Linear PDE with Constant Coefficients

Bernd Sturmfels MPI Leipzig and UC Berkeley

Primary Ideals and their Differential Equations (with Yairon Cid-Ruiz and Roser Homs)

Primary Decomposition with Differential Operators (with Yairon Cid-Ruiz)

Noetherian Operators and Primary Decomposition (by Justin Chen, Marc Härkönen, Robert Krone, Anton Leykin)

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History

In his 1938 article on foundations of algebraic geometry, Gröbner introduced differential operators to characterize **membership in a polynomial ideal**. He derived this for zero-dimensional ideals (Macaulay's inverse systems), and he envisioned it for all ideals. Gröbner wanted algorithmic solutions. *We provide them.*

Wolfgang Gröbner: Über die algebraischen Eigenschaften der Integrale von linearen Differentialgleichungen mit konstanten Koeffizienten, *Monatshefte für Mathematik und Physik* (1939)

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Analysts made substantial contributions to this subject.

In the 1960s, Ehrenpreis and Palamodov studied solutions to linear partial differential equations (PDE) with constant coefficients. A main step was the characterization of membership in a primary ideal by *Noetherian operators*.

Their celebrated Fundamental Principle appears in the books

Leon Ehrenpreis: Fourier Analysis in Several Complex Variables, 1970 Victor Palamodov: Linear Differential Operators w Constant Coeffs, 1970

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Question 1: Solve the system of polynomial equations

$$x^2 = y^2 = xz - yz^2 = 0.$$

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$$x^2 = y^2 = xz - yz^2 = 0.$$

Question 2: Determine all functions $\phi(x, y, z)$ satisfying the PDE

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{\partial^2 \phi}{\partial y^2} = \frac{\partial^2 \phi}{\partial x \partial z} - \frac{\partial^3 \phi}{\partial y \partial z^2} = 0.$$

We identify polynomials with linear PDE with constant coefficients.

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Question 4: We presented a subscheme of affine 3-space. Describe it.

Four Solutions

Answer 1: Our equations $x^2 = y^2 = xz - yz^2 = 0$ define the *z*-axis:

$$x = y = 0.$$

Answer 2: A sufficiently differentiable function p satisfies

$$\frac{\partial^2 \phi}{\partial x^2} = \frac{\partial^2 \phi}{\partial y^2} = \frac{\partial^2 \phi}{\partial x \partial z} - \frac{\partial^3 \phi}{\partial y \partial z^2} = 0$$

if and only if it decomposes into four summands as follows:

 $\phi(x,y,z) = \xi(z) + (y\psi(z) + x\psi'(z)) + \alpha xy + \beta x.$

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Answer 3: A polynomial f lies in $I = \langle x^2, y^2, x - yz \rangle \cap \langle x^2, y^2, z \rangle$ if and only if the following four conditions hold: Both f and $\frac{\partial f}{\partial y} + z \frac{\partial f}{\partial x}$ vanish on the z-axis, and both $\frac{\partial^2 f}{\partial x \partial y}$ and $\frac{\partial f}{\partial x}$ vanish at the origin.

Answer 4: The scheme is a double *z*-axis with an embedded point of length two at the origin. The arithmetic multiplicity of *I* is four.

Prime Ideals

Let *P* be a prime ideal in $\mathbb{C}[x_1, \ldots, x_n]$ and V(P) its variety in \mathbb{C}^n . A polynomial *f* is in the ideal *P* if and only if *f* vanishes on V(P). Setting $x_i = \partial_{z_i}$, view *P* as PDE for an unknown function $\phi(z_1, \ldots, z_n)$.

Remark

For $y \in \mathbb{C}^n$, the exponential function

$$z \mapsto \exp(y^t z) = \exp(y_1 z_1 + \cdots + y_n z_n)$$

satisfies the PDE given by P if and only if $y \in V(P)$.

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Proposition

Each solution to P admits an integral representation

$$\phi(z) = \int_{V(P)} \exp(y^t z) d\mu(y),$$

where μ is a measure on the irreducible variety V(P).

Primary Ideals

$$m = \operatorname{length}(R_P/QR_P) = rac{\operatorname{degree}(Q)}{\operatorname{degree}(P)}.$$

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Fix a prime *P* of codimension *c* in $R = \mathbb{C}[x_1, \ldots, x_n]$, in Noether position. Write $\mathbb{F} = \mathbb{C}(u_1, \ldots, u_n)$ for the field of fractions of R/P.

