

The background of the slide is white and features several black silhouettes of birds in flight. There are approximately 15 birds of various sizes and orientations scattered across the frame, some appearing to fly towards the left and others towards the right. The birds are rendered in a simple, solid black style.

January 20, 2020

INRIA Saclay

On Moment Problems with Holonomic Functions

Florent Bréhard, Mioara Joldes, Jean-Bernard Lasserre



Moments of a mesure

$$m_\alpha = \int_{\mathbb{R}^n} x^\alpha d\mu \quad \text{for } \alpha \in \mathbb{N}^{na}$$

${}^a\alpha = (\alpha_1, \dots, \alpha_n)$, $x^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$, $|\alpha| = \alpha_1 + \dots + \alpha_n$, $\mathbb{K}[x]_d =$ polynomials of total degree at most d



Moments of a mesure

$$m_\alpha = \int_{\mathbb{R}^n} x^\alpha d\mu = \int_G x^\alpha f(x) dx \quad \text{for } \alpha \in \mathbb{N}^{na}$$

- G n -dim **semi-algebraic** set, with $g \in \mathbb{K}[x]$ vanishing on ∂G
- $f : \mathbb{R}^n \rightarrow \mathbb{R}$ **D-finite** = satisfies a “complete” system of PDEs

^a $\alpha = (\alpha_1, \dots, \alpha_n)$, $x^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$, $|\alpha| = \alpha_1 + \dots + \alpha_n$, $\mathbb{K}[x]_d =$ polynomials of total degree at most d



Moments of a measure

$$m_\alpha = \int_{\mathbb{R}^n} x^\alpha d\mu = \int_G x^\alpha f(x) dx \quad \text{for } \alpha \in \mathbb{N}^{na}$$

- G n -dim **semi-algebraic** set, with $g \in \mathbb{K}[x]$ vanishing on ∂G
- $f : \mathbb{R}^n \rightarrow \mathbb{R}$ **D-finite** = satisfies a “complete” system of PDEs

^a $\alpha = (\alpha_1, \dots, \alpha_n)$, $x^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$, $|\alpha| = \alpha_1 + \dots + \alpha_n$, $\mathbb{K}[x]_d =$ polynomials of total degree at most d

- **Direct problem:** knowing G and f , find a *complete* system of recurrences for (m_α)
- ↪ **Finite determinacy** of such measures
 - ↪ Solved with **Creative Telescoping**, e.g., [Oaku2013] + Takayama's algorithm



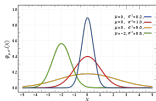
Moments of a mesure

$$m_\alpha = \int_{\mathbb{R}^n} x^\alpha d\mu = \int_G x^\alpha f(x) dx \quad \text{for } \alpha \in \mathbb{N}^{na}$$

- G n -dim **semi-algebraic** set, with $g \in \mathbb{K}[x]$ vanishing on ∂G
- $f : \mathbb{R}^n \rightarrow \mathbb{R}$ **D-finite** = satisfies a “complete” system of PDEs

${}^a\alpha = (\alpha_1, \dots, \alpha_n)$, $x^\alpha = x_1^{\alpha_1} \dots x_n^{\alpha_n}$, $|\alpha| = \alpha_1 + \dots + \alpha_n$, $\mathbb{K}[x]_d =$ polynomials of total degree at most d

- **Direct problem:** knowing G and f , find a *complete* system of recurrences for (m_α)
 - ↳ **Finite determinacy** of such measures
 - ↳ Solved with **Creative Telescoping**, e.g., [Oaku2013] + Takayama's algorithm
- **Inverse problem:** reconstruct G and/or f , given finitely many moments m_α



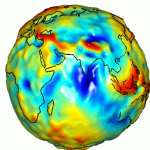
statistics



signal processing



medical imaging (MRI)



gravimetry

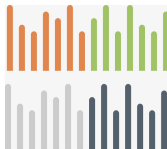


combinatorics





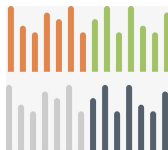
Measures



$$(m_\alpha)_{|\alpha| \leq N}$$



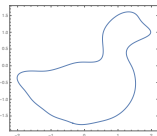
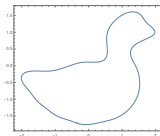
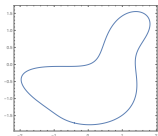
Measures



$$(m_\alpha)_{|\alpha| \leq N}$$

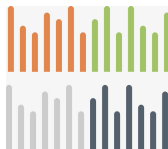


Reconstruction





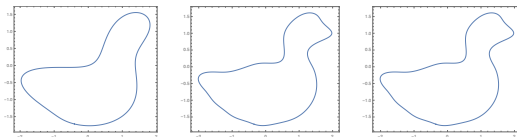
Measures



$$(m_\alpha)_{|\alpha| \leq N}$$



Reconstruction



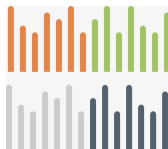
Decision



?



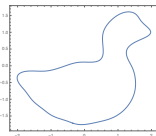
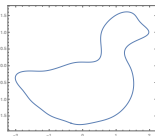
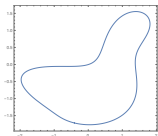
Measures



$$(m_\alpha)_{|\alpha| \leq N}$$



Reconstruction



Decision



or



?



→ Numerical methods, e.g.:

- Convex polytopes: [GolubMilanfarVarah1999] [GravinLasserrePasechnikRobins2012]
- Planar quadrature domains: [EbenfeltGustafssonKhavinsonPutinar2005]
- Sublevel sets of homogeneous polynomials: [Lasserre2013]



→ Numerical methods, e.g.:

- Convex polytopes: [GolubMilanfarVarah1999] [GravinLasserrePasechnikRobins2012]
- Planar quadrature domains: [EbenfeltGustafssonKhavinsonPutinar2005]
- Sublevel sets of homogeneous polynomials: [Lasserre2013]

→ Symbolic/algebraic methods:

- A historical starting point: Prony's method
 - reconstructing sparse exponential functions ($\sum_{\alpha \in I} \lambda_{\alpha} e^{\alpha x}$) from evaluations
 - link with moments of **Dirac** measures
- **Multivariate** extensions of Prony's method, e.g., [Mourrain2018]
- Reconstructing **univariate** piecewise D-finite densities: [Batenkov2009]

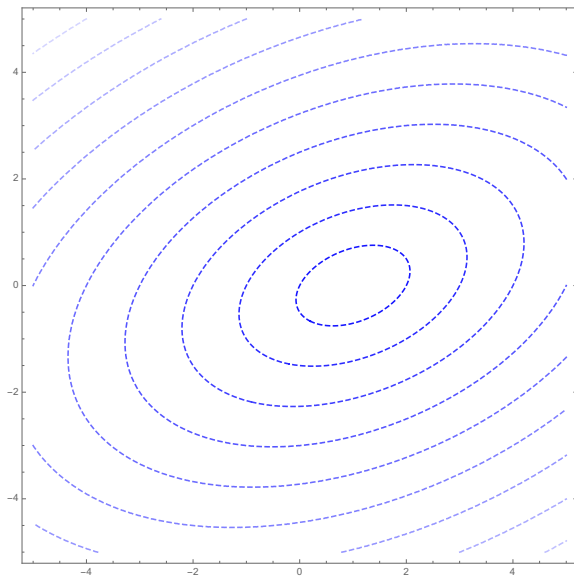


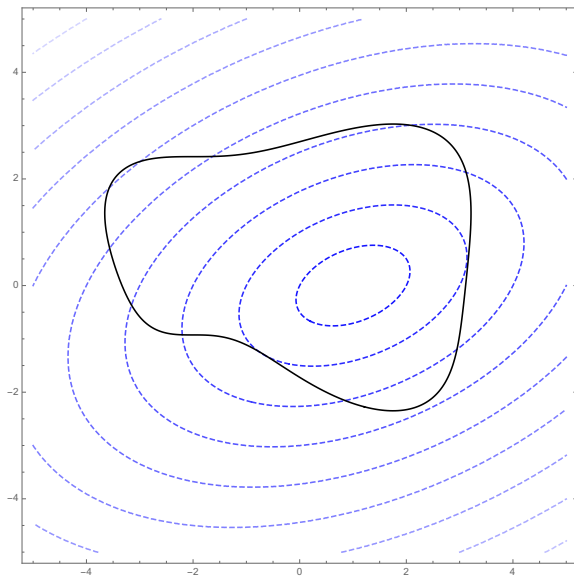
- Lasserre and Putinar's exact reconstruction algorithm (2015)

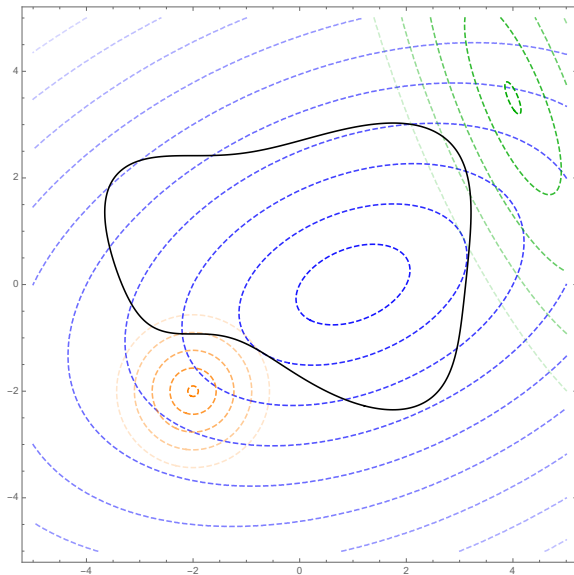
Inverse Problem: Exponential-Polynomial Measure, Algebraic Support

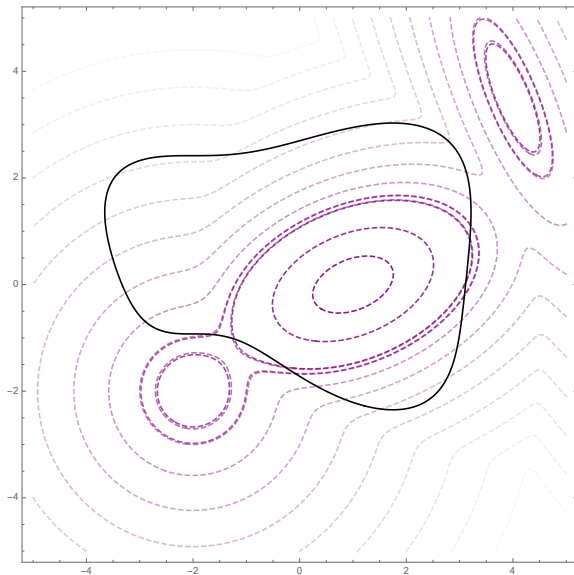
Let $G \subset \mathbb{R}^n$, bounded open set, whose algebraic boundary is included in the zero set of a polynomial $g \in \mathbb{K}[x]_d$, and $f(x) = \exp(p(x))$ with $p \in \mathbb{K}[x]_s$. Given p , degree d and moments m_α up to order $|\alpha| = 3d + s$, the coefficients of g can be exactly recovered.

- Key idea: Linear recurrences satisfied by the moments + Stokes' Theorem











- **Lasserre** and **Putinar**'s exact reconstruction algorithm (2015)

Inverse Problem: Exponential-Polynomial Measure, Algebraic Support

Let $G \subset \mathbb{R}^n$, bounded open set, whose algebraic boundary is included in the zero set of a polynomial $g \in \mathbb{K}[x]_d$, and $f(x) = \exp(p(x))$ with $p \in \mathbb{K}[x]_s$. Given p , degree d and moments m_α up to order $|\alpha| = 3d + s$, the coefficients of g can be exactly recovered.

- Key idea: Linear recurrences satisfied by the moments + Stokes' Theorem

Our contribution: a computer algebra approach

- generalization in the framework of holonomic distributions
 - ⇒ they satisfy (as a generalized function) a "complete" system of linear PDEs/ODEs with polynomial coefficients



- Lasserre and Putinar's exact reconstruction algorithm (2015)

Inverse Problem: Exponential-Polynomial Measure, Algebraic Support

Let $G \subset \mathbb{R}^n$, bounded open set, whose algebraic boundary is included in the zero set of a polynomial $g \in \mathbb{K}[x]_d$, and $f(x) = \exp(p(x))$ with $p \in \mathbb{K}[x]_s$. Given p , degree d and moments m_α up to order $|\alpha| = 3d + s$, the coefficients of g can be exactly recovered.

