

# **Generalized Hermite reduction, Creative telescoping, and Definite integration of differentially finite functions**

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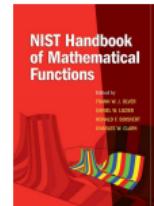
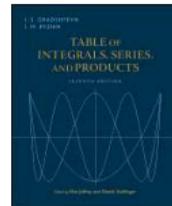
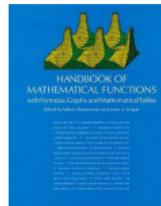
# Automatic computation of sums and integrals

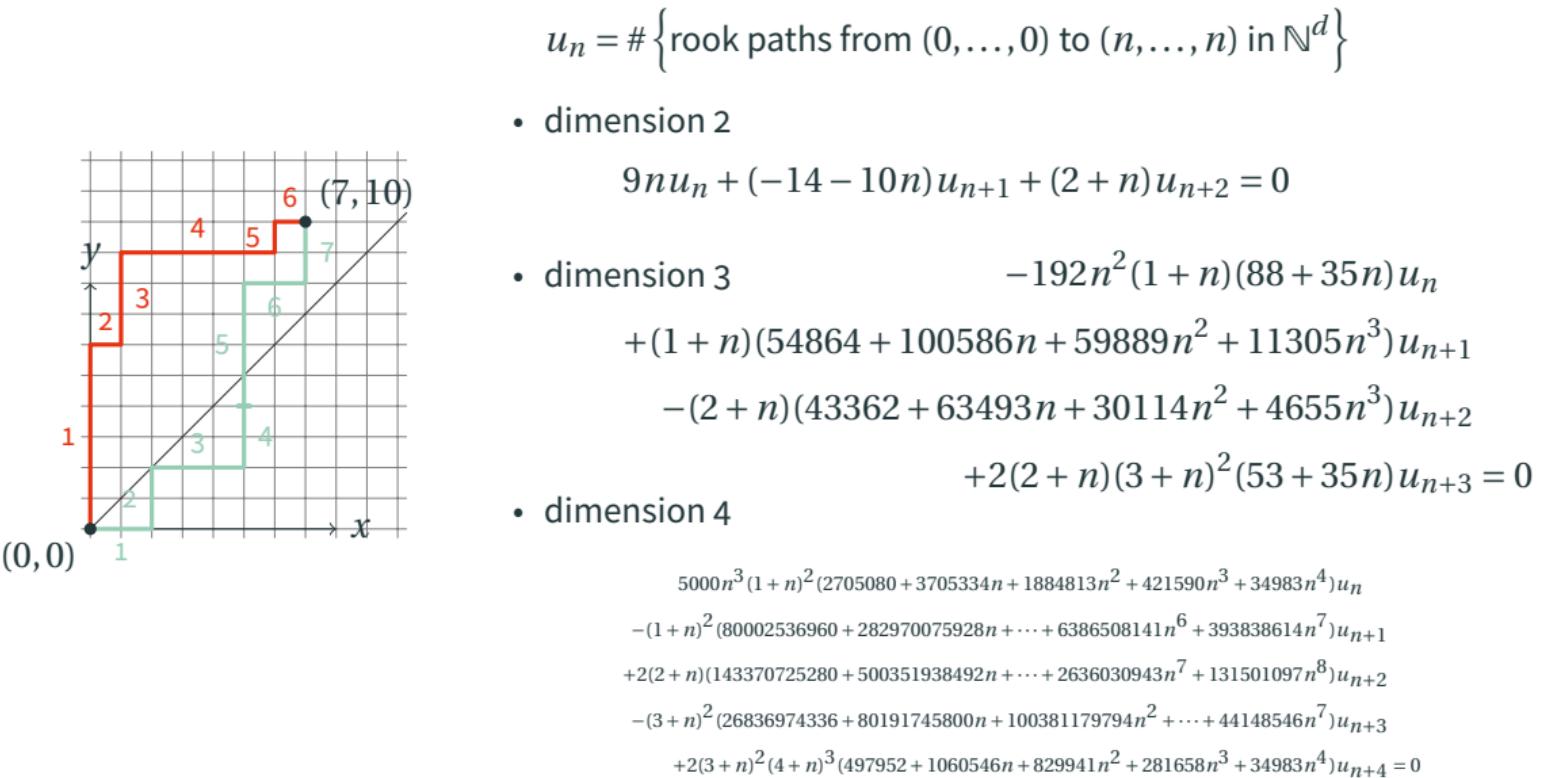
$$\sum_{i=0}^n \sum_{j=0}^n \binom{i+j}{i}^2 \binom{4n-2i-2j}{2n-2i} = (2n+1) \binom{2n}{n}^2 \quad (\text{Blodgett, 1990})$$