Theorem

The following sets are in bijective correspondences:

- (a) P-primary ideals Q in R of multiplicity m,
- (b) points in the punctual Hilbert scheme $\operatorname{Hilb}^m(\mathbb{F}[[y_1,\ldots,y_c]]),$
- (c) m-dimensional \mathbb{F} -subspaces of $\mathbb{F}[z_1, \ldots, z_c]$ that are closed under differentiation, Inverse systems

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- (c) m-dimensional \mathbb{F} -subspaces of $\mathbb{F}[z_1, \ldots, z_c]$ that are closed under differentiation, Inverse systems
- (d) *m*-dimensional \mathbb{F} -subspaces of the Weyl-Noether module $\mathbb{F} \otimes_R D_{n,c}$ that are *R*-bi-modules, where $D_{n,c} = R\langle \partial_{x_1}, \ldots, \partial_{x_c} \rangle$.

Any basis of the \mathbb{F} -subspace in (d) lifts to Noetherian operators $A_1, \ldots, A_m \in D_{n,c}$. These characterize ideal membership in Q.

Ehrenpreis-Palamodov

Each A_l in $D_{n,c}$ is written uniquely as $\sum_{\alpha,\beta} c_{\alpha,\beta} x^{\alpha} \partial_x^{\beta}$. Replace ∂_x by z to get polynomials

$$B_l(\mathsf{x},\mathsf{z}) := A_l(\mathsf{x},\partial_\mathsf{x})|_{\partial_{x_1}\mapsto z_1,\ldots,\partial_{x_c}\mapsto z_c}$$
 for $l=1,\ldots,m$.

The *Noetherian multipliers* B_1, \ldots, B_m span the inverse system (c).

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The *Noetherian multipliers* B_1, \ldots, B_m span the inverse system (c).

Theorem (Ehrenpreis-Palamodov Fundamental Principle) Consider the PDE given by a P-primary ideal Q. Any sufficiently nice solution ψ has an integral representation

$$\psi(z) = \sum_{l=1}^{m} \int_{V(P)} B_l(x, z) \exp(x^t z) d\mu_l(x)$$

for suitable measures μ_l supported in the variety V(P). Conversely, all such functions are solutions.

From (a) to (d)

Algorithm (From ideal generators to Noetherian operators) Input: Generators of a P-primary ideal Q in $R = \mathbb{C}[x_1, ..., x_n]$. Output: Operators $A_1, ..., A_m$ in the relative Weyl algebra $D_{n,c}$ with $Q = \{ f \in \mathbb{C}[x_1, ..., x_n] : A_i \bullet f \in P \text{ for all } i \}$.

Set
$$\gamma: R \hookrightarrow \mathbb{F}[y_1, \dots, y_c], \quad \begin{array}{ccc} x_i & \mapsto & y_i + u_i \\ x_j & \mapsto & u_j \end{array} \quad \begin{array}{ccc} \text{for } 1 \leq i \leq c, \\ \text{for } c + 1 \leq j \leq n. \end{array}$$

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1. Find generators of the 0-dim'l ideal $I = \langle y_1, \ldots, y_c \rangle^m + \gamma(Q)$.

- 2. Using linear algebra over $\mathbb{F} = \mathbb{C}(u_1, \ldots, u_n)$, compute a basis $\{B_1, \ldots, B_m\}$ for the inverse system I^{\perp} in $\mathbb{F}[z_1, \ldots, z_c]$.
- 3. Lift $B_i(u, z)$ to obtain the Noetherian multipliers $B_i(x, z)$.
- 4. Replace z by ∂_x to get the Noetherian operators $A_i(x, \partial_x)$.

Available in Macaulay2, as part of J. Chen, Y. Cid-Ruiz, M. Härkönen, R. Krone, A. Leykin: *Noetherian operators in Macaulay2*, January 2021.

Operators versus Multipliers

Input: Primary ideal $Q = \langle x_1^2, x_2^2, x_1 - x_2 x_3 \rangle$.

Here
$$n = 3$$
, $c = m = 2$ and $P = \langle x_1, x_2 \rangle$.

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Output in Step 4: The Noetherian operators

$$A_1(x,\partial_x) = 1$$
 and $A_2(x,\partial_x) = x_3\partial_{x_1} + \partial_{x_2}$.

Output in Step 3: The Noetherian multipliers

$$B_1(x,z) = 1$$
 and $B_2(x,z) = x_3 z_1 + z_2$.

Operators versus Multipliers

Input: Primary ideal $Q = \langle x_1^2, x_2^2, x_1 - x_2 x_3 \rangle$.

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$$n = 3$$
, $c = m = 2$ and $P = \langle x_1, x_2 \rangle$.