- Key idea: Linear recurrences satisfied by the moments + Stokes' Theorem

Our contribution: a computer algebra approach

- generalization in the framework of holonomic distributions
 - ⇒ they satisfy (as a generalized function) a "complete" system of linear PDEs/ODEs with polynomial coefficients
- exact recovery of both support and Exponential-Polynomial density $f = \exp(p)$, with explicit bound on the required number of moments
- similar algorithm for D-finite density, but no a priori bound on the required number of moments

Outline

1 Introduction

2 Holonomic Distributions and Recurrences on Moments

3 Inverse Problem: Algorithms and Proofs

- Exponential-Polynomial Densities
- The General Case with D-Finite Densities

4 Limits and Perspectives



Outline

1 Introduction

2 Holonomic Distributions and Recurrences on Moments

3 Inverse Problem: Algorithms and Proofs

- Exponential-Polynomial Densities
- The General Case with D-Finite Densities

4 Limits and Perspectives





1. Differential Ore Algebras

- Differential operators: **non-commutative**, spanned by $x_1, \partial_{x_1}, \dots, x_n, \partial_{x_n}$

$$\partial_{x_i} f = f'_{x_i} \quad (x_i f)'_{x_i} = x_i f'_{x_i} + f \quad \Rightarrow \quad \partial_{x_i} x_i = x_i \partial_{x_i} + 1$$



1. Differential Ore Algebras

- Differential operators: **non-commutative**, spanned by $x_1, \partial_{x_1}, \dots, x_n, \partial_{x_n}$

$$\partial_{x_i} f = f'_{x_i} \quad (x_i f)'_{x_i} = x_i f'_{x_i} + f \quad \Rightarrow \quad \partial_{x_i} x_i = x_i \partial_{x_i} + 1$$

- $\mathbb{K}[\mathbf{x}]\langle \partial_{\mathbf{x}} \rangle$ **polynomial** Ore algebra



1. Differential Ore Algebras

- Differential operators: **non-commutative**, spanned by $x_1, \partial_{x_1}, \dots, x_n, \partial_{x_n}$

$$\partial_{x_i} f = f'_{x_i} \quad (x_i f)'_{x_i} = x_i f'_{x_i} + f \quad \Rightarrow \quad \partial_{x_i} x_i = x_i \partial_{x_i} + 1$$

- $\mathbb{K}[x]\langle \partial_x \rangle$ **polynomial** Ore algebra vs $\mathbb{K}(x)\langle \partial_x \rangle$ **rational** Ore algebra



1. Differential Ore Algebras

- Differential operators: **non-commutative**, spanned by $x_1, \partial_{x_1}, \dots, x_n, \partial_{x_n}$

$$\partial_{x_i} f = f'_{x_i} \quad (x_i f)'_{x_i} = x_i f'_{x_i} + f \quad \Rightarrow \quad \partial_{x_i} x_i = x_i \partial_{x_i} + 1$$

- $\mathbb{K}[x]\langle \partial_x \rangle$ **polynomial** Ore algebra vs $\mathbb{K}(x)\langle \partial_x \rangle$ **rational** Ore algebra
- $\mathfrak{Ann}(f) = \{L \in \mathbb{K}(x)\langle \partial_x \rangle \mid Lf = 0\}$ PDEs satisfied by density f



1. Differential Ore Algebras

- Differential operators: **non-commutative**, spanned by $x_1, \partial_{x_1}, \dots, x_n, \partial_{x_n}$

$$\partial_{x_i} f = f'_{x_i} \quad (x_i f)'_{x_i} = x_i f'_{x_i} + f \quad \Rightarrow \quad \partial_{x_i} x_i = x_i \partial_{x_i} + 1$$

- $\mathbb{K}[x]\langle \partial_x \rangle$ **polynomial** Ore algebra vs $\mathbb{K}(x)\langle \partial_x \rangle$ **rational** Ore algebra
 - $\mathfrak{Ann}(f) = \{L \in \mathbb{K}(x)\langle \partial_x \rangle \mid Lf = 0\}$ PDEs satisfied by density f
- $\Rightarrow f$ is **D-finite** iff $\mathbb{K}(x)\langle \partial_x \rangle / \mathfrak{Ann}(f)$ has **finite** dimension over the ∂_{x_i}



1. Differential Ore Algebras

- Differential operators: **non-commutative**, spanned by $x_1, \partial_{x_1}, \dots, x_n, \partial_{x_n}$

$$\partial_{x_i} f = f'_{x_i} \quad (x_i f)'_{x_i} = x_i f'_{x_i} + f \quad \Rightarrow \quad \partial_{x_i} x_i = x_i \partial_{x_i} + 1$$

- $\mathbb{K}[x]\langle \partial_x \rangle$ **polynomial** Ore algebra vs $\mathbb{K}(x)\langle \partial_x \rangle$ **rational** Ore algebra

- $\mathfrak{Ann}(f) = \{L \in \mathbb{K}(x)\langle \partial_x \rangle \mid Lf = 0\}$ PDEs satisfied by density f

$\Rightarrow f$ is **D-finite** iff $\mathbb{K}(x)\langle \partial_x \rangle / \mathfrak{Ann}(f)$ has **finite** dimension over the ∂_{x_i}

Example: Exponential-Polynomial Density

$f(x) = c \exp(p(x))$ with $p \in \mathbb{K}_s[x]$ (e.g., Gaussian distribution)

$f'_{x_i} - p'_{x_i} f = 0 \Rightarrow \mathfrak{Ann}(f)$ generated by the $\partial_{x_i} - p'_{x_i} \Rightarrow f$ is **D-finite**



2. Difference Ore Algebras

- Difference operators: **non-commutative**, spanned by $\alpha_1, S_{\alpha_1}, \dots, \alpha_n, S_{\alpha_n}$

$$(\alpha_j u)_\alpha = \alpha_j u_\alpha \quad (S_{\alpha_j} u)_\alpha = u_{\alpha_1, \dots, \alpha_j+1, \dots, \alpha_n} \quad S_{\alpha_j} \alpha_j = (\alpha_j + 1) S_{\alpha_j}$$

- $\mathfrak{Ann}(u) = \{R \in \mathbb{K}[\alpha]\langle S_\alpha \rangle \mid R u = 0\}$ recurrences satisfied by u



2. Difference Ore Algebras

- Difference operators: **non-commutative**, spanned by $\alpha_1, S_{\alpha_1}, \dots, \alpha_n, S_{\alpha_n}$

$$(\alpha_j u)_\alpha = \alpha_j u_\alpha \quad (S_{\alpha_j} u)_\alpha = u_{\alpha_1, \dots, \alpha_j+1, \dots, \alpha_n} \quad S_{\alpha_j} \alpha_j = (\alpha_j + 1) S_{\alpha_j}$$

- $\mathfrak{Ann}(u) = \{R \in \mathbb{K}[\alpha](S_\alpha) \mid R u = 0\}$ recurrences satisfied by u

Goals

Recurrences for the moments $m_\alpha = \int_G x^\alpha f(x) dx$:

- o **Direct problem:** $\mathfrak{I} \subseteq \mathfrak{Ann}(f) \xrightarrow{?} \mathfrak{I} \subseteq \mathfrak{Ann}(m_\alpha)$
- o **Inverse problem:** Reconstruct G and $\mathfrak{I} \subseteq \mathfrak{Ann}(f)$ from sufficiently many m_α



- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$



- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

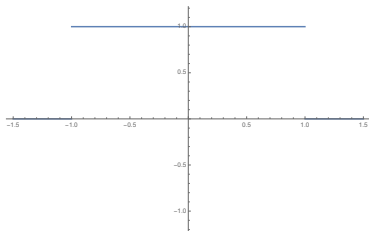
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \mathbf{1}_G, \varphi \rangle = \int_{-1}^1 \varphi(x)dx$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

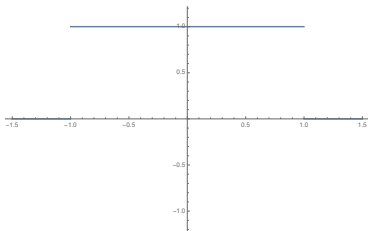
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x \mathbf{1}_G, \varphi \rangle$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

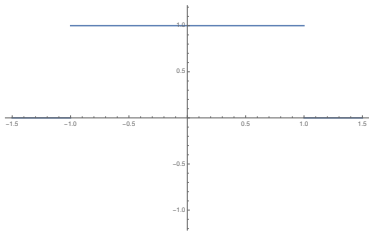
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x \varphi \rangle$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

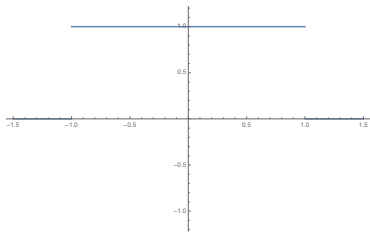
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x \varphi \rangle = - \int_{-1}^1 \varphi'(x)dx$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

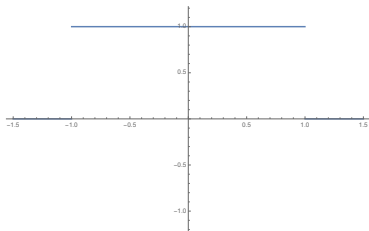
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x \varphi \rangle = \varphi(-1) - \varphi(1)$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

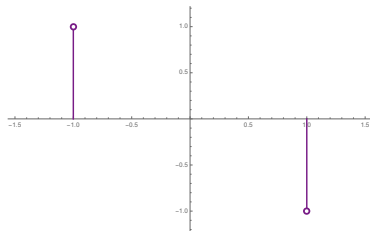
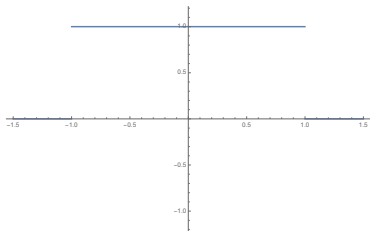
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x \varphi \rangle = \varphi(-1) - \varphi(1) \quad \Rightarrow \quad \partial_x \mathbf{1}_G = \delta_{-1} - \delta_1$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

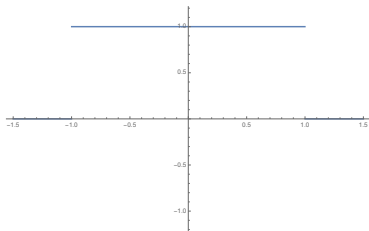
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x^2 \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, (-\partial_x)^2 \varphi \rangle = \varphi'(-1) - \varphi'(1)$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

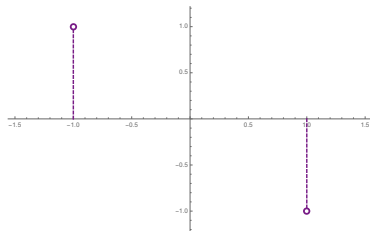
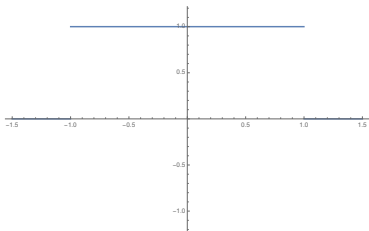
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle \partial_x^2 \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, (-\partial_x)^2 \varphi \rangle = \varphi'(-1) - \varphi'(1) \quad \Rightarrow \quad \partial_x^2 \mathbf{1}_G = \delta'_{-1} - \delta'_1$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

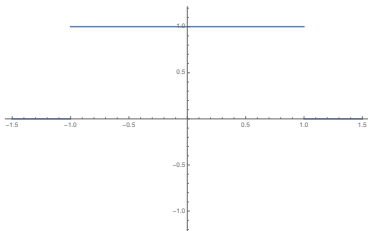
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

