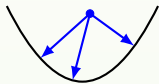
Line

EDdegree= 1



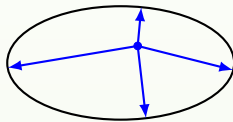
Circle

EDdegree= 2



Parabola

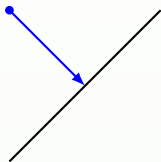
EDdegree= 3



Ellipse

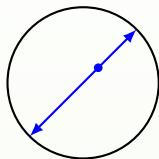
EDdegree= 4

The EDdegree as a complexity measure



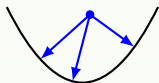
Line

EDdegree= 1



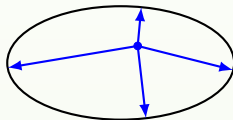
Circle

EDdegree= 2



Parabola

EDdegree= 3



Ellipse

EDdegree= 4

Strong **experimental correlation** between timings (symbolic solving with Gröbner bases) and **EDdegree**.

Structured Low-Rank Approximation:

↪ family of computationally hard problems

with (relatively) **low algebraic degree!**

Timings of Gröbner basis software (FGb, Magma):

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Goals:

- find efficient formulations as polynomial systems;
- Algebraic geometry techniques for estimating the EDdegree;
- Certification of numerical methods?

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Ottaviani/S./Sturmfels '13

Let \mathcal{L} be a **generic codimension** s linear space of $p \times q$ matrices, and V be the variety of **rank-deficient matrices** in \mathcal{L} . The **generic EDdegree** of V equals

$$\delta_0 + \cdots + \delta_{pq-2-s}.$$

where

$$\begin{aligned}\delta_\ell &= \sum_{k=\ell}^{p+q-2} (-1)^{p+q-k} \binom{k+1}{\ell+1} v_k \\ v_k &= [s^{p-1} t^{q-1}] (1+s)^p (1+t)^q (t+s)^k.\end{aligned}$$

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+ conjectured formula for the **Frobenius norm** ($\lambda_1 = \cdots = \lambda_{p,q} = 1$).

$$\begin{aligned}f(X) &= f_m X^m + \cdots + f_1 X + f_0 \\g(X) &= g_n X^n + \cdots + g_1 X + g_0 \\ \|(f, g)\|^2 &= \alpha_m f_m^2 + \cdots + \alpha_0 f_0^2 + \beta_n g_n^2 + \cdots + \beta_0 g_0^2\end{aligned}$$

$V \subset \mathbb{C}^{m+n+2}$: vanishing locus of the **resultant**.

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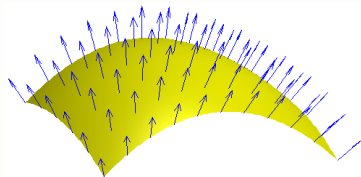
Ottaviani/S./Sturmfels '13

The **generic EDdegree** of V equals $4(m+n) - 2$.

For all weights (α, β) , the number of **locally nearest pairs** (f', g') with a non trivial GCD is bounded by $4(m+n) - 2$.

In the case of the **rotation invariant quadratic form**, we conjecture that the **ED degree** equals $2 \max(n, m)$.

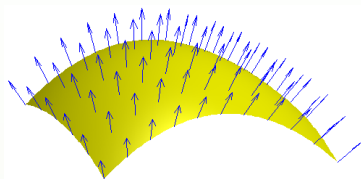
The conormal variety



Let $X \subset \mathbb{C}^n$ be an affine cone (the vanishing locus of homogeneous polynomials). The *conormal variety* $\mathcal{N}_X \subset \mathbb{C}^n \times \mathbb{C}^n$ is defined as

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\Leftrightarrow

$$\nabla \sum \lambda_i(x_i - u_i)^2 \in N_{\mathbf{x}}X$$

\Leftrightarrow

$$\begin{bmatrix} 2\lambda_1 x_1 - v_1 \\ \vdots \\ 2\lambda_n x_n - v_n \end{bmatrix} = \begin{bmatrix} 2\lambda_1 u_1 \\ \vdots \\ 2\lambda_n u_n \end{bmatrix} \quad \text{for } (\mathbf{x}, \mathbf{v}) \in \mathcal{N}_X$$

Proposition (Draisma/Horobet/Ottaviani/Sturmfels/Thomas)

The **EDdegree** of a projective variety is bounded by the **sum of the degrees of its polar classes**. Equality holds when the **diagonal** of the **conormal variety** is empty.

Duality:

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Other applications:

- low-rank approximation of **tensors**
- low-rank approximation of **Hankel matrices**

What about the **number** of **real critical points/local minima**?

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Open even for **unstructured** weighted low-rank approximation!

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Ottaviani/S./Sturmfels'13: **negative answer**

$$U = \begin{bmatrix} -59 & 11 & 59 \\ 11 & 59 & -59 \\ 59 & -59 & 11 \end{bmatrix} \quad \Lambda = \begin{bmatrix} 9 & 6 & 1 \\ 6 & 1 & 9 \\ 1 & 9 & 6 \end{bmatrix}$$

Rank 1 approximation of U has 7 local minima. EDdegree = 39, number of real critical points: 19.

Can we find **more real critical points/local minima**?

Linear sections of determinantal varieties

rich **structure** with a lot of facets
(numeric/symbolic, finite fields/characteristic 0, real solutions)
which appears in many applications.

Perspectives

- Replacing the SVD by other **rank approximation techniques** to speed up the computations
- Model of **noise**
- Impact of the choice of the **distance**
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Thank you!