$$\int_0^{+\infty} x J_1(ax) I_1(ax) Y_0(x) K_0(x) dx = -\frac{\ln(1-a^4)}{2\pi a^2} \quad (\text{Glasser, Montaldi, 1994})$$

$$\int_{-1}^1 \frac{e^{-px} T_n(x)}{\sqrt{1-x^2}} dx = (-1)^n \pi I_n(p)$$

$$\sum_{j=0}^n \sum_{i=0}^{n-j} \frac{q^{(i+j)^2+j^2}}{(q;q)_{n-i-j}(q;q)_i(q;q)_j} = \sum_{k=-n}^n \frac{(-1)^k q^{7/2k^2+1/2k}}{(q;q)_{n+k}(q;q)_{n-k}} \quad (\text{Paule, 1985})$$





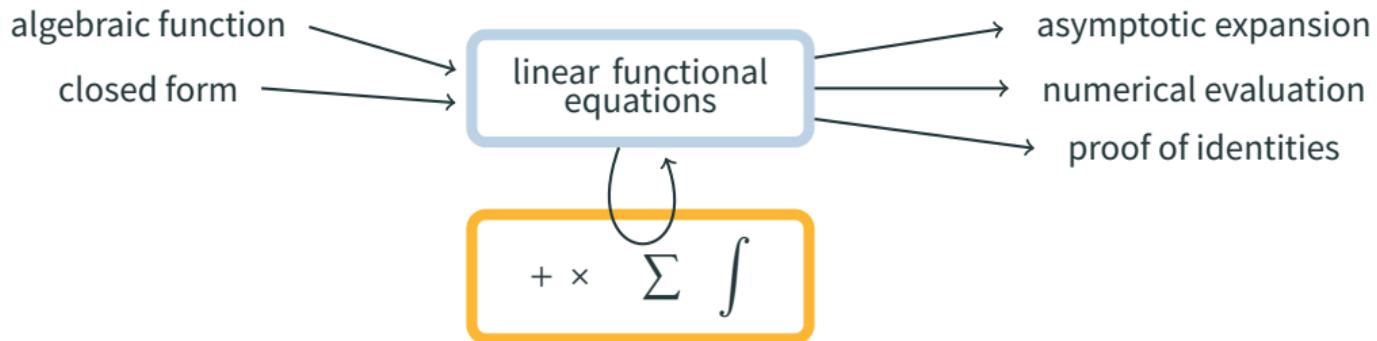
# The problem of definite integration

**input**  $F(t_1, \dots, t_n, x)$

**output**  $G(t_1, \dots, t_n) = \int_D F(t_1, \dots, t_n, x) dx$

**assumption**  $\int_D \frac{\partial}{\partial x}(\dots) dx = 0$

**data structure** linear functional equations



## **Previous works**

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**input**  $F(t, x) \in \mathbb{Q}(t, x)$

**output** A differential equation for  $G(t) = \oint F(t, x) dx$

**references** Ostrogradsky (1845), Hermite (1872), Bostan, Chen, Chyzak, Li (2010a)

$$\begin{aligned} F &= \frac{A_0}{B} + \frac{\partial}{\partial x} H_0 \\ \frac{\partial}{\partial t} F &= \frac{A_1}{B} + \frac{\partial}{\partial x} H_1 \\ \frac{\partial^2}{\partial t^2} F &= \frac{A_2}{B} + \frac{\partial}{\partial x} H_2 \\ \vdots &\quad \vdots \\ \frac{\partial^r}{\partial t^r} F &= \frac{A_r}{B} + \frac{\partial}{\partial x} H_r \end{aligned}$$

$\xrightarrow[\text{finite dimension}]{} \text{confinement in}$

$$\sum_{k=0}^r a_k(t) \frac{\partial^k}{\partial t^k} F = 0 + \frac{\partial}{\partial x} H$$

$$\rightsquigarrow \sum_{k=0}^r a_k(t) G^{(k)} = 0 \quad \checkmark$$

(simple poles)

**theorem** (Bostan, Chen, Chyzak, Li 2010a)

On input of degree  $d$ , one can compute the output in  $\mathcal{O}(d^{\omega+4})$  arithmetic operations.