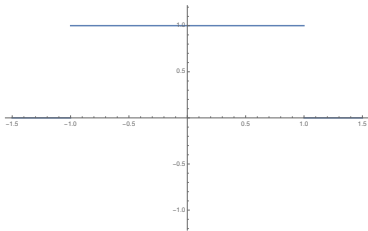
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x(x^2 - 1)\varphi \rangle$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

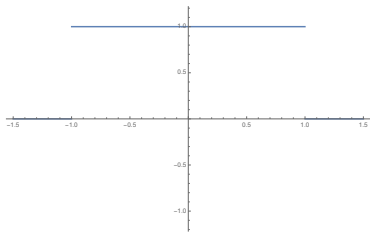
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x(x^2 - 1)\varphi \rangle = - \int_{-1}^1 ((x^2 - 1)\varphi)' dx$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

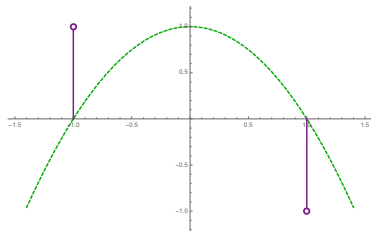
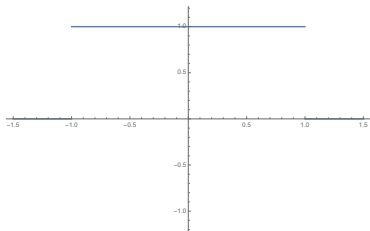
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x(x^2 - 1)\varphi \rangle = [(1 - x^2)\varphi]_{-1}^1 = 0$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

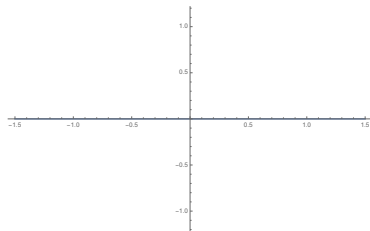
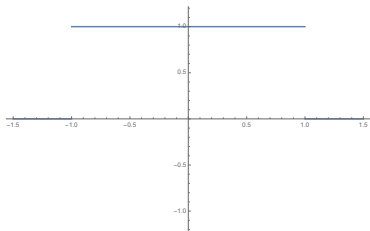
$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

- Action of Ore polynomials: $L\mu = ?$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x(x^2 - 1)\varphi \rangle = [(1 - x^2)\varphi]_{-1}^1 = 0 \Rightarrow (x^2 - 1)\partial_x \mathbf{1}_G = 0$$





- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x(x^2 - 1)\varphi \rangle = [(1 - x^2)\varphi]_{-1}^1 = 0 \Rightarrow (x^2 - 1)\partial_x \mathbf{1}_G = 0$$

- o Ore polynomials acting on **distributions**: $\langle L T, \varphi \rangle = \langle T, L^* \varphi \rangle$

$$x_i^* = x_i \quad \partial_{x_i}^* = -\partial_{x_i} \quad (L_1 L_2)^* = L_2^* L_1^*$$



- Measure $\mu = f\mathbf{1}_G$ as a linear functional:

$$\langle f\mathbf{1}_G, \varphi \rangle = \int_{\mathbb{R}^n} \varphi(x)f(x)\mathbf{1}_G(x)dx = \int_G \varphi(x)f(x)dx$$

Example: Lebesgue measure over a segment

Let $G = [-1, 1]$, $f = 1$, and $\mu = \mathbf{1}_G$

$$\langle (x^2 - 1)\partial_x \mathbf{1}_G, \varphi \rangle = \langle \mathbf{1}_G, -\partial_x(x^2 - 1)\varphi \rangle = [(1 - x^2)\varphi]_{-1}^1 = 0 \Rightarrow (x^2 - 1)\partial_x \mathbf{1}_G = 0$$

- o Ore polynomials acting on **distributions**: $\langle L T, \varphi \rangle = \langle T, L^* \varphi \rangle$

$$x_i^* = x_i \quad \partial_{x_i}^* = -\partial_{x_i} \quad (L_1 L_2)^* = L_2^* L_1^*$$

- o $\mathfrak{Ann}(T)$ in $\mathbb{K}[\mathbf{x}]\langle \partial_x \rangle \Rightarrow$ **holonomic** instead of D-finite



- Again, with $G = [-1, 1]$, and using $\varphi = x^k$:

$$0 = \langle (1 - x^2) \partial_x \mathbf{1}_G, x^k \rangle$$



- Again, with $G = [-1, 1]$, and using $\varphi = x^k$:

$$0 = \langle (1 - x^2) \partial_x \mathbf{1}_G, x^k \rangle = \langle \mathbf{1}_G, \partial_x (x^2 - 1) x^k \rangle = \int_{-1}^1 ((k+2)x^{k+1} - kx^{k-1}) dx$$



- Again, with $G = [-1, 1]$, and using $\varphi = x^k$:

$$0 = \langle (1 - x^2) \partial_x \mathbf{1}_G, x^k \rangle = \langle \mathbf{1}_G, \partial_x (x^2 - 1) x^k \rangle = \int_{-1}^1 ((k+2)x^{k+1} - kx^{k-1}) dx$$

⇒ Recurrence satisfied by the moments (m_k) :

$$(k+2)m_{k+1} - km_{k-1} = 0$$

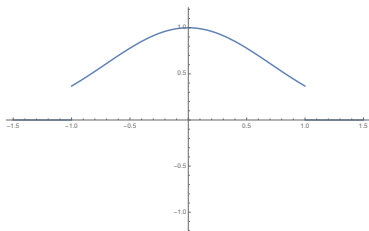
This is indeed true...

$$m_k = \int_{-1}^1 x^k dx = \begin{cases} \frac{2}{k+1} & \text{if } k \text{ even} \\ 0 & \text{if } k \text{ odd} \end{cases}$$



– $\mu = f\mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

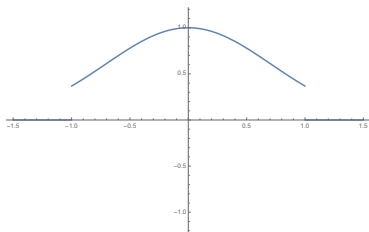
$$\langle \mu, \varphi \rangle = \int_{-1}^1 \varphi f dx$$





- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

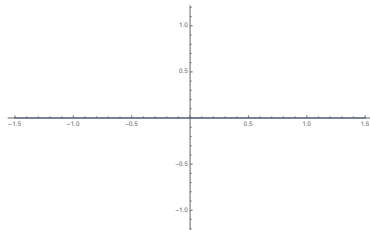
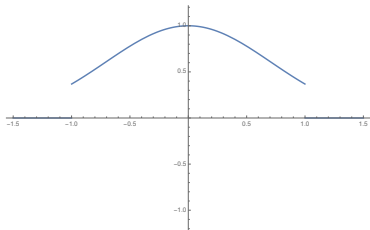
$$\int_{-1}^1 \varphi (\partial_x - 2x) f dx$$





– $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

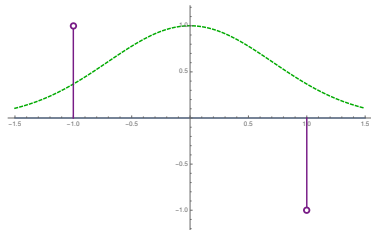
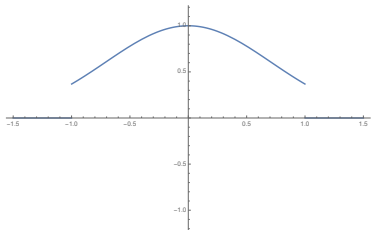
$$0 = \int_{-1}^1 \varphi \underbrace{(\partial_x - 2x)f}_{=0} dx$$





- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

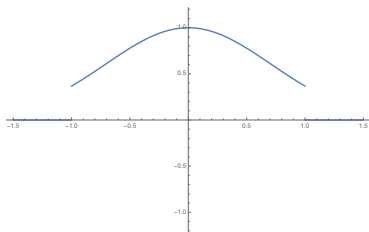
$$0 = \int_{-1}^1 \varphi \underbrace{(\partial_x - 2x)}_{=0} f \, dx = \int_{-1}^1 (-\partial_x - 2x) \varphi \, dx + [\varphi f]_{-1}^1$$





– $\mu = f1_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

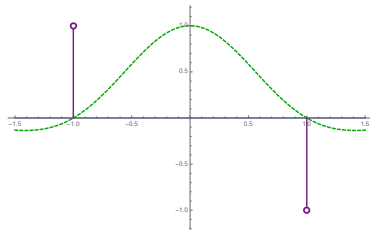
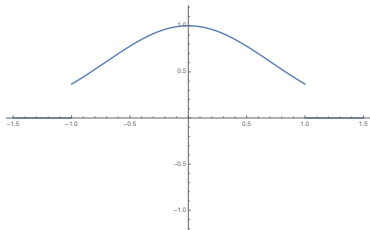
$$0 = \int_{-1}^1 \varphi \underbrace{(1-x^2)(\partial_x - 2x)f}_{=0} dx =$$





- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

$$0 = \int_{-1}^1 \varphi \underbrace{(1-x^2)(\partial_x - 2x)f}_{=0} dx = \int_{-1}^1 (\partial_x + 2x)(x^2 - 1)\varphi f dx + \underbrace{[(x^2 - 1)\varphi f]_{-1}^1}_{=0}$$

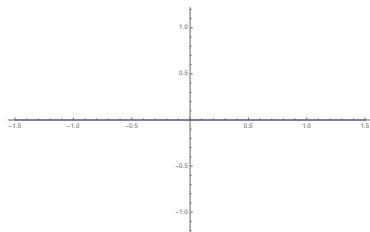
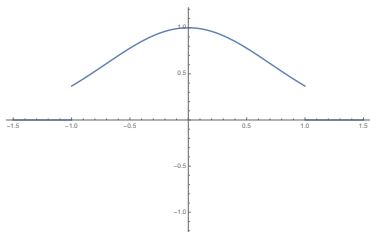




- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

$$0 = \int_{-1}^1 \varphi \underbrace{(1-x^2)(\partial_x - 2x)}_{=0} f \, dx = \int_{-1}^1 \underbrace{(\partial_x + 2x)(x^2 - 1)\varphi}_{=0} f \, dx + \underbrace{[(x^2 - 1)\varphi f]_{-1}^1}_{=0}$$

$\Rightarrow (1-x^2)(\partial_x - 2x) \in \mathfrak{Ann}(\mu)$





- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

$$0 = \int_{-1}^1 \varphi \underbrace{(1-x^2)(\partial_x - 2x)}_{=0} f \, dx = \int_{-1}^1 (\partial_x + 2x)(x^2 - 1) \varphi \, dx + \underbrace{[(x^2 - 1)\varphi f]_{-1}^1}_{=0}$$

$\Rightarrow (1-x^2)(\partial_x - 2x) \in \mathfrak{Ann}(\mu)$

- replace $\varphi = x^k$ to obtain a recurrence

$$\int_{-1}^1 (\partial_x + 2x)(x^2 - 1)x^k f(x) \, dx = 0$$



- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

$$0 = \int_{-1}^1 \varphi \underbrace{(1-x^2)(\partial_x - 2x)}_{=0} f \, dx = \int_{-1}^1 \underbrace{(\partial_x + 2x)(x^2 - 1)\varphi}_{=0} f \, dx + \underbrace{[(x^2 - 1)\varphi f]_{-1}^1}_{=0}$$

$\Rightarrow (1-x^2)(\partial_x - 2x) \in \mathfrak{Ann}(\mu)$

- replace $\varphi = x^k$ to obtain a recurrence

$$\int_{-1}^1 (2x^{k+3} + kx^{k+1} - kx^{k-1}) f(x) \, dx = 0$$



- $\mu = f \mathbf{1}_G$ with $G = [-1, 1]$ and $f(x) = \exp(-x^2)$:

$$0 = \int_{-1}^1 \varphi \underbrace{(1-x^2)(\partial_x - 2x)}_{=0} f \, dx = \int_{-1}^1 (\partial_x + 2x)(x^2 - 1) \varphi \, dx + \underbrace{[(x^2 - 1)\varphi f]_{-1}^1}_{=0}$$