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Ehrenpreis-Palamodov: Solutions to $\phi_{z_1z_1} = \phi_{z_2z_2} = \phi_{z_1} - \phi_{z_2z_3} = 0$:

$$\phi_1(z) = \int 1 \cdot \exp(0z_1 + 0z_2 + x_3z_3) d\mu_x = \xi(z_3)$$
 and

$$\begin{aligned} \phi_2(z) &= \int (z_2 + z_1 x_3) \cdot \exp(0z_1 + 0z_2 + x_3 z_3) \, d\mu_x \\ &= z_2 \int \exp(0z_1 + 0z_2 + x_3 z_3) \, d\mu_x + z_1 \int x_3 \, \exp(0z_1 + 0z_2 + x_3 z_3) \, d\mu_x \\ &= z_2 \, \psi(z_3) + z_1 \, \psi'(z_3). \end{aligned}$$

Gröbner's Dream

Consider **any** ideal $I \subset R$ with associated primes P_1, \ldots, P_k . Its *arithmetic multiplicity* is $\operatorname{amult}(I) = \sum_{j=1}^k \operatorname{mult}_I(P_j)$, where

$$mult_I(P) = \frac{degree(saturate(I,P)/I)}{degree(P))}$$

is the length of the largest ideal of finite length in R_P/IR_P .

A differential primary decomposition of I is a list $(P_1, A_1), \ldots, (P_k, A_k)$ where A_i is a finite subset of $D_{n,n}$ with $I = \{f \in R \mid \delta \bullet f \in P_i \text{ for all } \delta \in A_i \text{ and } i = 1, \ldots, k\}.$

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Theorem

The size of a differential primary decomposition is at least $\operatorname{amult}(I)$, and this lower bound is tight. More precisely:

- (i) The ideal I has a differential primary decomposition $(P_1, A_1), \ldots, (P_k, A_k)$ such that $|A_i| = \text{mult}_I(P_i)$.
- (ii) If $(P_1, A_1), \ldots, (P_k, A_k)$ is any differential primary decomposition for I, then $|A_i| \ge \text{mult}_I(P_i)$.

Macaulay 2

Computing a minimal differential primary decomposition:

i1 : load "modulesNoetherianOperators.m2"

$$i2 : R = QQ[x,y,z]$$

- i3 : I = ideal(x²,y²,x*z-y*z²);
- i4 : amult(I)

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i5 : netList solvePDE(I)

o5 = |ideal (y, x) |{| 1 |, | dxz+dy |} +-----+ |ideal (z, y, x)|{| dx |, | dxdy |}

This is Answer 2 & 3 for our double line: $P_1 = \langle x, y \rangle$, $A_1 = \{1, z\partial_x + \partial_y\}$ $P_2 = \langle x, y, z \rangle$, $A_2 = \{\partial_x, \partial_x \partial_y\}$

Modules

The treatment of Ehrenpreis-Palamodov in books on analysis emphasizes PDE for vector-valued functions $\psi : \mathbb{C}^n \to \mathbb{C}^k$.

[J.-E. Björk: Rings of Differential Operators], [L. Hörmander: An Introduction to Complex Analysis in Several Variables]

In calculus we learn how to rewrite one higher-order ODE as a system of first order ODE, and in algebraic geometry we learn how to appreciate matrix representations of geometric objects:

 $\begin{array}{rcl} \mbox{Ideals} & \longrightarrow & \mbox{Schemes} \\ \mbox{Modules} & \longrightarrow & \mbox{Coherent Sheaves} \end{array}$

A system of ℓ linear PDE for ψ is represented by a $k \times \ell$ matrix with entries in $R = \mathbb{C}[x_1, \ldots, x_n]$. The image of this matrix is a submodule M of R^k . Primary decomposition makes sense here:

$$M = M_1 \cap \cdots \cap M_k.$$

... and so does differential primary decomposition $\Box_{A} \subset \Box_{A} \subset \Box_{A}$

Coherent Sheaves

Let $M \subset R^2$ be the module spanned by the columns of

$$\begin{bmatrix} \partial_1 \partial_3 & \partial_1 \partial_2 & \partial_1^2 \partial_2 \\ \partial_1^2 & \partial_2^2 & \partial_1^2 \partial_4 \end{bmatrix}$$