**input**  $F(t, x_1, \dots, x_n) \in \mathbb{Q}(t, x_1, \dots, x_n)$

**output** A differential equation for  $G(t) = \oint F(t, x_1, \dots, x_n) dx_1 \cdots dx_n$

**references** Dwork (1962), Griffiths (1969), Bostan, Lairez, Salvy (2013), and Lairez (2016)

Compute  $a_0(t), \dots, a_r(t) \in \mathbb{Q}(t)$  such that

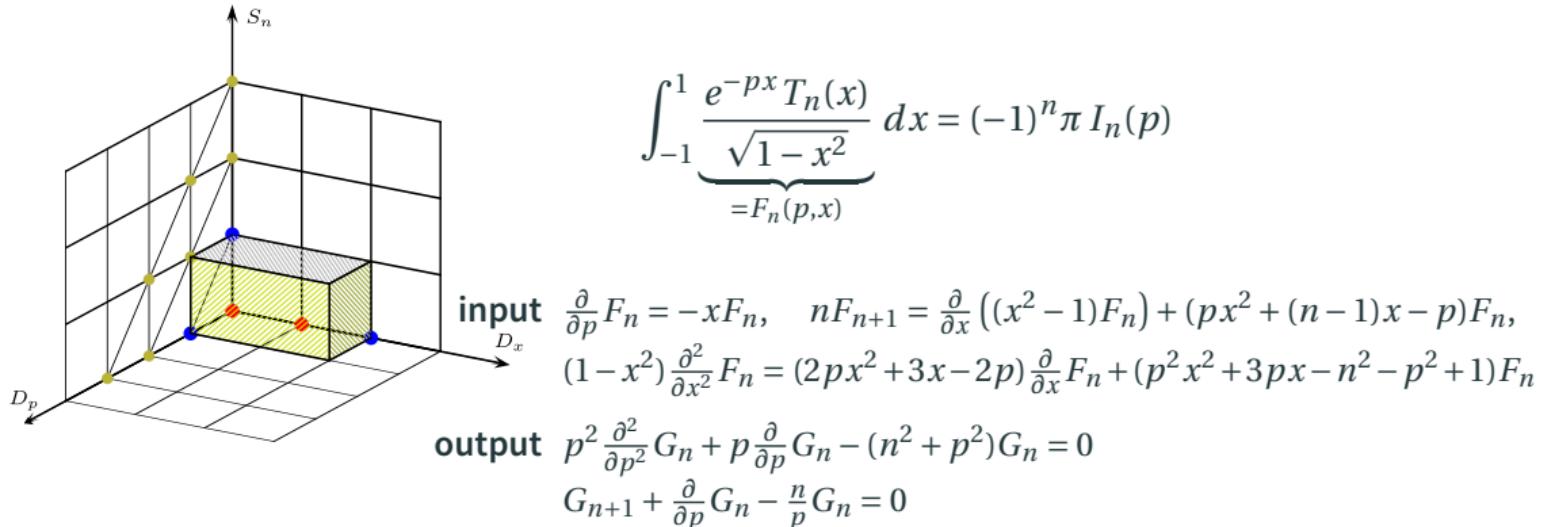
$$\sum_{k=0}^r a_k(t) \frac{\partial^k}{\partial t^k} F = \sum_{i=1}^n \frac{\partial}{\partial x_i} \quad (\text{some rational function})$$

**theorem** (Bostan, Lairez, Salvy 2013)

One input of degree  $d$ , one can compute the output in  $d^{8n+\mathcal{O}(1)}$  arithmetic operations.

Generically, the certificate has size  $> d^{n^2/2}$ .

## A differentially finite example



**differential finiteness** For all  $i, j, k \geq 0$ , there are  $a_{ijk}$  and  $b_{ijk} \in \mathbb{Q}(n, p, x)$  such that

$$\frac{\partial^i}{\partial x^i} \frac{\partial^j}{\partial p^j} F_{n+k}(p, x) = a_{ijk}(n, p, x)F_n(p, x) + b_{ijk}(n, p, x) \frac{\partial}{\partial x} F_n(p, x).$$

## Challenges

**minimality** We want to find *all* relations satisfied by the integrals

**bounds** We want to understand and control:

- the size of the output,
- the computational complexity of the algorithm.