$\Rightarrow (1-x^2)(\partial_x - 2x) \in \mathfrak{Ann}(\mu)$

- replace $\varphi = x^k$ to obtain a recurrence

$$\int_{-1}^1 (2x^{k+3} + kx^{k+1} - kx^{k-1}) f(x) \, dx = 0$$

\Rightarrow Recurrence for the m_k :

$$2m_{k+3} + km_{k+1} - km_{k-1} = 0$$



$\mu = f \mathbf{1}_G$, $L \in \mathbb{K}[x](\partial_x)$ of order r ,

– Use **Lagrange identity**:

$$\varphi (L f) - (L^* \varphi) f = \partial_x \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$



$$\mu = f \mathbf{1}_G, \quad L \in \mathbb{K}[x](\partial_x) \text{ of order } r, \quad x = (x_1, \dots, x_n)$$

– Use **Lagrange identity**:

$$\varphi (L f) - (L^* \varphi) f = \nabla \cdot \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$



$$\mu = f \mathbf{1}_G, \quad L \in \mathbb{K}[x](\partial_x) \text{ of order } r, \quad x = (x_1, \dots, x_n)$$

– Use **Lagrange identity**:

$$\varphi (L f) - (L^* \varphi) f = \nabla \cdot \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$

$$- \int_G \varphi (L f) dx - \int_G (L^* \varphi) f dx = \int_G \nabla \cdot \mathcal{L}_L(f, \varphi) dx$$



$$\mu = f \mathbf{1}_G, \quad L \in \mathbb{K}[x](\partial_x) \text{ of order } r, \quad x = (x_1, \dots, x_n)$$

– Use **Lagrange identity**:

$$\varphi (L f) - (L^* \varphi) f = \nabla \cdot \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$

$$- \int_G \varphi (L f) dx - \overbrace{\int_G (L^* \varphi) f dx}^{\langle L \mu, \varphi \rangle} = \int_G \nabla \cdot \mathcal{L}_L(f, \varphi) dx$$



$$\mu = f \mathbf{1}_G, \quad L \in \mathbb{K}[x](\partial_x) \text{ of order } r, \quad x = (x_1, \dots, x_n)$$

– Use **Lagrange identity**:

$$\varphi (L f) - (L^* \varphi) f = \nabla \cdot \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$

$$- \int_G \varphi (L f) dx - \overbrace{\int_G (L^* \varphi) f dx}^{\langle L \mu, \varphi \rangle} = \int_G \nabla \cdot \mathcal{L}_L(f, \varphi) dx = \int_{\partial G} \mathcal{L}_L(f, \varphi) \cdot \vec{n} dS$$

→ use **Stokes' theorem**



$$\mu = f \mathbf{1}_G, \quad L \in \mathbb{K}[x](\partial_x) \text{ of order } r, \quad x = (x_1, \dots, x_n)$$

– Use **Lagrange identity**:

$$\varphi (L f) - (L^* \varphi) f = \nabla \cdot \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$

$$\begin{aligned}
 - \int_G \mathbf{g}^r \varphi (L f) \, dx - \overbrace{\int_G (L^* \mathbf{g}^r \varphi) f \, dx}^{\langle \mathbf{g}^r L \mu, \varphi \rangle} &= \int_G \nabla \cdot \mathcal{L}_L(f, \mathbf{g}^r \varphi) \, dx = \overbrace{\int_{\partial G} \mathcal{L}_L(f, \mathbf{g}^r \varphi) \cdot \vec{n} \, dS}^{= 0} \\
 &\rightarrow \text{ where } \mathbf{g} = 0 \text{ on } \partial G \quad \rightarrow \text{ use } \mathbf{Stokes' theorem}
 \end{aligned}$$



$$\mu = f \mathbf{1}_G, \quad L \in \mathbb{K}[x](\partial_x) \text{ of order } r, \quad x = (x_1, \dots, x_n)$$

– Use **Lagrange identity**:

$$\varphi(Lf) - (L^* \varphi) f = \nabla \cdot \mathcal{L}_L(f, \varphi)$$

→ \mathcal{L}_L bilinear concomitant in f, φ with derivatives of order $\leq r - 1$

$$\begin{aligned}
 & - \overbrace{\int_G \mathbf{g}^r \varphi(Lf) dx}^{= 0} - \overbrace{\int_G (L^* \mathbf{g}^r \varphi) f dx}^{\langle \mathbf{g}^r L \mu, \varphi \rangle} = \int_G \nabla \cdot \mathcal{L}_L(f, \mathbf{g}^r \varphi) dx = \overbrace{\int_{\partial G} \mathcal{L}_L(f, \mathbf{g}^r \varphi) \cdot \vec{n} dS}^{= 0} \\
 & \quad \rightarrow \text{if } L \in \mathfrak{A} \text{Inn}(f) \quad \rightarrow \text{where } \mathbf{g} = 0 \text{ on } \partial G \quad \rightarrow \text{use Stokes' theorem}
 \end{aligned}$$

$$\Rightarrow \bar{L} = \mathbf{g}^r L \in \mathfrak{A} \text{Inn}(\mu)$$



- Translate $\bar{L} = g^r L \in \mathfrak{A}(\ln(\mu))$ into a recurrence on (m_α) :

$$x_i \rightarrow S_{\alpha_i} \qquad \partial_{x_i} \rightarrow -\alpha_i S_{\alpha_i}^{-1}$$



- Translate $\bar{L} = g^r L \in \mathfrak{Ann}(\mu)$ into a recurrence on (m_α) :

$$x_i \rightarrow S_{\alpha_i} \qquad \partial_{x_i} \rightarrow -\alpha_i S_{\alpha_i}^{-1}$$

Direct Problem

1. $\{L_1, \dots, L_k\} \subseteq \mathfrak{Ann}(f)$ D-finite
2. $\{\bar{L}_1, \dots, \bar{L}_k\} \subseteq \mathfrak{Ann}(\mu)$
3. Translate into $\{R_1, \dots, R_k\} \subseteq \mathfrak{Ann}(m_\alpha)$
4. Gröbner basis algo on $\{R_1, \dots, R_k\}$



- Translate $\bar{L} = g^r L \in \mathfrak{A}(\mu)$ into a recurrence on (m_α) :

$$x_i \rightarrow S_{\alpha_i} \qquad \partial_{x_i} \rightarrow -\alpha_i S_{\alpha_i}^{-1}$$

Direct Problem

1. $\{L_1, \dots, L_k\} \subseteq \mathfrak{A}(\mu)$ D-finite
2. $\{\bar{L}_1, \dots, \bar{L}_k\} \subseteq \mathfrak{A}(\mu)$
3. Translate into $\{R_1, \dots, R_k\} \subseteq \mathfrak{A}(m_\alpha)$
4. Gröbner basis algo on $\{R_1, \dots, R_k\}$

Theorem

If $f(x) = \exp(p(x))$ and $g = 0$ on ∂_G s.t.
 $\{x \in \mathbb{C}^n \mid g(x) = 0 \text{ and } \nabla g(x) = 0\} = \emptyset$,
 then the recurrences system is holonomic.

⇒ Conjecture for the general case?



- Translate $\bar{L} = g^r L \in \mathfrak{A}(\mu)$ into a recurrence on (m_α) :

$$x_i \rightarrow S_{\alpha_i} \qquad \partial_{x_i} \rightarrow -\alpha_i S_{\alpha_i}^{-1}$$

Direct Problem

Inverse Problem

1. $\{L_1, \dots, L_k\} \subseteq \mathfrak{A}(\mu)$ D-finite
2. $\{\bar{L}_1, \dots, \bar{L}_k\} \subseteq \mathfrak{A}(\mu)$
3. Translate into $\{R_1, \dots, R_k\} \subseteq \mathfrak{A}(m_\alpha)$
4. Gröbner basis algo on $\{R_1, \dots, R_k\}$
 - o Reconstruct \bar{L}_i , then g and L_i from the given moments m_α

\Rightarrow Translation $\bar{L}_i \leftrightarrow R_i$ is linear

\Rightarrow Holonomicity **not** needed

Theorem

If $f(x) = \exp(p(x))$ and $g = 0$ on ∂_G s.t.
 $\{x \in \mathbb{C}^n \mid g(x) = 0 \text{ and } \nabla g(x) = 0\} = \emptyset$,
 then the recurrences system is holonomic.

\Rightarrow Conjecture for the general case?

Outline

1 Introduction

2 Holonomic Distributions and Recurrences on Moments

3 Inverse Problem: Algorithms and Proofs

- Exponential-Polynomial Densities
- The General Case with D-Finite Densities

4 Limits and Perspectives





– To reconstruct g vanishing on ∂G and $L \in \mathfrak{Ann}(f)$ of order r :

1. Make an **ansatz** \tilde{L} for $\bar{L} = g^r L \in \mathfrak{Ann}(\mu)$

2. Find the coefficients of \tilde{L} by solving the **linear system**:

$$\langle \tilde{L}, \mu, x^\alpha \rangle = \langle \mu, \tilde{L}^* x^\alpha \rangle = \int_G (\tilde{L}^* x^\alpha) f(x) dx = 0, \quad |\alpha| \leq N \quad (LS_N)$$

requiring moments m_α for $|\alpha| \leq N + \dots$

3. Extract g and L from \tilde{L} using (numerical) GCDs



– To reconstruct g vanishing on ∂G and $L \in \mathfrak{Ann}(f)$ of order r :

1. Make an **ansatz** \tilde{L} for $\bar{L} = g^r L \in \mathfrak{Ann}(\mu)$

2. Find the coefficients of \tilde{L} by solving the **linear system**:

$$\langle \tilde{L} \mu, x^\alpha \rangle = \langle \mu, \tilde{L}^* x^\alpha \rangle = \int_G (\tilde{L}^* x^\alpha) f(x) dx = 0, \quad |\alpha| \leq N \quad (LS_N)$$

requiring moments m_α for $|\alpha| \leq N + \dots$

3. Extract g and L from \tilde{L} using (numerical) GCDs

– Issues to be handled:

- **False** solutions in (LS_N) : $\tilde{L} \notin \mathfrak{Ann}(\mu)$?
- How many moments m_α : **a priori bounds** on N ?
- Can g and L be always extracted from $\tilde{L} \in \mathfrak{Ann}(\mu)$?

Outline

1 Introduction

2 Holonomic Distributions and Recurrences on Moments

3 Inverse Problem: Algorithms and Proofs

- Exponential-Polynomial Densities
- The General Case with D-Finite Densities

4 Limits and Perspectives





– $\mu = f \mathbf{1}_G$ with $f(x) = \exp(p(x))$ for $p \in \mathbb{K}[x]_s$ and $g \in \mathbb{K}[x]_d$ vanishing on ∂G

$$\bar{L}_i = g(\partial_{x_i} - p'_{x_i}) \in \mathfrak{Ann}(\mu)$$



– $\mu = f \mathbf{1}_G$ with $f(x) = \exp(p(x))$ for $p \in \mathbb{K}[x]_s$ and $g \in \mathbb{K}[x]_d$ vanishing on ∂G

$$\bar{L}_i = g \partial_{x_i} - \underbrace{g p'_{x_i}}_{h_i} \in \mathfrak{Ann}(\mu)$$



– $\mu = f \mathbf{1}_G$ with $f(x) = \exp(p(x))$ for $p \in \mathbb{K}[x]_s$ and $g \in \mathbb{K}[x]_d$ vanishing on ∂G

$$\bar{L}_i = g \partial_{x_i} - \underbrace{g p'_{x_i}}_{h_i} \in \mathfrak{Ann}(\mu)$$

Algorithm RECONSTRUCTEXPOLY

Input: Moments m_α of μ for $|\alpha| \leq N + d + s - 1$

Output: Polynomials \tilde{g} and \tilde{p}



– $\mu = f \mathbf{1}_G$ with $f(x) = \exp(p(x))$ for $p \in \mathbb{K}[x]_s$ and $g \in \mathbb{K}[x]_d$ vanishing on ∂G

$$\bar{L}_i = g \partial_{x_i} - \underbrace{g p'_{x_i}}_{h_i} \in \mathfrak{Ann}(\mu)$$