This represents PDE for functions $\psi : \mathbb{C}^4 \to \mathbb{C}^2$. We seek $\psi(z) = (\psi_1(z_1, z_2, z_3, z_4), \psi_2(z_1, z_2, z_3, z_4))$ such that

$$\frac{\partial^2 \psi_1}{\partial z_1 \partial z_3} + \frac{\partial^2 \psi_2}{\partial z_1^2} = \frac{\partial^2 \psi_1}{\partial z_1 \partial z_2} + \frac{\partial^2 \psi_2}{\partial z_2^2} = \frac{\partial^3 \psi_1}{\partial z_1^2 \partial z_2} + \frac{\partial^3 \psi_2}{\partial z_1^2 \partial z_4} = 0.$$

The module *M* has six associated primes, namely $P_1 = \langle \partial_1 \rangle$, $P_2 = \langle \partial_2, \partial_4 \rangle$, $P_3 = \langle \partial_2, \partial_3 \rangle$, $P_4 = \langle \partial_1, \partial_3 \rangle$, $P_5 = \langle \partial_1, \partial_2 \rangle$, $P_6 = \langle \partial_1^2 - \partial_2 \partial_3, \partial_1 \partial_2 - \partial_3 \partial_4, \partial_2^2 - \partial_1 \partial_4 \rangle$. Primes P_4, P_5 are embedded. Arithmetic multiplicity: 1+1+1+1+4+1 = 9 = amult(M).

To solve the PDE, we compute a differential primary decomposition.

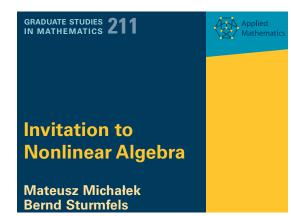
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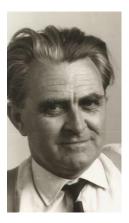
Macaulay 2 $\frac{\partial^2 \psi_1}{\partial z_1 \partial z_3} + \frac{\partial^2 \psi_2}{\partial z_1^2} = \frac{\partial^2 \psi_1}{\partial z_1 \partial z_2} + \frac{\partial^2 \psi_2}{\partial z_2^2} = \frac{\partial^3 \psi_1}{\partial z_1^2 \partial z_2} + \frac{\partial^3 \psi_2}{\partial z_1^2 \partial z_4} = 0.$

```
i1 : load "modulesNoetherianOperators.m2"
           i2 : R = QQ[x1,x2,x3,x4]
           i3 : M = image matrix{
                    {x1*x3, x1*x2, x1^2*x2 },
                    { x1^2, x2^2, x1^2*x4} };
           i4 : amult(M)
           04 = 9
           i5 : S = solvePDE(M)
           o5 = {ideal x1, {| 1 |}}
                2
{ideal (x2 - x1*x4, x1*x2 - x3*x4, x1 - x2*x3), {| -x4 |}
| x2 |
                {ideal (x4, x2), {| -x1 |}}
                {ideal (x2, x1), {|0|, |0|, |0|, |0|, |0|}
                {ideal (x3, x2), {| 1 |}}
                {ideal (x3, x1), {| -dx1x2 |}}
Solutions (\psi_1, \psi_2)?
```

For Students

Wolfgang Gröbner





Theorem 3.27. Let I be a zero-dimensional ideal in $\mathbb{C}[x_1,\ldots,x_n]$, here interpreted as a system of linear PDEs. The space of holomorphic solutions has dimension equal to the degree of I. There exist nonzero polynomial solutions if and only if the maximal ideal $M = \langle x_1, \ldots, x_n \rangle$ is an associated prime of I. In that case, the polynomial solutions are precisely the solutions to the system of PDEs given by the M-primary component $(I:(I:M^{\infty}))$. ・ロト ・ 戸 ・ ・ ヨ ・ ・ ヨ ・ ・ つ へ ()

Calculus Homework

Given three distinct integers a, b, c > 0, describe the space of all functions $\phi = \phi(x, y, z)$ that satisfy the three PDE

$$\frac{\partial^a \phi}{\partial x^a} + \frac{\partial^a \phi}{\partial y^a} + \frac{\partial^a \phi}{\partial z^a} = \frac{\partial^b \phi}{\partial x^b} + \frac{\partial^b \phi}{\partial y^b} + \frac{\partial^b \phi}{\partial z^b} = \frac{\partial^c \phi}{\partial x^c} + \frac{\partial^c \phi}{\partial y^c} + \frac{\partial^c \phi}{\partial z^c} = 0.$$

For (a, b, c) = (1, 2, 3) get $\phi = (x-y)(x-z)(y-z)$ and its derivatives. To gain insight, start with (a, b, c) = (2, 5, 8).

Due Date: **Tomorrow** Submit your solution to: bernd@mis.mpg.de No late homework, please

Many thanks for your attention!

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