**certificateless** We want to avoid computing the certificate (otherwise, the complexity gets out of control):

- the certificate is much bigger than the output
- not possible to compute it with good complexity
- it is often useless

We give up:

- simple certification of the output
- case where  $\int_D \frac{\partial}{\partial x}(\dots) dx \neq 0$

# Creative telescoping

principle Find all relations

$$\begin{aligned} \sum_{(j,k) \in B} c_{j,k}(n, p) \frac{\partial}{\partial p^j} F_{n+k}(p, x) &= \frac{\partial}{\partial x} \left( u(n, p, x) F_n(p, x) + v(n, p, x) \frac{\partial}{\partial x} F_n(p, x) \right) \\ \rightsquigarrow \sum_{(j,k) \in B} c_{j,k}(n, p) \frac{\partial}{\partial p^j} G_{n+k}(p) &= 0. \end{aligned}$$

equivalently Find all  $B \subset \mathbb{N}^2$  and  $\begin{pmatrix} c_{jk} \end{pmatrix} \in \mathbb{Q}(n, p)^B$  such that

$$\begin{cases} \frac{\partial}{\partial x} u = -a_{200} v + \sum_{(i,j) \in B} c_{jk} a_{0jk} \\ \frac{\partial}{\partial x} v = -b_{200} u + \sum_{(i,j) \in B} c_{jk} b_{0jk}, \end{cases}$$

has a rational solution  $u, v \in \mathbb{Q}(n, p, x)$ .

**problem** Find all  $B \subset \mathbb{N}^2$  and  $\begin{pmatrix} c_{jk} \end{pmatrix} \in \mathbb{Q}(n, p)^B$  s.t.  $\exists u, v \in \mathbb{Q}(n, p, x)$

$$\frac{\partial}{\partial x} \begin{pmatrix} u \end{pmatrix} = -a_{200} \begin{pmatrix} v \end{pmatrix} + \sum_{(i,j) \in B} \begin{pmatrix} c_{jk} \end{pmatrix} a_{0jk} \quad \text{and} \quad \frac{\partial}{\partial x} \begin{pmatrix} v \end{pmatrix} = - \begin{pmatrix} u \end{pmatrix} - b_{200} \begin{pmatrix} v \end{pmatrix} + \sum_{(i,j) \in B} \begin{pmatrix} c_{jk} \end{pmatrix} b_{0jk}.$$

**elimination** Only look for solutions with  $u, v \in \mathbb{Q}(n, p)$ .

Akin to polynomial elimination.

↳ Fasenmyer (1949); see also Takayama (1990), Galligo (1985), etc.

minimality    bounds    certificateless

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**problem** Find all  $B \subset \mathbb{N}^2$  and  $\begin{pmatrix} c_{jk} \end{pmatrix} \in \mathbb{Q}(n, p)^B$  s.t.  $\exists u, v \in \mathbb{Q}(n, p, x)$

$$\frac{\partial}{\partial x} u = -a_{200} v + \sum_{(i,j) \in B} c_{jk} a_{0jk} \quad \text{and} \quad \frac{\partial}{\partial x} v = -u - b_{200} v + \sum_{(i,j) \in B} c_{jk} b_{0jk}.$$

**rational solutions** Iteratively solve the differential system (Abramov 1989; Barkatou 1999) with increasing support  $B$  (FGLM-like).

↳ Chyzak (2000) ; see also Picard (1906), Zeilberger (1990)

minimality    bounds    certificateless



**problem** Find all  $B \subset \mathbb{N}^2$  and  $\begin{pmatrix} c_{jk} \end{pmatrix} \in \mathbb{Q}(n, p)^B$  s.t.  $\exists u, v \in \mathbb{Q}(n, p, x)$

$$\frac{\partial}{\partial x} \begin{pmatrix} u \end{pmatrix} = -a_{200} \begin{pmatrix} v \end{pmatrix} + \sum_{(i,j) \in B} \begin{pmatrix} c_{jk} \end{pmatrix} a_{0jk} \quad \text{and} \quad \frac{\partial}{\partial x} \begin{pmatrix} v \end{pmatrix} = - \begin{pmatrix} u \end{pmatrix} - b_{200} \begin{pmatrix} v \end{pmatrix} + \sum_{(i,j) \in B} \begin{pmatrix} c_{jk} \end{pmatrix} b_{0jk}.$$

**linear algebra** Predict the denominator of solutions  $u, v \in \mathbb{Q}(n, p, x)$ ,  
reduce to linear algebra over  $\mathbb{Q}(n, p)$ .