Algorithm RECONSTRUCTEXPOLY

Input: Moments m_α of μ for $|\alpha| \leq N + d + s - 1$

Output: Polynomials \tilde{g} and \tilde{p}

1. Build ansatz $\tilde{L}_i = \tilde{g} \partial_{x_i} - \tilde{h}_i$ for $1 \leq i \leq n$
2. Compute coefficients of \tilde{g}, \tilde{h}_i with nontrivial solution of

$$\langle \mu, \tilde{L}_i^* x^\alpha \rangle = 0, \quad 1 \leq i \leq n, \quad |\alpha| \leq N \quad (LS_N)$$

3. $\tilde{p} \leftarrow \sum_{i=1}^n \int_0^{x_i} \tilde{p}_i(0, \dots, t_i, x_{i+1}, \dots, x_n) dt_i$ where $\tilde{p}_i = \tilde{h}_i / \tilde{g}$



– $\mu = f \mathbf{1}_G$ with $f(x) = \exp(p(x))$ for $p \in \mathbb{K}[x]_s$ and $g \in \mathbb{K}[x]_d$ vanishing on ∂G

$$\bar{L}_i = g \partial_{x_i} - \underbrace{g p'_{x_i}}_{h_i} \in \mathfrak{Ann}(\mu)$$

Algorithm RECONSTRUCTEXPOLY

Input: Moments m_α of μ for $|\alpha| \leq N + d + s - 1$

Output: Polynomials \tilde{g} and \tilde{p}

1. Build ansatz $\tilde{L}_i = \tilde{g} \partial_{x_i} - \tilde{h}_i$ for $1 \leq i \leq n$
2. Compute coefficients of \tilde{g}, \tilde{h}_i with nontrivial solution of

$$\langle \mu, \tilde{L}_i^* x^\alpha \rangle = 0, \quad 1 \leq i \leq n, \quad |\alpha| \leq N \quad (LS_N)$$

3. $\tilde{p} \leftarrow \sum_{i=1}^n \int_0^{x_i} \tilde{p}_i(0, \dots, t_i, x_{i+1}, \dots, x_n) dt_i$ where $\tilde{p}_i = \tilde{h}_i / \tilde{g}$

Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq ???$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq ???$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

2. Reconstruction of g

**Theorem — Correctness of RECONSTRUCTEXPOLY**

If $N \geq ???$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle$$

2. Reconstruction of g


Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq ???$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \int_G \varphi (\tilde{g} \partial_{x_i} - \tilde{h}_i) f dx + \int_{\partial G} \tilde{g} \varphi f \tilde{e}_i \cdot \tilde{n} dS$$

2. Reconstruction of g


Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq ???$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx + \int_{\partial G} \tilde{g} \varphi f \tilde{e}_i \cdot \tilde{n} dS$$

2. Reconstruction of g


Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

2. Reconstruction of g


Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.
1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx}_{(*)} + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

→ Hence $(*) = 0 \Rightarrow g^2(\tilde{g}p'_{x_i} - \tilde{h}_i)^2 f = 0$ on $G \Rightarrow p'_{x_i} = \tilde{h}_i/\tilde{g}$

2. Reconstruction of g



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx}_{(*)} + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

→ Hence $(*) = 0 \Rightarrow g^2(\tilde{g}p'_{x_i} - \tilde{h}_i)^2 f = 0$ on $G \Rightarrow p'_{x_i} = \tilde{h}_i/\tilde{g}$

2. Reconstruction of g



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx}_{(*)} + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

→ Hence $(*) = 0 \Rightarrow g^2(\tilde{g}p'_{x_i} - \tilde{h}_i)^2 f = 0$ on $G \Rightarrow p'_{x_i} = \tilde{h}_i/\tilde{g}$

2. Reconstruction of g

for all $\varphi \in \mathbb{K}[x]_N$:

$$\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS = 0$$



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx}_{(*)} + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

→ Hence $(*) = 0 \Rightarrow g^2(\tilde{g}p'_{x_i} - \tilde{h}_i)^2 f = 0$ on $G \Rightarrow p'_{x_i} = \tilde{h}_i/\tilde{g}$

2. Reconstruction of g

for all $\varphi \in \mathbb{K}[x]_N$:

$$\int_{\partial G} \tilde{g}\varphi f \underbrace{\tilde{e}_i \cdot \tilde{n}}_{=g'_{x_i}/\|\nabla g\|} dS = 0$$



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx}_{(*)} + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

→ Hence $(*) = 0 \Rightarrow g^2(\tilde{g}p'_{x_i} - \tilde{h}_i)^2 f = 0$ on $G \Rightarrow p'_{x_i} = \tilde{h}_i/\tilde{g}$

2. Reconstruction of g

for all $\varphi \in \mathbb{K}[x]_N$:

$$\int_{\partial G} \tilde{g}\varphi f \underbrace{\tilde{e}_i \cdot \tilde{n}}_{=g'_{x_i}/\|\nabla g\|} dS = 0$$

→ Take $\varphi = \tilde{g}g'_{x_i}$ of degree $2d - 1$



Theorem — Correctness of RECONSTRUCTEXPOLY

If $N \geq 3d + s - 1$, then RECONSTRUCTEXPOLY computes:

- $\tilde{g} = \lambda g$ with $\lambda \neq 0$
- $\tilde{p} = p - p(0)$

Proof.

1. Reconstruction of p

for all $\varphi \in \mathbb{K}[x]_N$:

$$0 = \langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi (\tilde{g}p'_{x_i} - \tilde{h}_i) f dx}_{(*)} + \underbrace{\int_{\partial G} \tilde{g}\varphi f \tilde{e}_i \cdot \tilde{n} dS}_{=0}$$

→ Take $\varphi = (\tilde{g}p'_{x_i} - \tilde{h}_i)g^2$ of degree $3d + s - 1$

→ Hence $(*) = 0 \Rightarrow g^2(\tilde{g}p'_{x_i} - \tilde{h}_i)^2 f = 0$ on $G \Rightarrow p'_{x_i} = \tilde{h}_i/\tilde{g}$

2. Reconstruction of g

for all $\varphi \in \mathbb{K}[x]_N$:

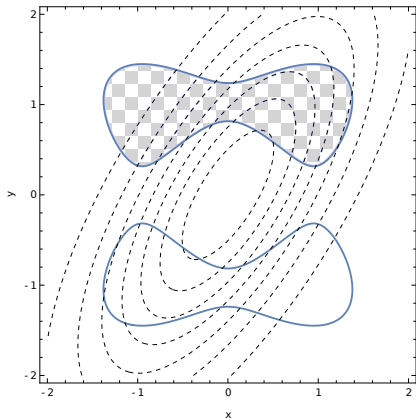
$$\int_{\partial G} \tilde{g}\varphi f \underbrace{\tilde{e}_i \cdot \tilde{n}}_{=g'_{x_i}/\|\nabla g\|} dS = 0$$

→ Take $\varphi = \tilde{g}g'_{x_i}$ of degree $2d - 1 \Rightarrow \tilde{g}^2 g'_{x_i}{}^2 \frac{f}{\|\nabla g\|} = 0$ on $\partial G \Rightarrow \tilde{g} = 0$ on ∂G



→ Reconstruction of:

$$f(x, y) = \exp(-x^2 + xy - y^2/2) \quad \text{and} \quad g(x, y) = (x^2 - 9/10)^2 + (y^2 - 11/10)^2 - 1$$

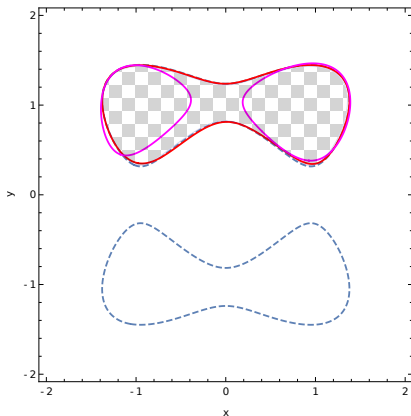


Moments $(m_{ij})_{i+j \leq 18}$ with **10** digits of accuracy



→ Reconstruction of:

$$f(x, y) = \exp(-x^2 + xy - y^2/2) \quad \text{and} \quad g(x, y) = (x^2 - 9/10)^2 + (y^2 - 11/10)^2 - 1$$

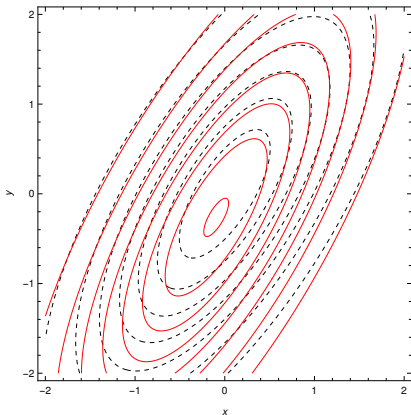


Moments $(m_{ij})_{i+j \leq 18}$ with **4, 6, 8** digits of accuracy



→ Reconstruction of:

$$f(x, y) = \exp(-x^2 + xy - y^2/2) \quad \text{and} \quad g(x, y) = (x^2 - 9/10)^2 + (y^2 - 11/10)^2 - 1$$



Moments $(m_{ij})_{i+j \leq 18}$ with **8** digits of accuracy

Outline

1 Introduction

2 Holonomic Distributions and Recurrences on Moments

3 Inverse Problem: Algorithms and Proofs

- Exponential-Polynomial Densities
- The General Case with D-Finite Densities

4 Limits and Perspectives





- $\mu = f \mathbf{1}_G$ with $g \in \mathbb{K}[x]_d$ vanishing on ∂G , and $\{L_1, \dots, L_n\}$ **rectangular** system for f :

$$L_i = q_{ir_i} \partial_{x_i}^{r_i} + \dots + q_{i1} \partial_{x_i} + q_{i0} \in \mathfrak{Ann}(f) \cap \mathbb{K}[x] \langle \partial_{x_i} \rangle$$



- $\mu = f \mathbf{1}_G$ with $g \in \mathbb{K}[x]_d$ vanishing on ∂G , and $\{L_1, \dots, L_n\}$ **rectangular** system for f :

$$\bar{L}_i = \mathbf{g}^{r_i} (q_{ir_i} \partial_{x_i}^{r_i} + \dots + q_{i1} \partial_{x_i} + q_{i0}) \in \mathfrak{Ann}(\mu) \cap \mathbb{K}[x] \langle \partial_{x_i} \rangle \quad h_{ij} = \mathbf{g}^{r_i} q_{ij} \in \mathbb{K}[x]_s$$



- $\mu = f \mathbf{1}_G$ with $g \in \mathbb{K}[x]_d$ vanishing on ∂G , and $\{L_1, \dots, L_n\}$ **rectangular** system for f :

$$\bar{L}_i = g^{r_i} (q_{ir_i} \partial_{x_i}^{r_i} + \dots + q_{i1} \partial_{x_i} + q_{i0}) \in \mathfrak{Ann}(\mu) \cap \mathbb{K}[x] \langle \partial_{x_i} \rangle \quad h_{ij} = g^{r_i} q_{ij} \in \mathbb{K}[x]_s$$

Algorithm RECONSTRUCTDENSITY

Input: Moments m_α of μ for $|\alpha| \leq N + s$

Output: A rectangular system $\{\tilde{L}_1, \dots, \tilde{L}_n\}$ for f



- $\mu = f \mathbf{1}_G$ with $g \in \mathbb{K}[x]_d$ vanishing on ∂G , and $\{L_1, \dots, L_n\}$ **rectangular** system for f :

$$\tilde{L}_i = g^{r_i} (q_{ir_i} \partial_{x_i}^{r_i} + \dots + q_{i1} \partial_{x_i} + q_{i0}) \in \mathfrak{Ann}(\mu) \cap \mathbb{K}[x] \langle \partial_{x_i} \rangle \quad h_{ij} = g^{r_i} q_{ij} \in \mathbb{K}[x]_s$$

Algorithm RECONSTRUCTDENSITY

Input: Moments m_α of μ for $|\alpha| \leq N + s$

Output: A rectangular system $\{\tilde{L}_1, \dots, \tilde{L}_n\}$ for f

1. Build ansatz $\tilde{L}_i = \tilde{h}_{ir_i} \partial_{x_i}^{r_i} + \dots + \tilde{h}_{i0}$ for $1 \leq i \leq n$
2. Compute coefficients of \tilde{h}_{ij} with nontrivial solution of

$$\langle \mu, \tilde{L}_i^* x^\alpha \rangle = 0, \quad 1 \leq i \leq n, \quad |\alpha| \leq N$$
3. Extract (numerical) GCD polynomial factor in \tilde{L}_i



– $\mu = f \mathbf{1}_G$ with $g \in \mathbb{K}[x]_d$ vanishing on ∂G , and $\{L_1, \dots, L_n\}$ **rectangular** system for f :

$$\bar{L}_i = g^{r_i} (q_{ir_i} \partial_{x_i}^{r_i} + \dots + q_{i1} \partial_{x_i} + q_{i0}) \in \mathfrak{Ann}(\mu) \cap \mathbb{K}[x] \langle \partial_{x_i} \rangle \quad h_{ij} = g^{r_i} q_{ij} \in \mathbb{K}[x]_s$$

Algorithm RECONSTRUCTDENSITY

Input: Moments m_α of μ for $|\alpha| \leq N + s$

Output: A rectangular system $\{\tilde{L}_1, \dots, \tilde{L}_n\}$ for f

1. Build ansatz $\tilde{L}_i = \tilde{h}_{ir_i} \partial_{x_i}^{r_i} + \dots + \tilde{h}_{i0}$ for $1 \leq i \leq n$
2. Compute coefficients of \tilde{h}_{ij} with nontrivial solution of

$$\langle \mu, \tilde{L}_i^* x^\alpha \rangle = 0, \quad 1 \leq i \leq n, \quad |\alpha| \leq N$$

3. Extract (numerical) GCD polynomial factor in \tilde{L}_i

Algorithm RECONSTRUCTSUPPORT

Input: Rectangular $\{L_1, \dots, L_n\}$ and m_α for $|\alpha| \leq N + dr + \max_{ij} \{\deg(q_{ij}) - j\}$

Output: Polynomial $\tilde{g} \in \mathbb{K}[x]_d$



- $\mu = f \mathbf{1}_G$ with $g \in \mathbb{K}[x]_d$ vanishing on ∂G , and $\{L_1, \dots, L_n\}$ **rectangular** system for f :

$$\bar{L}_i = g^{r_i} (q_{ir_i} \partial_{x_i}^{r_i} + \dots + q_{i1} \partial_{x_i} + q_{i0}) \in \mathfrak{Ann}(\mu) \cap \mathbb{K}[x] \langle \partial_{x_i} \rangle \quad h_{ij} = g^{r_i} q_{ij} \in \mathbb{K}[x]_s$$

Algorithm RECONSTRUCTDENSITY

Input: Moments m_α of μ for $|\alpha| \leq N + s$

Output: A rectangular system $\{\tilde{L}_1, \dots, \tilde{L}_n\}$ for f

1. Build ansatz $\tilde{L}_i = \tilde{h}_{ir_i} \partial_{x_i}^{r_i} + \dots + \tilde{h}_{i0}$ for $1 \leq i \leq n$
2. Compute coefficients of \tilde{h}_{ij} with nontrivial solution of

$$\langle \mu, \tilde{L}_i^* x^\alpha \rangle = 0, \quad 1 \leq i \leq n, \quad |\alpha| \leq N$$
3. Extract (numerical) GCD polynomial factor in \tilde{L}_i

Algorithm RECONSTRUCTSUPPORT

Input: Rectangular $\{L_1, \dots, L_n\}$ and m_α for $|\alpha| \leq N + dr + \max_{ij} \{\deg(q_{ij}) - j\}$

Output: Polynomial $\tilde{g} \in \mathbb{K}[x]_d$

1. Compute coefficients of ansatz $\tilde{h} \in \mathbb{K}[x]_{dr}$ with nontrivial solution of

$$\langle \mu, (\tilde{h} L_i)^* x^\alpha \rangle = 0, \quad 1 \leq i \leq n, \quad |\alpha| \leq N$$
2. $\tilde{g} \leftarrow$ (numerical) GCD of $\{\tilde{h}, \tilde{h}'_{x_1}, \dots, \tilde{h}'_{x_n}\}$



Theorem — Correctness of RECONSTRUCTDENSITY

For N large enough, the rectangular system $\{\tilde{L}_1, \dots, \tilde{L}_n\}$ computed by RECONSTRUCTDENSITY is in $\mathfrak{Ann}(f)$.



Theorem — Correctness of RECONSTRUCTDENSITY

For N large enough, the rectangular system $\{\tilde{L}_1, \dots, \tilde{L}_n\}$ computed by RECONSTRUCTDENSITY is in $\mathfrak{Ann}(f)$.

Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever $q_{ir} \neq 0$ on ∂G and $N \geq (2r - 1)d + (d - 1)b + s$ where:

- $r = \max_{1 \leq i \leq n} r_i$, orders of the L_i
- $b = r \bmod 2$
- $s = \max_{1 \leq i \leq n} \{\deg(q_{ir})\}$ maximal degree of the head coefficients



Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

Proof.



Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

Proof.

$$- 0 = \langle \tilde{h}L_i\mu, \varphi \rangle$$

for $\varphi \in \mathbb{K}[x]_N$

**Theorem — Correctness of RECONSTRUCTSUPPORT**

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \int_G \varphi \tilde{h}(L_i f) dx - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h} \varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

**Theorem — Correctness of RECONSTRUCTSUPPORT**

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h}(L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$


Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h} (L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h} \varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

- Suppose for contradiction that $\tilde{h} = g^k h_0$ with $g \nmid h_0$ and $k < r$


Theorem — Correctness of RECONSTRUCTSUPPORT

 RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h} (L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h} \varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

 - Suppose for contradiction that $\tilde{h} = g^k h_0$ with $g \nmid h_0$ and $k < r$

$$\begin{aligned} \mathcal{L}_{L_i}(f, \tilde{h} \varphi) &= f [q_{i1} \tilde{h} \varphi - \partial_{x_i}(q_{i2} \tilde{h} \varphi) + \dots + (-1)^{r-1} \partial_{x_i}^{r-1}(q_{ir} \tilde{h} \varphi)] \\ &\quad + \partial_{x_i}(f) [q_{i2} \tilde{h} \varphi - \partial_{x_i}(q_{i3} \tilde{h} \varphi) + \dots + (-1)^{r-2} \partial_{x_i}^{r-2}(q_{ir} \tilde{h} \varphi)] \\ &\quad + \dots \\ &\quad + \partial_{x_i}^{r-1}(f) q_{ir} \tilde{h} \varphi. \end{aligned}$$


Theorem — Correctness of RECONSTRUCTSUPPORT

 RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

- $N \geq (2r-1)d + (d-1)b + s$

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h}(L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

 - Suppose for contradiction that $\tilde{h} = g^k h_0$ with $g \nmid h_0$ and $k < r$

$$\begin{aligned} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) &= f [q_{i1} \tilde{h}\varphi - \partial_{x_i}(q_{i2} \tilde{h}\varphi) + \dots + (-1)^{r-1} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \partial_{x_i}(f) [q_{i2} \tilde{h}\varphi - \partial_{x_i}(q_{i3} \tilde{h}\varphi) + \dots + (-1)^{r-2} \partial_{x_i}^{r-2}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \dots \\ &\quad + \partial_{x_i}^{r-1}(f) q_{ir} \tilde{h}\varphi. \end{aligned}$$

 → Take $\varphi = q_{ir} h_0 g^{r-1-k} \tilde{g}'_{x_i}{}^b$ of deg $\leq (2r-1)d + (d-1)\overset{r \bmod 2}{\tilde{b}} + s$, so that $g^{r-1} \mid \tilde{h}\varphi$



Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

- $N \geq (2r - 1)d + (d - 1)b + s$

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h}(L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

- Suppose for contradiction that $\tilde{h} = g^k h_0$ with $g \nmid h_0$ and $k < r$

$$\begin{aligned} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) &= f [q_{i1} \tilde{h}\varphi - \partial_{x_i}(q_{i2} \tilde{h}\varphi) + \dots + (-1)^{r-1} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \partial_{x_i}(f) [q_{i2} \tilde{h}\varphi - \partial_{x_i}(q_{i3} \tilde{h}\varphi) + \dots + (-1)^{r-2} \partial_{x_i}^{r-2}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \dots \\ &\quad + \partial_{x_i}^{r-1}(f) q_{ir} \tilde{h}\varphi. \end{aligned}$$

→ Take $\varphi = q_{ir} h_0 g^{r-1-k} \tilde{g}_{x_i}^b$ of deg $\leq (2r - 1)d + (d - 1)b + s$, so that $g^{r-1} \mid \tilde{h}\varphi$

$$\rightarrow 0 = \int_{\partial G} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi) \frac{\tilde{g}_{x_i}^b}{\|\nabla g\|} f dS$$



Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

- $N \geq (2r-1)d + (d-1)b + s$

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h} (L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

– Suppose for contradiction that $\tilde{h} = g^k h_0$ with $g \nmid h_0$ and $k < r$

$$\begin{aligned} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) &= f [q_{i1} \tilde{h}\varphi - \partial_{x_i}(q_{i2} \tilde{h}\varphi) + \dots + (-1)^{r-1} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \partial_{x_i}(f) [q_{i2} \tilde{h}\varphi - \partial_{x_i}(q_{i3} \tilde{h}\varphi) + \dots + (-1)^{r-2} \partial_{x_i}^{r-2}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \dots \\ &\quad + \partial_{x_i}^{r-1}(f) q_{ir} \tilde{h}\varphi. \end{aligned}$$

→ Take $\varphi = q_{ir} h_0 g^{r-1-k} \widetilde{g'_{x_i}}^b$ of deg $\leq (2r-1)d + (d-1)b + s$, so that $g^{r-1} \mid \tilde{h}\varphi$

$$\rightarrow 0 = \int_{\partial G} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi) \frac{\widetilde{g'_{x_i}}^b}{\|\nabla g\|} f dS = (r-1)! \int_{\partial G} \left(\widetilde{g'_{x_i}}^{\frac{r+b}{2}} q_{ir} h_0 \right)^2 \frac{f}{\|\nabla g\|} dS$$



Theorem — Correctness of RECONSTRUCTSUPPORT

RECONSTRUCTSUPPORT computes $\tilde{g} = \lambda g$ with $\lambda \neq 0$ whenever:

- $N \geq (2r-1)d + (d-1)b + s$
- $q_{ir} \neq 0$ on ∂G

Proof.

$$- 0 = \langle \tilde{h} L_i \mu, \varphi \rangle = \underbrace{\int_G \varphi \tilde{h} (L_i f) dx}_{=0} - \int_{\partial G} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) \tilde{e}_i \cdot \tilde{n} dS \quad \text{for } \varphi \in \mathbb{K}[x]_N$$

– Suppose for contradiction that $\tilde{h} = g^k h_0$ with $g \nmid h_0$ and $k < r$

$$\begin{aligned} \mathcal{L}_{L_i}(f, \tilde{h}\varphi) &= f [q_{i1} \tilde{h}\varphi - \partial_{x_i}(q_{i2} \tilde{h}\varphi) + \dots + (-1)^{r-1} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \partial_{x_i}(f) [q_{i2} \tilde{h}\varphi - \partial_{x_i}(q_{i3} \tilde{h}\varphi) + \dots + (-1)^{r-2} \partial_{x_i}^{r-2}(q_{ir} \tilde{h}\varphi)] \\ &\quad + \dots \\ &\quad + \partial_{x_i}^{r-1}(f) q_{ir} \tilde{h}\varphi. \end{aligned}$$

→ Take $\varphi = q_{ir} h_0 g^{r-1-k} \widetilde{g'_{x_i}}^b$ of deg $\leq (2r-1)d + (d-1)b + s$, so that $g^{r-1} \mid \tilde{h}\varphi$