↳ Lipshitz (1988), Apagodu, Zeilberger (2006), Koutschan (2010)

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**problem** Find all  $B \subset \mathbb{N}^2$  and  $\begin{pmatrix} c_{jk} \end{pmatrix} \in \mathbb{Q}(n, p)^B$  s.t.  $\exists u, v \in \mathbb{Q}(n, p, x)$

$$\frac{\partial}{\partial x} u = -a_{200} v + \sum_{(i,j) \in B} c_{jk} a_{0jk} \quad \text{and} \quad \frac{\partial}{\partial x} v = -u - b_{200} v + \sum_{(i,j) \in B} c_{jk} b_{0jk}.$$

**reduction of pole order** Generalization of Hermite's reduction

- ↳ Bostan, Chen, Chyzak, Li (2010b), Chen, Kauers, Singer (2012) and  
Chen, Kauers, Koutschan (2016), Bostan, Chen, Chyzak, Li, Xin (2013),  
Chen, Huang, Kauers, Li (2015) and Huang (2016), Bostan, Dumont,  
Salvy (2016), Chen, Hoeij, Kauers, Koutschan (2018), Hoeven (2017)

minimality    bounds    certificateless



## New algorithm

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## Obstructions to integrability

**problem** Find all  $B \subset \mathbb{N}^2$  and  $\begin{pmatrix} c_{jk} \end{pmatrix} \in \mathbb{Q}(n, p)^B$  s.t.  $\exists u, v \in \mathbb{Q}(n, p, x)$

$$(*) \quad \frac{\partial}{\partial x} \begin{matrix} u \\ v \end{matrix} = -a_{200} \begin{matrix} u \\ v \end{matrix} + \sum_{(i,j) \in B} c_{jk} a_{0jk} \quad \text{and} \quad \frac{\partial}{\partial x} \begin{matrix} u \\ v \end{matrix} = - \begin{matrix} u \\ v \end{matrix} - b_{200} \begin{matrix} u \\ v \end{matrix} + \sum_{(i,j) \in B} c_{jk} b_{0jk}.$$

**2G/4G hybrid algorithm** For all  $(j, k) \in \mathbb{N}^2$ , produce an *obstruction*  $\lambda_{jk}$  such that

$$\lambda_{jk} = 0 \quad \Leftrightarrow \quad \begin{cases} \frac{\partial}{\partial x} \begin{matrix} u \\ v \end{matrix} = & -a_{200} \begin{matrix} u \\ v \end{matrix} + a_{0jk} \\ \frac{\partial}{\partial x} \begin{matrix} u \\ v \end{matrix} = - \begin{matrix} u \\ v \end{matrix} & -b_{200} \begin{matrix} u \\ v \end{matrix} + b_{0jk} \end{cases} \quad \text{has a solution.}$$

By linearity,  $(*)$  has a solution if and only if

$$\sum_{(j,k) \in B} c_{jk} \lambda_{jk} = 0.$$

## Lagrange identity

**differential operator**  $L : f(x) \mapsto \sum_i a_i(x) \frac{d^i}{dx^i} f(x)$

**adjoint operator**  $L^* : f(x) \mapsto \sum_i (-1)^i \frac{d^i}{dx^i} (a_i(x) f(x))$

**Lagrange's identity**  $uL(f) = L^*(u)f + \frac{d}{dx}(\dots).$

**corollary 1**  $M(f) = M^*(1)f + \frac{d}{dx}(\dots)$ , for any diff. op.  $M$ .

**corollary 2** If  $L(f) = 0$  then  $L^*(u)f = \frac{d}{dx}(\dots)$  for any  $u(x)$

**corollary 3** If  $L$  is the minimal annihilating operator of  $f$ ,  
then for any differential operator  $M$ ,

$M(f)$  “is a derivative”  $\Leftrightarrow \exists y \in K(x), M^*(1) = L^*(y).$

## Generalized Hermite reduction

	Hermite reduction	Generalized Hermite red.
<b>input</b>	$u \in K(x)$	$u \in K(x)$ and $M \in K[x] \langle \frac{d}{dx} \rangle$
<b>output</b>	$v \in K(x)$	$v \in K(x)$
<b>prop. 1</b>	$u - v \in \frac{d}{dx} K(x)$	$u - v \in M(K(x))$
<b>prop. 2</b>	$u = \frac{d}{dx}(\dots) \Rightarrow v = 0$	$u = M(\dots) \Rightarrow v = 0$

## Testing integrability with GHR

**input**  $\gamma(x)$  a “function”

$L$ , the minimal annihilating operator of  $\gamma$

$f \in K(x)\langle \frac{d}{dx} \rangle \cdot \gamma$ , the function space generated by  $\gamma$