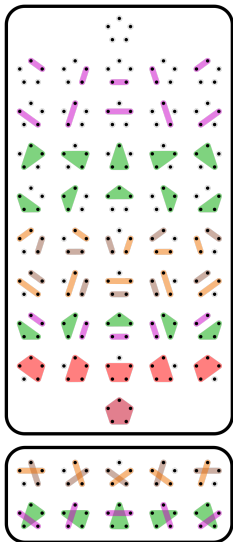
$$\rightarrow 0 = \int_{\partial G} \partial_{x_i}^{r-1}(q_{ir} \tilde{h}\varphi) \frac{\widetilde{g'_{x_i}}^b}{\|\nabla g\|} f dS = (r-1)! \int_{\partial G} \left(\widetilde{g'_{x_i}}^{\frac{r+b}{2}} q_{ir} h_0 \right)^2 \frac{f}{\|\nabla g\|} dS$$

⇒ **Contradiction:** $h_0 = 0$ on ∂G , hence $g \mid h_0$



→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

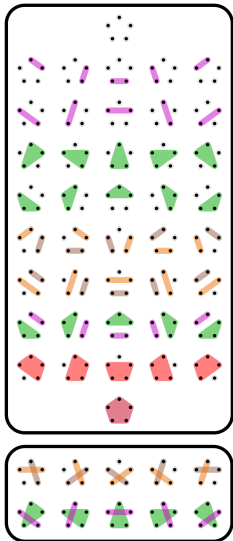




→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

$$(n+2)C_{n+1} - (4n+2)C_n = 0$$





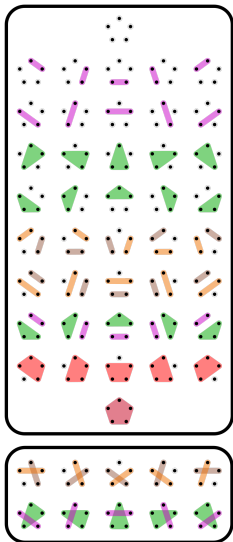
→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

– Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$(n+2)S_n - (4n+2)$$





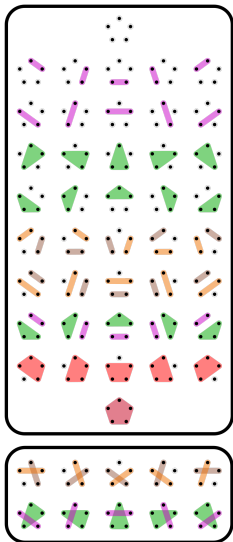
→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

– Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$S_n(n+1) - 4(n+1) + 2$$





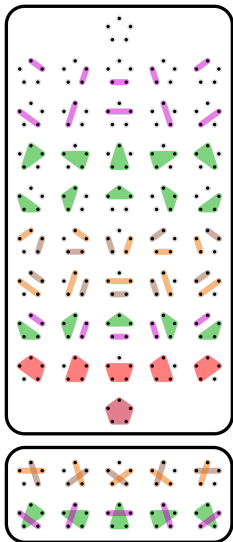
→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

– Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$S_n^2 S_n^{-1}(n+1) - 4S_n S_n^{-1}(n+1) + 2$$





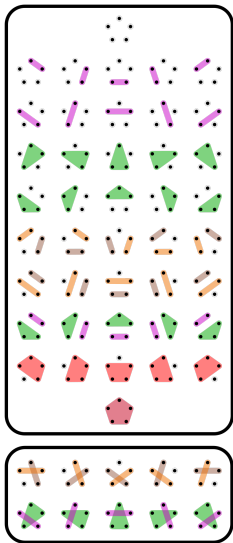
→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

- Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$\underbrace{S_n^2}_{x^2} \underbrace{S_n^{-1}(n+1)}_{-\partial_x} - 4 \underbrace{S_n}_x \underbrace{S_n^{-1}(n+1)}_{-\partial_x} + 2$$





→ Express **Catalan numbers** as moments of a measure μ :

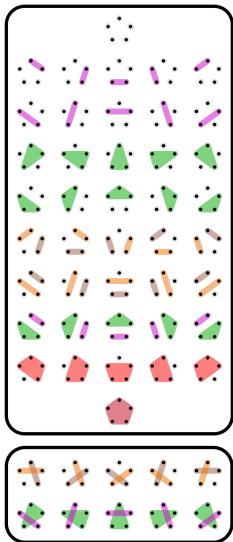
$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

- Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$\underbrace{S_n^2}_{x^2} \underbrace{S_n^{-1}(n+1)}_{-\partial_x} - 4 \underbrace{S_n}_x \underbrace{S_n^{-1}(n+1)}_{-\partial_x} + 2$$

$$\Rightarrow (4x - x^2)\partial_x + 2 \in \mathfrak{Ann}(\mu)$$





→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

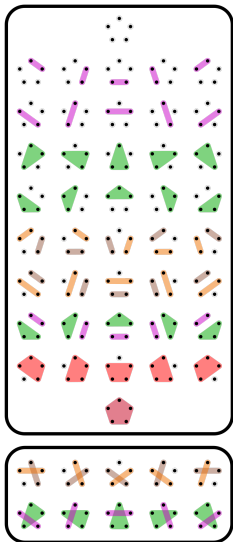
$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

- Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$\underbrace{S_n^2}_{x^2} \underbrace{S_n^{-1}(n+1)}_{-\partial_x} - 4 \underbrace{S_n}_x \underbrace{S_n^{-1}(n+1)}_{-\partial_x} + 2$$

$$\Rightarrow (4x - x^2)\partial_x + 2 \in \mathfrak{Ann}(\mu) \quad g = 1 ?$$

$$C_n = \lambda \int_{-\infty}^{+\infty} x^n \sqrt{\frac{4-x}{x}} dx \quad ?$$





→ Express **Catalan numbers** as moments of a measure μ :

$$C_n = \frac{1}{n+1} \binom{2n}{n} \stackrel{?}{=} \int_I x^n f(x) dx$$

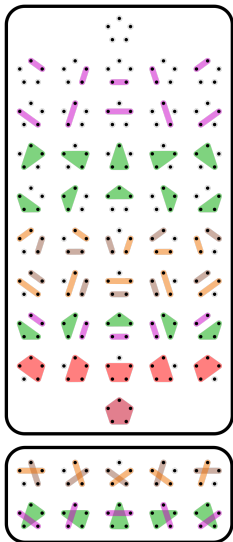
$$(n+2)C_{n+1} - (4n+2)C_n = 0$$

- Reverse translation $x \leftarrow S_n$ and $\partial_x \leftarrow -S_n^{-1}(n+1)$:

$$\underbrace{S_n^2}_{x^2} \underbrace{S_n^{-1}(n+1)}_{-\partial_x} - 4 \underbrace{S_n}_x \underbrace{S_n^{-1}(n+1)}_{-\partial_x} + 2$$

$$\Rightarrow (4x - x^2)\partial_x + 2 \in \mathfrak{Ann}(\mu) \quad \mathbf{g=-1?}$$

$$C_n = \frac{1}{2\pi} \int_0^4 x^n \sqrt{\frac{4-x}{x}} dx \quad ?$$



Outline

1 Introduction

2 Holonomic Distributions and Recurrences on Moments

3 Inverse Problem: Algorithms and Proofs

- Exponential-Polynomial Densities
- The General Case with D-Finite Densities

4 Limits and Perspectives





- A priori bounds for N in the general case with unknown D-finite density?
- Full determination of the density, including initial conditions
- Extracting the component of $V(g)$ corresponding to ∂G



– Is there an explicit bound N_0 on N s.t. for ansatz \tilde{L} of $\bar{L} = g^r L$:

$$\langle \tilde{L}\mu, \varphi \rangle = 0 \quad \text{for all } \varphi \in \mathbb{K}[x]_N \quad \Rightarrow \quad \tilde{L}\mu = 0 \quad \text{when } N \geq N_0 \quad ?$$



- Is there an explicit bound N_0 on N s.t. for ansatz \tilde{L} of $\bar{L} = g^r L$:

$$\langle \tilde{L}\mu, \varphi \rangle = 0 \quad \text{for all } \varphi \in \mathbb{K}[x]_N \quad \Rightarrow \quad \tilde{L}\mu = 0 \quad \text{when } N \geq N_0 \quad ?$$

- The proof of the Exp-Poly density case doesn't generalize:

$$\langle \tilde{L}\mu, \varphi \rangle = \int_G \varphi(\tilde{L}f) dx - \int_{\partial G} \mathcal{L}_{\tilde{L}}(f, \varphi) \cdot \bar{n} dS$$



- Is there an explicit bound N_0 on N s.t. for ansatz \tilde{L} of $\bar{L} = g^r L$:

$$\langle \tilde{L}\mu, \varphi \rangle = 0 \quad \text{for all } \varphi \in \mathbb{K}[x]_N \quad \Rightarrow \quad \tilde{L}\mu = 0 \quad \text{when } N \geq N_0 \quad ?$$

- The proof of the Exp-Poly density case doesn't generalize:

$$\langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi(\tilde{L}f) dx}_{???} - \int_{\partial G} \mathcal{L}_{\tilde{L}}(f, \varphi) \cdot \bar{n} dS$$



- Is there an explicit bound N_0 on N s.t. for ansatz \tilde{L} of $\bar{L} = g^r L$:

$$\langle \tilde{L}\mu, \varphi \rangle = 0 \quad \text{for all } \varphi \in \mathbb{K}[x]_N \quad \Rightarrow \quad \tilde{L}\mu = 0 \quad \text{when } N \geq N_0 \quad ?$$

- The proof of the Exp-Poly density case doesn't generalize:

$$\langle \tilde{L}\mu, \varphi \rangle = \underbrace{\int_G \varphi(\tilde{L}f) dx}_{???} - \int_{\partial G} \mathcal{L}_{\tilde{L}}(f, \varphi) \cdot \vec{n} dS$$

- Such a bound N_0 depending only on the structure of \tilde{L} cannot exist:

Example [Batenkov2009] — Legendre Polynomials P_n over $[-1, 1]$

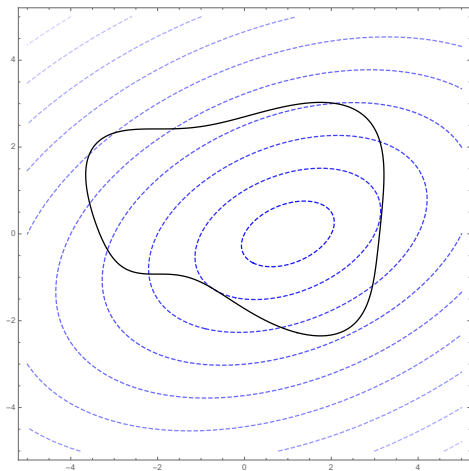
$P_n(x)$ annihilated by $L_n = \partial_x((1-x^2)\partial_x) + n(n+1) \Rightarrow$ common ansatz \tilde{L}

but $m_k^{(n)} = \int_{-1}^1 x^k P_n(x) dx = 0$ for $k < n$ and $m_n^{(n)} > 0$

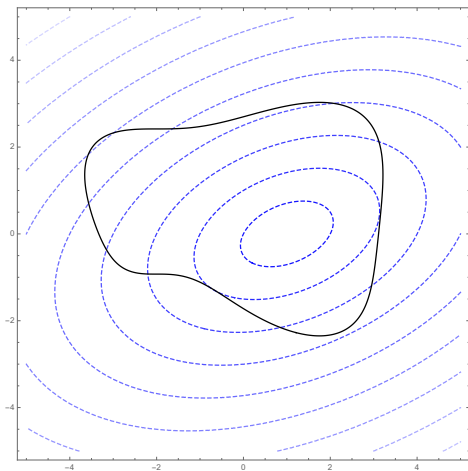
- Explicit bounds depending on upper bounds on the coefficients of \tilde{L} ?



- Algorithm RECONSTRUCTDENSITY only computes a system $\tilde{\mathcal{J}} = \{\tilde{L}_1, \dots, \tilde{L}_n\}$ but not the initial conditions that fully characterize f

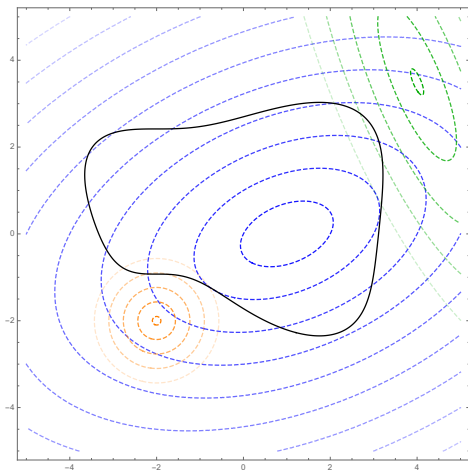


$$f(x, y) = \lambda_1 e^{\rho_1(x, y)}$$
$$\rho_1 = -\frac{1}{2} \begin{pmatrix} x - \mu_{x1} \\ y - \mu_{y1} \end{pmatrix}^T \Sigma_1^{-1} \begin{pmatrix} x - \mu_{x1} \\ y - \mu_{y1} \end{pmatrix}$$



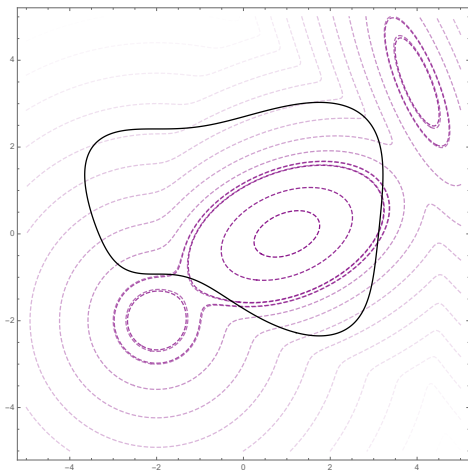
$$f(x, y) = \lambda_1 e^{\rho_1(x, y)}$$

$$\rho_1 = -\frac{1}{2} \begin{pmatrix} x - \mu_{x1} \\ y - \mu_{y1} \end{pmatrix}^T \Sigma_1^{-1} \begin{pmatrix} x - \mu_{x1} \\ y - \mu_{y1} \end{pmatrix} \quad \lambda_1 = \frac{1}{2\pi\sqrt{|\Sigma|}}$$



$$f(x, y) = \lambda_1 e^{p_1(x,y)} + \lambda_2 e^{p_2(x,y)} + \lambda_3 e^{p_3(x,y)}$$

$$p_i = -\frac{1}{2} \begin{pmatrix} x - \mu_{xi} \\ y - \mu_{yi} \end{pmatrix}^T \Sigma_i^{-1} \begin{pmatrix} x - \mu_{xi} \\ y - \mu_{yi} \end{pmatrix}$$

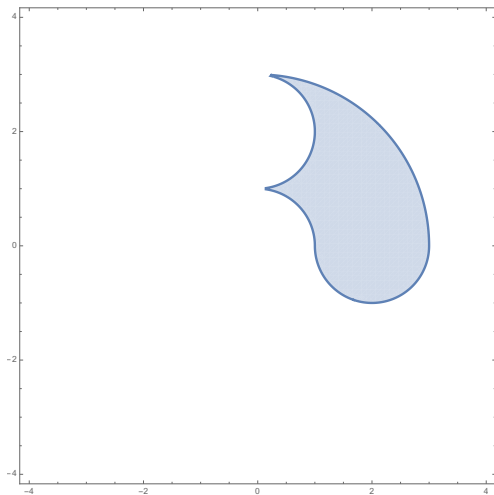


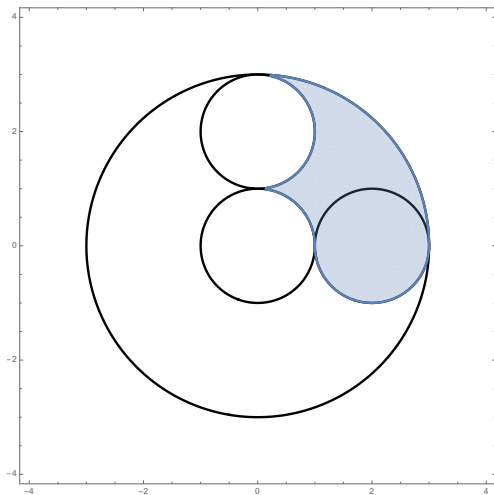
$$f(x, y) = \lambda_1 e^{p_1(x,y)} + \lambda_2 e^{p_2(x,y)} + \lambda_3 e^{p_3(x,y)}$$

$$p_i = -\frac{1}{2} \begin{pmatrix} x - \mu_{xi} \\ y - \mu_{yi} \end{pmatrix}^T \Sigma_i^{-1} \begin{pmatrix} x - \mu_{xi} \\ y - \mu_{yi} \end{pmatrix} \quad \lambda_i = ???$$

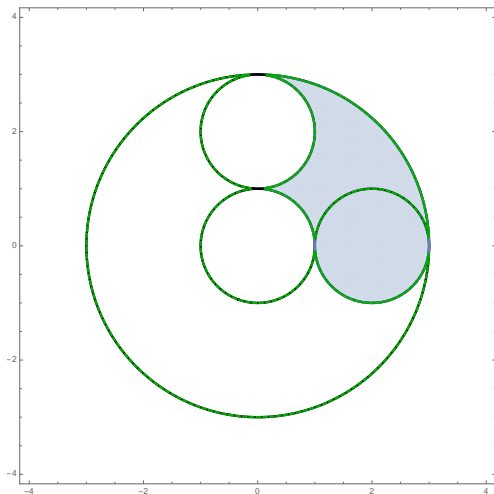


- Algorithm RECONSTRUCTDENSITY only computes a system $\tilde{\mathcal{J}} = \{\tilde{L}_1, \dots, \tilde{L}_n\}$ but not the initial conditions that fully characterize f
- Solution: compute initial moments for a basis of solution densities of $\tilde{\mathcal{J}}$
 - **Optimization techniques**, e.g., [HenionLasserreSavorgnan2009]
 - **Computer algebra**, e.g., [LairezMezzarobbaElDin2019]



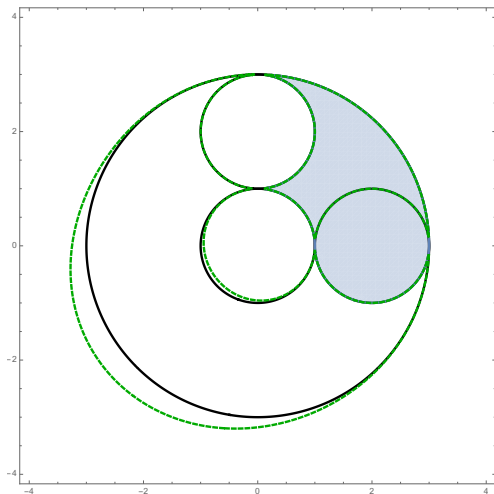


$$I(\partial G) = (g) \quad \text{with} \quad g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x - 2)^2 + y^2 - 1)(x^2 + (y - 2)^2 - 1)$$



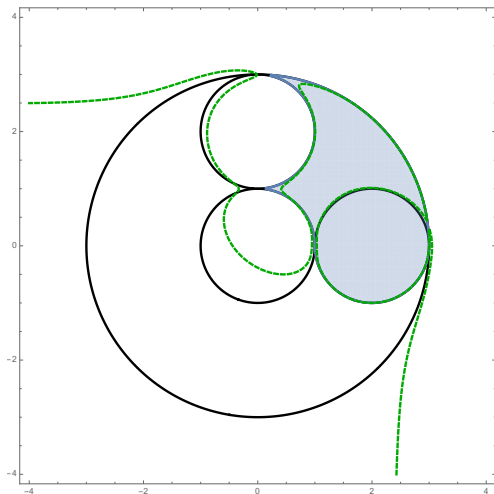
$I(\partial G) = (g)$ with $g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x - 2)^2 + y^2 - 1)(x^2 + (y - 2)^2 - 1)$

\tilde{g} reconstructed using 6 digits accuracy for the moments (m_α)



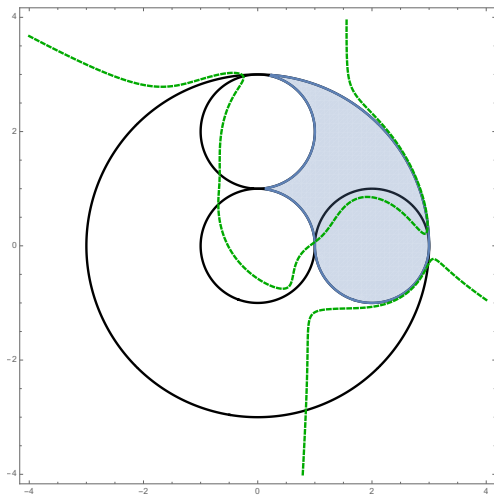
$$I(\partial G) = (g) \quad \text{with} \quad g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x - 2)^2 + y^2 - 1)(x^2 + (y - 2)^2 - 1)$$

\tilde{g} reconstructed using 4 digits accuracy for the moments (m_α)



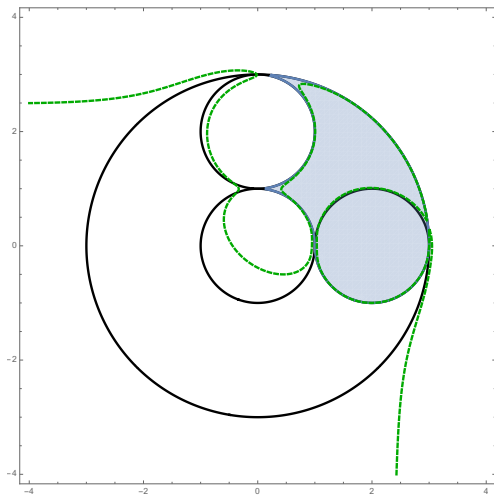
$I(\partial G) = (g)$ with $g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x - 2)^2 + y^2 - 1)(x^2 + (y - 2)^2 - 1)$

\tilde{g} reconstructed using 2 digits accuracy for the moments (m_α)



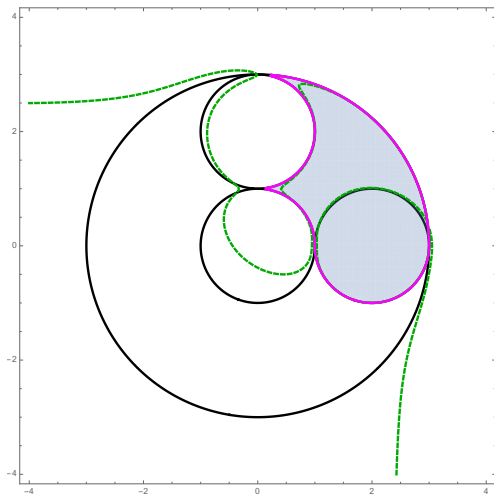
$$I(\partial G) = (g) \quad \text{with} \quad g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x-2)^2 + y^2 - 1)(x^2 + (y-2)^2 - 1)$$

\tilde{g} reconstructed using 1 digit accuracy for the moments (m_α)



$I(\partial G) = (g)$ with $g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x - 2)^2 + y^2 - 1)(x^2 + (y - 2)^2 - 1)$

\tilde{g} reconstructed using 2 digits accuracy for the moments (m_α)



$$I(\partial G) = (g) \quad \text{with} \quad g(x, y) = (x^2 + y^2 - 9)(x^2 + y^2 - 1)((x - 2)^2 + y^2 - 1)(x^2 + (y - 2)^2 - 1)$$

$$\partial G \approx \{(x, y) \mid g(x, y) = 0 \text{ and } \mathbb{E}[\tilde{g}(x, y)^2] \leq \varepsilon\}, \quad \tilde{g} \leftarrow \text{randomly perturbed } (\tilde{m}_\alpha)$$



Contributions:

- Extension of [LasserrePutinar2015] to reconstruction of unknown **Exp-Poly** density and unknown semi-algebraic support
- Explicit bound for the number N of required moments
- Reconstruction algorithm for unknown **holonomic** density and unknown semi-algebraic support
- Numerical experiments using **least-squares** approximation when approximate moments are known

Future work:

- Generic bounds for N depending on the magnitude of the coefficients
- **Numerical** aspects: robustness w.r.t. approximate moments, or nonpolynomial boundary
- Isolation of the **topological** boundary via perturbation techniques
- Application to problems involving **combinatorial sequences**



Thanks!