**output**  $\exists g \in K(x)\langle \frac{d}{dx} \rangle \cdot \gamma, f = \frac{d}{dx}g$

**algorithm**    write  $f = u(x)\gamma + \frac{d}{dx}(\dots)$

▷ corollary 1

$v(x) \leftarrow \text{GHR}(u, L^*)$

return  $v = 0$

▷ corollary 3

## GHR powered variant of Chyzak's algorithm

**input**  $\mathcal{I}$  a D-finite ideal and  $f \in \mathbb{A}/\mathcal{I}$   
**output** generators of the telescoping ideal  $\mathcal{T}_f$  w.r.t.  $\frac{\partial}{\partial x}$

**algorithm**

- $\gamma \leftarrow$  a cyclic vector of  $\mathbb{A}/\mathcal{I}$  with respect to  $\frac{\partial}{\partial x}$
- $L \leftarrow$  the minimal operator annihilating  $\gamma$
- $\mathcal{L} \leftarrow [1]; G \leftarrow \{\}; Q \leftarrow \{\}$
- while**  $\mu \leftarrow \text{pop}(\mathcal{L})$  **do**
  - if**  $\mu$  is a not multiple of the leading term of an element of  $G$  **then**
    - write  $\mu \cdot f = u_\mu(x)\gamma + \frac{\partial}{\partial x}(\dots)$
    - $\lambda_\mu \leftarrow \text{GHR}(u_\mu, L^*)$
    - if**  $\exists$  a  $K$ -linear rel. between  $\lambda_\mu$  and  $\{\lambda_\nu \mid \nu \in Q\}$  **then**
      - $(a_\nu)_{\nu \in Q} \leftarrow$  coeff. of the relation  $\lambda_\mu u = \sum_{\nu \in Q} a_\nu \lambda_\nu$
      - Add  $\mu - \sum_{\nu \in Q} a_\nu \nu$  to  $G$
  - else**
    - add  $\mu$  to  $Q$ ; enqueue  $\delta_1 \mu, \dots, \delta_e \mu$  in  $\mathcal{L}$ .
- return**  $G$

$$\int \frac{2J_{m+n}(2tx)T_{m-n}(x)}{\sqrt{1-x^2}} dx \quad [\text{diff. } t, \text{ shift } n \text{ and } m] \quad (1)$$

$$\int_0^1 C_n^{(\lambda)}(x)C_m^{(\lambda)}(x)C_\ell^{(\lambda)}(x)(1-x^2)^{\lambda-\frac{1}{2}} dx \quad [\text{shift } n, m, \ell] \quad (2)$$

$$\int_0^\infty x J_1(ax) I_1(ax) Y_0(x) K_0(x) dx \quad [\text{diff. } a] \quad (3)$$

$$\int \frac{n^2+x+1}{n^2+1} \left( \frac{(x+1)^2}{(x-4)(x-3)^2(x^2-5)^3} \right)^n \sqrt{x^2-5} e^{\frac{x^3+1}{x(x-3)(x-4)^2}} dx \quad [\text{shift } n] \quad (4)$$

$$\int C_m^{(\mu)}(x)C_n^{(\nu)}(x)(1-x^2)^{\nu-1/2} dx \quad [\text{shift } n, m, \mu, \nu] \quad (5)$$

$$\int x^\ell C_m^{(\mu)}(x)C_n^{(\nu)}(x)(1-x^2)^{\nu-1/2} dx \quad [\text{shift } \ell, m, n, \mu, \nu] \quad (6)$$

$$\int (x+a)^{\gamma+\lambda-1} (a-x)^{\beta-1} C_m^{(\gamma)}(x/a)C_n^{(\lambda)}(x/a) dx, \quad [\text{diff. } a, \text{ shift } n, m, \beta, \gamma, \lambda] \quad (7)$$

Integral	(1)	(2)	(3)	(4)	(5)	(6)	(7)
New algorithm (Maple)	13 s	> 1h	> 1h	1.5 s	1.5 s	165 s	53 s
Chyzak <sup>K</sup>	19 s	253 s	45 s	232 s	516 s	>1h	>1h
Koutschan <sup>K</sup>	1.9 s*	2.3 s	5.3 s	>1h	2.3 s*	5.4 s	2.2 s*

\* Non minimal output.

<sup>K</sup> Uses Koutschan's *HolonomicFunctions* (Mathematica package).

**conclusion** It really works! New algorithm for D-finite integration

New proof of the D-finiteness of the telescoping ideal of a D-finite function  
2G/4G unification

**future work** Better understanding of the practical performance  
Generalization to discrete sums

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